

Smoothed Isotonic Estimators of a Monotone Baseline Hazard in the Cox Model

Lopuhaa, Hendrik P.; Musta, Eni

DOI

[10.1111/sjos.12321](https://doi.org/10.1111/sjos.12321)

Publication date

2018

Document Version

Final published version

Published in

Scandinavian Journal of Statistics: theory and applications

Citation (APA)

Lopuhaa, H. P., & Musta, E. (2018). Smoothed Isotonic Estimators of a Monotone Baseline Hazard in the Cox Model. *Scandinavian Journal of Statistics: theory and applications*, 45, 753-791.
<https://doi.org/10.1111/sjos.12321>

Important note

To cite this publication, please use the final published version (if applicable).
Please check the document version above.

Copyright

Other than for strictly personal use, it is not permitted to download, forward or distribute the text or part of it, without the consent of the author(s) and/or copyright holder(s), unless the work is under an open content license such as Creative Commons.

Takedown policy

Please contact us and provide details if you believe this document breaches copyrights.
We will remove access to the work immediately and investigate your claim.

Smoothed Isotonic Estimators of a Monotone Baseline Hazard in the Cox Model

HENDRIK P. LOPUHAÄ AND ENI MUSTA 

Delft Institute of Applied Mathematics, Delft University of Technology

ABSTRACT. We consider the smoothed maximum likelihood estimator and the smoothed Grenander-type estimator for a monotone baseline hazard rate λ_0 in the Cox model. We analyze their asymptotic behaviour and show that they are asymptotically normal at rate $n^{m/(2m+1)}$, when λ_0 is $m \geq 2$ times continuously differentiable, and that both estimators are asymptotically equivalent. Finally, we present numerical results on pointwise confidence intervals that illustrate the comparable behaviour of the two methods.

Key words: asymptotic normality, Cox regression model, hazard rate, isotonic estimation, kernel smoothing, smoothed Grenander estimator, smoothed maximum likelihood estimator

1. Introduction

The semi-parametric Cox regression model is a very popular method in survival analysis that allows incorporation of covariates when studying lifetime distributions in the presence of right censored data. The ease of interpretation, resulting from the formulation in terms of the hazard rate and the proportional effect of the covariates, and the fact that the regression coefficients (parametric component) can be estimated while leaving the baseline distribution unspecified favour the wide use of this framework, especially in medical applications. On the other hand, because its first introduction (Cox, 1972), much effort has been spent on giving a firm mathematical basis to this approach. Initially, the attention was on the derivation of large sample properties of the maximum partial likelihood estimator of the regression coefficients and of the Breslow estimator for the cumulative baseline hazard (e.g., see Efron, 1977; Cox, 1975; Tsiatis, 1981). Although the most attractive property of this approach is that it does not assume any fixed shape on the hazard curve, there are several cases where order restrictions better match the practical expectations (see van Geloven, 2013, for an example of a decreasing hazard in a large clinical trial for patients with acute coronary syndrome). Estimation of the baseline hazard function under monotonicity constraints has been studied in Chung & Chang (1994) and Lopuhaä & Nane (2013).

Traditional isotonic estimators, such as maximum likelihood estimators and Grenander-type estimators, are step functions that exhibit a non normal limit distribution at rate $n^{1/3}$. On the other hand, a long stream of research has shown that, if one is willing to assume more regularity on the function of interest, smooth estimators might be preferred to piecewise constant ones because they can be used to achieve a faster rate of convergence to a Gaussian distributional law and to estimate derivatives. Isotonized smooth estimators, obtained either by a least squares projection, maximum likelihood or penalization, are studied in Mukerjee (1988), Ramsay (1998), Eggermont & LaRiccia (2000), van der Vaart & van der Laan (2003) and in Mammen (1991), who also compares isotonized kernel estimators with smoothed isotonic estimators in the regression setting. Smoothed maximum likelihood estimators (SMLEs) for monotone functions have also been investigated by Durot *et al.* (2013) to bootstrap from a

smooth decreasing density estimate, by Groeneboom *et al.* (2010) for the current status model, together with a maximum smoothed likelihood estimator (MSLE), and by Groeneboom & Jongbloed (2013) for estimating a monotone hazard rate, together with a penalized least squares estimator. Other references for combining shape constraints and smoothness can be found in Chapter 8 in Groeneboom & Jongbloed (2014). Distribution theory was first studied by Mukerjee (1988), who established asymptotic normality for a kernel smoothed least squares regression estimator, but this result is limited to a rectangular kernel and the rate of convergence is slower than the usual rate for kernel estimators. In van der Vaart & van der Laan (2003), it is shown that the isotonized kernel density estimator has the same limit normal distribution at the usual rate $n^{m/(2m+1)}$ as the ordinary kernel density estimator, when the density is m times continuously differentiable. Similar results were obtained by Groeneboom *et al.* (2010) for the SMLE and the MSLE and by Groeneboom & Jongbloed (2013) for a smoothed Grenander-type estimator.

Smooth estimation under monotonicity constraints for the baseline hazard in the Cox model was introduced in Nane (2013). By combining an isotonization step with a smoothing step and alternating the order of smoothing and isotonization, four different estimators can be constructed. Two of them are kernel smoothed versions of the maximum likelihood estimator and the Grenander-type estimator from Lopusuää & Nane (2013). The third estimator is a MSLE obtained by first smoothing the loglikelihood of the Cox model and then finding the maximizer of the smoothed likelihood among all decreasing baseline hazards. The fourth one is a Grenander-type estimator based on the smoothed Breslow estimator for the cumulative hazard. Three of these estimators were shown to be consistent in Nane (2013). Moreover, the last two methods have been studied in Lopusuää & Musta (2017a) and were shown to be asymptotically normal at the usual rate $n^{m/(2m+1)}$, where m denotes the level of smoothness of the baseline hazard. The main interest of the present paper is to investigate the asymptotic behaviour of the first two methods, the SMLE and a smoothed Grenander-type estimator.

This is particularly challenging for the Cox model, because the existing approaches to these type of problems for smoothed isotonic estimators do not apply to the Cox model. The situation is different from isotonized smooth estimators, such as the MSLE and a Grenander-type estimator based on the smoothed Breslow estimator, which are studied in Lopusuää & Musta (2017a). In the latter paper, the main idea is that the isotonic smooth estimator can be represented as a least squares projection of a naive estimator (smooth but not monotone), which is simpler to analyze and asymptotically equivalent to the isotonic smooth estimator.

The smoothed Grenander-type estimator in the ordinary right censoring model without covariates was investigated by Lopusuää & Musta (2017b). Following the approach in Groeneboom & Jongbloed (2013), asymptotic normality was established by using a Kiefer–Wolfowitz type of result, recently derived in Durot & Lopusuää (2014). Unfortunately, the lack of a Kiefer–Wolfowitz type of result for the Breslow estimator provides a strong limitation towards extending the previous approach to the more general setting of the Cox model. Recently, Groeneboom & Jongbloed (2014) developed a different method for finding the limit distribution of smoothed isotonic estimators, which is mainly based on uniform L_2 -bounds on the distance between the non-smoothed isotonic estimator and the true function, and also uses that the maximal distance between succeeding points of jump of the isotonic estimator is of the order $O_p(n^{-1/3} \log n)$. A sketch of proof in the right censoring model is given in Section 11.6 of Groeneboom & Jongbloed (2014). However, these two key ingredients heavily depend on having exponential bounds for tail probabilities of the so-called inverse process, or rely on a strong embedding for the relevant sum process. Exponential bounds for tail probabilities of the inverse process are difficult to obtain in the Cox model and a strong embedding for the Breslow estimator is not available. Nevertheless, inspired by the approach in Groeneboom &

Jongbloed (2014), we obtain polynomial bounds, which will suffice for obtaining uniform L_2 -bounds, and we avoid using the maximal distance between succeeding points of jump of the non-smoothed isotonic estimator, by establishing a sufficiently small bound on the expected supremum distance between the non-smoothed isotonic estimator and the true baseline hazard.

This leads to asymptotic normality at rate $n^{m/(2m+1)}$ of the SMLE and the smoothed Grenander-type estimator, which are also shown to be asymptotically equivalent. By means of a small simulation, we investigate the finite sample behaviour in terms of asymptotic confidence intervals corresponding to the limit normal distributions, as well as bootstrap confidence intervals based on a smooth bootstrap proposed by Burr (1994) and Xu *et al.* (2014). As expected, no estimator performs strictly better than the other.

The paper is organized as follows. In Section 2, we specify the Cox regression model and provide some background information that will be used in the sequel. The kernel smoothed versions of the Grenander-type estimator and of the maximum likelihood estimator of a non-decreasing baseline hazard function are considered in Section 3. We only consider the case of a nondecreasing baseline hazard. The same results can be obtained similarly for a non-increasing hazard. The results of a small simulation study are reported in Section 4, and we conclude with a brief discussion in Section 5. In order to keep the exposition clear and simple, most of the proofs are delayed until Section 6, and remaining technicalities have been put in the Supporting Information online.

2. The Cox regression model

Let X_1, \dots, X_n be an i.i.d. sample representing the survival times of n individuals, which can be observed only on time intervals $[0, C_i]$ for some i.i.d. censoring times C_1, \dots, C_n . One observes i.i.d. triplets $(T_1, \Delta_1, Z_1), \dots, (T_n, \Delta_n, Z_n)$, where $T_i = \min(X_i, C_i)$ denotes the follow up time, $\Delta_i = \mathbb{1}_{\{X_i \leq C_i\}}$ is the censoring indicator and $Z_i \in \mathbb{R}^p$ is a time independent covariate vector. Given the covariate vector Z , the event time X and the censoring time C are assumed to be independent. Furthermore, conditionally on $Z = z$, the event time is assumed to be a nonnegative r.v. with an absolutely continuous distribution function $F(x|z)$ and density $f(x|z)$. Similarly, the censoring time is assumed to be a nonnegative r.v. with an absolutely continuous distribution function $G(x|z)$ and density $g(x|z)$. The censoring mechanism is assumed to be non-informative, i.e., F and G share no parameters. Within the Cox model, the conditional hazard rate $\lambda(x|z)$ for a subject with covariate vector $z \in \mathbb{R}^p$ is related to the corresponding covariate by

$$\lambda(x|z) = \lambda_0(x)e^{\beta_0'z}, \quad x \in \mathbb{R}^+,$$

where λ_0 represents the baseline hazard function, corresponding to a subject with $z = 0$, and $\beta_0 \in \mathbb{R}^p$ is the vector of the regression coefficients.

Let H and H^{uc} denote, respectively, the distribution function of the follow-up time and the sub-distribution function of the uncensored observations, i.e.,

$$H^{uc}(x) = \mathbb{P}(T \leq x, \Delta = 1) = \int \delta \mathbb{1}_{\{t \leq x\}} d\mathbb{P}(t, \delta, z), \tag{1}$$

where \mathbb{P} is the distribution of (T, Δ, Z) . We also require the following assumptions, some of which are common in large sample studies of the Cox model (e.g., see Lopuhaä & Nane, 2013):

(A1) Let τ_F, τ_G and τ_H be the end points of the support of F, G and H . Then

$$\tau_H = \tau_G < \tau_F \leq \infty.$$

(A2) There exists $\epsilon > 0$ such that

$$\sup_{|\beta - \beta_0| \leq \epsilon} \mathbb{E} \left[|Z|^2 e^{2\beta'Z} \right] < \infty.$$

(A3) There exists $\epsilon > 0$ such that

$$\sup_{|\beta - \beta_0| \leq \epsilon} \mathbb{E} \left[|Z|^2 e^{4\beta'Z} \right] < \infty.$$

Let us briefly comment on these assumptions. While the first one tells us that, at the end of the study, there is at least one subject alive, the other two are somewhat hard to justify from a practical point of view. One can think of (A2) and (A3) as conditions on the boundedness of the second moment of the covariates, uniformly for β in a neighbourhood of β_0 .

By now, it seems to be rather a standard choice estimating β_0 by $\hat{\beta}_n$, the maximizer of the partial likelihood function, as proposed by Cox (1972). The asymptotic behaviour was first studied by Tsiatis (1981). We aim at estimating λ_0 , subject to the constraint that it is increasing (the case of a decreasing hazard is analogous), on the basis of n observations $(T_1, \Delta_1, Z_1), \dots, (T_n, \Delta_n, Z_n)$. We refer to the quantity

$$\Lambda_0(t) = \int_0^t \lambda_0(u) du$$

as the cumulative baseline hazard and, by introducing

$$\Phi(x; \beta) = \int \mathbb{1}_{\{t \geq x\}} e^{\beta'z} d\mathbb{P}(t, \delta, z), \tag{2}$$

we have

$$\lambda_0(x) = \frac{h(x)}{\Phi(x; \beta_0)}, \tag{3}$$

where $h(x) = dH^{uc}(x)/dx$ (e.g., see (9) in Lopuhaä & Nane, 2013). For $\beta \in \mathbb{R}^p$ and $x \in \mathbb{R}$, the function $\Phi(x; \beta)$ can be estimated by

$$\Phi_n(x; \beta) = \int \mathbb{1}_{\{t \geq x\}} e^{\beta'z} d\mathbb{P}_n(t, \delta, z), \tag{4}$$

where \mathbb{P}_n is the empirical measure of the triplets (T_i, Δ_i, Z_i) with $i = 1, \dots, n$. Moreover, in lemma 4 of Lopuhaä & Nane (2013), it is shown that

$$\sup_{x \in \mathbb{R}} |\Phi_n(x; \beta_0) - \Phi(x; \beta_0)| = O_p(n^{-1/2}). \tag{5}$$

It will be often used throughout the paper that a stochastic bound of the same order holds also for the distance between the cumulative hazard Λ_0 and the Breslow estimator

$$\Lambda_n(x) = \int \frac{\delta \mathbb{1}_{\{t \leq x\}}}{\Phi_n(t; \hat{\beta}_n)} d\mathbb{P}_n(t, \delta, z), \tag{6}$$

but only on intervals staying away of the right boundary, i.e.,

$$\sup_{x \in [0, M]} |\Lambda_n(x) - \Lambda_0(x)| = O_p(n^{-1/2}), \quad \text{for all } 0 < M < \tau_H, \tag{7}$$

(see theorem 5 in Lopuhaä & Nane, 2013).

Smoothing is done by means of kernel functions. We will consider kernel functions k that are m -orthogonal, for some $m \geq 1$, which means that $\int |k(u)| |u|^m du < \infty$ and $\int k(u)u^j du = 0$, for $j = 1, \dots, m - 1$, if $m \geq 2$. We assume that

$$k \text{ has bounded support } [-1, 1] \text{ and is such that } \int_{-1}^1 k(y) dy = 1; \tag{8}$$

k is differentiable with a uniformly bounded derivative.

We denote by k_b its scaled version $k_b(u) = b^{-1}k(u/b)$. Here, $b = b_n$ is a bandwidth that depends on the sample size, in such a way that $0 < b_n \rightarrow 0$ and $nb_n \rightarrow \infty$, as $n \rightarrow \infty$. From now on, we will simply write b instead of b_n . Note that if $m > 2$, the kernel function k necessarily attains negative values, and as a result, also the smooth estimators of the baseline hazard defined in Section 3 may be negative and monotonicity might not be preserved. To avoid this, one could restrict oneself to $m = 2$. In that case, the most common choice is to let k be a symmetric probability density.

3. Smoothed isotonic estimators

We consider smoothed versions of two isotonic estimators for λ_0 , i.e., the maximum likelihood estimator $\hat{\lambda}_n$ and the Grenander-type estimator $\tilde{\lambda}_n$, introduced in Lopuhaä & Nane (2013). The maximum likelihood estimator of a nondecreasing baseline hazard rate λ_0 can be characterized as the left derivative of the greatest convex minorant of the cumulative sum diagram consisting of points $P_0 = (0, 0)$ and $P_j = (\hat{W}_n(T_{(j+1)}), V_n(T_{(j+1)}))$, for $j = 1, \dots, n - 1$, where \hat{W}_n and V_n are defined as

$$\begin{aligned} \hat{W}_n(x) &= \int \left(e^{\hat{\beta}_n z} \int_{T_{(1)}}^x \mathbb{1}_{\{u \geq s\}} ds \right) d\mathbb{P}_n(u, \delta, z), \quad x \geq T_{(1)}, \\ V_n(x) &= \int \delta \mathbb{1}_{\{u < x\}} d\mathbb{P}_n(u, \delta, z), \end{aligned} \tag{9}$$

with $\hat{\beta}_n$ being the partial maximum likelihood estimator (see lemma 1 in Lopuhaä & Nane, 2013). For a fixed $x \in [0, \tau_H]$, the SMLE $\hat{\lambda}_n^{SM}$ of a nondecreasing baseline hazard rate λ_0 was defined in Nane (2013) by

$$\hat{\lambda}_n^{SM}(x) = \int_{(x-b) \vee 0}^{(x+b) \wedge \tau_H} k_b(x - u) \hat{\lambda}_n(u) du. \tag{10}$$

The Grenander-type estimator $\tilde{\lambda}_n$ of a nondecreasing baseline hazard rate λ_0 is defined as the left hand slope of the greatest convex minorant $\tilde{\Lambda}_n$ of the Breslow estimator Λ_n . For a fixed $x_0 \in [0, \tau_H]$, we consider the smoothed Grenander-type estimator $\tilde{\lambda}_n^{SG}$, which is defined by

$$\tilde{\lambda}_n^{SG}(x) = \int_{(x-b) \vee 0}^{(x+b) \wedge \tau_H} k_b(x - u) \tilde{\lambda}_n(u) du. \tag{11}$$

Uniform strong consistency on compact intervals in the interior of the support $[\epsilon, M] \subset [0, \tau_H]$ is provided by theorem 5.2 of Nane (2013),

$$\sup_{x \in [\epsilon, M]} \left| \tilde{\lambda}_n^{SG}(x) - \lambda_0(x) \right| \rightarrow 0, \quad \text{with probability one.} \tag{12}$$

Strong pointwise consistency of $\hat{\lambda}_n^{SM}$ in the interior of the support is established in theorem 5.1 in Nane (2013). Under additional smoothness assumptions on λ_0 , one can obtain

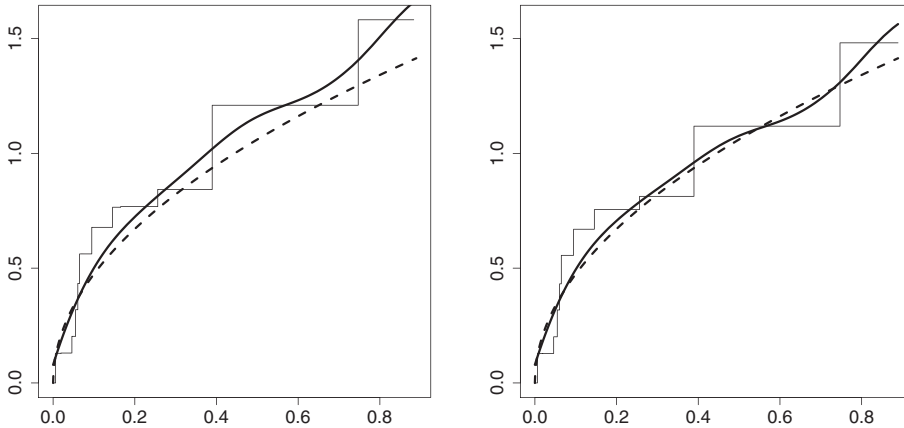


Fig. 1. Left panel: The maximum likelihood estimator (piecewise constant solid line) of the baseline hazard (dashed) together with the smoothed maximum likelihood estimator (solid). Right panel: The Grenander estimator (piecewise constant solid line) of the baseline hazard (dashed) together with the smoothed Grenander estimator (solid).

uniform strong consistency for $\hat{\lambda}_n^{SM}$, similar to (12). Inconsistency at the boundaries is a frequently encountered problem in such situations and can be partially avoided by using a boundary corrected kernel. One possibility is to construct linear combinations of $k(u)$ and $uk(u)$ with coefficients depending on the value near the boundary (e.g., see Zhang & Karunamuni, 1998; Durot *et al.*, 2013; or Lopuhaä & Musta, 2017b). Then, it can be proved, exactly as it is done in Lopuhaä & Musta (2017b), that uniform consistency holds on $[0, M] \subset [0, \tau_H]$.

Figure 1 shows the SMLE (left) and the smoothed Grenander-type estimator (right) for a sample of size $n = 500$ from a Weibull baseline distribution with shape parameter 1.5 and scale 1. For simplicity, we assume that the real valued covariate and the censoring times are uniformly $(0, 1)$ distributed and we take $\beta_0 = 0.5$. We used a boundary corrected triweight kernel function $k(u) = (35/32)(1 - u^2)^3 \mathbb{1}_{\{|u| \leq 1\}}$ and bandwidth $b = n^{-1/5}$.

In the remainder of this section, we will derive the pointwise asymptotic distribution of both smoothed isotonic estimators, in (10) and (11). As already mentioned, our approach is inspired by techniques introduced in Section 11.6 of Groeneboom & Jongbloed (2014). We briefly describe this approach for the smoothed Grenander estimator, for which the computations are more complicated. We start by writing

$$\tilde{\lambda}_n^{SG}(x) = \int k_b(x - u) d\Lambda_0(u) + \int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_0)(u). \tag{13}$$

The first (deterministic) term on the right hand side of (13) gives us the asymptotic bias. The method applied in Lopuhaä & Musta (2017b) for the right censoring model continues by decomposing the second term in two parts

$$\int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_n)(u) + \int k_b(x - u) d(\Lambda_n - \Lambda_0)(u),$$

and then uses the Kiefer–Wolfowitz type of result

$$\sup_{t \in [0, \tau_H]} |\tilde{\Lambda}_n(t) - \Lambda_n(t)| = O_P \left(n^{-2/3} (\log n)^{2/3} \right), \tag{14}$$

to show that $\int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_n)(u)$ converges to zero. Finally, results from empirical process theory are used to show the asymptotic normality of $\int k_b(x - u) d(\Lambda_n - \Lambda_0)(u)$. This approach cannot be followed in our case because of the lack of a Kiefer–Wolfowitz type of result as in (14) for the Cox model.

Alternatively, we proceed by describing the main steps of the L_2 -bounds approach introduced in Groeneboom & Jongbloed (2014). On an event E_n with probability tending to one, we will approximate

$$\int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_0)(u) \tag{15}$$

by $\int \theta_{n,x}(u, \delta, z) d\mathbb{P}(u, \delta, z)$, for some suitable function $\theta_{n,x}$ (lemma 3.1), whose piecewise constant modification $\bar{\theta}_{n,x}$ integrates to zero with respect to the empirical measure \mathbb{P}_n (lemma 3.2). This enables us to approximate (15) by

$$\int \bar{\theta}_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) + \int (\bar{\theta}_{n,x}(u, \delta, z) - \theta_{n,x}(u, \delta, z)) d\mathbb{P}(u, \delta, z). \tag{16}$$

Then, the key step is to bound the second integral in (16) by means of L_2 -bounds on the distance between the ordinary Grenander estimator and the true baseline hazard (lemma 3.3). The last step consists of replacing $\bar{\theta}_{n,x}$ by a deterministic function $\eta_{n,x}$ (lemma 3.4) and use empirical process theory to show that

$$\int \eta_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z)$$

is asymptotically normal.

Before we proceed to our first main result, we will formulate the steps described earlier in a series of lemmas. Let $x \in (0, \tau_H)$ and $0 < M < \tau_H$. For n sufficiently large, such that $0 < x - b < x + b < M$, define

$$a_{n,x}(u) = \frac{k_b(x - u)}{\Phi(u; \beta_0)}, \quad \text{for } u \leq x + b, \tag{17}$$

where $\Phi(u; \beta_0)$ is defined in (2), and $a_{n,x}(u) = 0$ for $u > x + b$. We then have the following approximation for (15). The proof can be found in Section 6.

Lemma 3.1. *Suppose that (A1)–(A2) hold. Let $a_{n,x}$ be defined by (17) and let $\hat{\beta}_n$ be the partial MLE for β_0 . There exists an event E_n , with $\mathbb{1}_{E_n} \rightarrow 1$ in probability, such that for*

$$\theta_{n,x}(u, \delta, z) = \mathbb{1}_{E_n} \left\{ \delta a_{n,x}(u) - e^{\hat{\beta}'_n z} \int_0^u a_{n,x}(v) d\tilde{\Lambda}_n(v) \right\}, \tag{18}$$

it holds

$$\int \theta_{n,x}(u, \delta, z) d\mathbb{P}(u, \delta, z) = -\mathbb{1}_{E_n} \int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_0)(u) + O_p(n^{-1/2}).$$

Next, we consider a piecewise constant modification $\bar{a}_{n,x}\bar{\Phi}_n$ of $a_{n,x}\Phi_n$, which is constant on the same intervals as $\tilde{\lambda}_n$. Let $\tau_0 = x - b$, $\tau_{m+1} = x + b$ and let $(\tau_i)_{i=1}^m$ be successive points of jump of $\tilde{\lambda}_n$ in the interval $(x - b, x + b)$. Then, for $u \in (\tau_i, \tau_{i+1}]$, we choose

$$\bar{a}_{n,x}\bar{\Phi}_n(u; \hat{\beta}_n) = a_{n,x}(\hat{A}_n(u))\Phi_n(\hat{A}_n(u); \hat{\beta}_n), \tag{19}$$

where for $u \in (\tau_i, \tau_{i+1}]$,

$$\hat{A}_n(u) = \begin{cases} \tau_i, & \text{if } \lambda_0(t) > \tilde{\lambda}_n(\tau_{i+1}), \text{ for all } t \in (\tau_i, \tau_{i+1}], \\ s, & \text{if } \lambda_0(s) = \tilde{\lambda}_n(s), \text{ for some } s \in (\tau_i, \tau_{i+1}], \\ \tau_{i+1}, & \text{if } \lambda_0(t) < \tilde{\lambda}_n(\tau_{i+1}), \text{ for all } t \in (\tau_i, \tau_{i+1}]. \end{cases} \tag{20}$$

Furthermore, let E_n be the event from lemma 3.1 and define

$$\tilde{\Psi}_{n,x}(u) = \frac{\bar{a}_{n,x} \tilde{\Phi}_n(u; \hat{\beta}_n)}{\Phi_n(u; \hat{\beta}_n)} \mathbb{1}_{E_n}, \quad u \in [x - b, x + b], \tag{21}$$

and $\tilde{\Psi}_{n,x}(u) = 0$, for $u \notin [x - b, x + b]$. Note that, because $u \leq x + b < M < T_{(n)}$ on the event E_n , we have $\Phi_n(u; \hat{\beta}_n) > 0$ (see the proof of lemma 3.1), and thus $\tilde{\Psi}_{n,x}(u)$ is well defined. Now, define the following piecewise constant modification of $\theta_{n,x}$ by

$$\bar{\theta}_{n,x}(u, \delta, z) = \delta \tilde{\Psi}_{n,x}(u) - e^{\hat{\beta}'z} \int_0^u \tilde{\Psi}_{n,x}(v) d\tilde{\Lambda}_n(v). \tag{22}$$

We then have the following property. The proof can be found in Section 6.

Lemma 3.2. *Let $\bar{\theta}_{n,x}$ be defined in (22). Then*

$$\int \bar{\theta}_{n,x}(u, \delta, z) d\mathbb{P}_n(u, \delta, z) = 0. \tag{23}$$

At this point, it is important to discuss in some detail how we will obtain suitable bounds for the second integral in (16). In order to do so, we first introduce the inverse process \tilde{U}_n . It is defined by

$$\tilde{U}_n(a) = \operatorname{argmin}_{x \in [0, T_{(n)}]} \{\Lambda_n(x) - ax\}, \tag{24}$$

and it satisfies the switching relation $\tilde{\lambda}_n(x) \leq a$ if and only if $\tilde{U}_n(a) \geq x$, for $x \leq T_{(n)}$. In their analysis of the current status model, Groeneboom *et al.* (2010) encounter an integral that is similar to the second integral in (16). They bound this integral using that the maximal distance between succeeding points of jump of the isotonic estimator is of the order $O_p(n^{-1/3} \log n)$. Such a property typically relies on the exponential bounds for the tail probabilities of $\tilde{U}_n(a)$, obtained either by using a suitable exponential martingale (e.g., see lemma 5.9 in Groeneboom & Wellner, 1992), or by an embedding of the relevant sum process into Brownian motion or Brownian bridge (e.g., see lemma 5.1 in Durot *et al.*, 2012). Unfortunately, an embedding of the process Λ_n is not available, and in our current situation, the martingale approach only yields polynomial bounds for tail probabilities of $\tilde{U}_n(a)$. A polynomial bound was also found by Durot (2007) (see her lemma 2), leading to

$$\sup_{x \in I_n} \mathbb{E} \left[\left(\tilde{\lambda}_n(x) - \lambda_0(x) \right)^p \right] \leq Kn^{-p/3}, \tag{25}$$

for $p \in [1, 2)$ and some interval I_n (see her theorem 1). By intersecting with the event E_n from lemma 3.1, we extend (25) to a similar bound for $p = 2$. Groeneboom & Jongbloed (2014) provide an alternative approach to bound the second integral in (16), based on bounds for (25) with $p = 2$. Unfortunately, they still make use of the fact that the maximum distance between succeeding points of jump of the isotonic estimator is of the order $O_p(n^{-1/3} \log n)$ to obtain a result similar to (28). Nevertheless, we do follow the approach in Groeneboom & Jongbloed

(2014), but instead of using the maximum distance between succeeding points of jump of $\tilde{\lambda}_n$, we use a bound on

$$\mathbb{E} \left[\sup_{x \in [\epsilon, M]} \left(\tilde{\lambda}_n(x) - \lambda_0(x) \right)^2 \right], \tag{26}$$

for $0 < \epsilon < M < \tau_H$. Exponential bounds for the tail probabilities of $\tilde{U}_n(a)$ would yield the same bound for (26) as the one in (25) apart from a factor $\log n$. Because we can only obtain polynomial bounds on the tail probabilities of $\tilde{U}_n(a)$, we establish a bound for (26) of the order $O(n^{-4/9})$. This is probably not optimal, but this will turn out to be sufficient for our purposes and leads to the following intermediate result, of which the proof can be found in Section 6.

Lemma 3.3. *Suppose that (A1)–(A2) hold. Fix $x \in (0, \tau_h)$ and let $\theta_{n,x}$ and $\bar{\theta}_{n,x}$ be defined by (18) and (22), respectively. Assume that λ_0 is differentiable, such that λ'_0 is uniformly bounded above and below by strictly positive constants. Assume that $x \mapsto \Phi(x; \beta_0)$ is differentiable with a bounded derivative in a neighborhood of x and let k satisfy (8). Then, it holds*

$$\int \{ \bar{\theta}_{n,x}(u, \delta, z) - \theta_{n,x}(u, \delta, z) \} d\mathbb{P}(u, \delta, z) = O_p(b^{-1}n^{-2/3}).$$

The last step is to replace $\bar{\theta}_{n,x}$ in the first integral of (16) with a deterministic approximation. This is done in the next lemma, of which the proof can be found in Section 6.

Lemma 3.4. *Suppose that (A1)–(A3) hold. Fix $x \in (0, \tau_h)$. Assume that λ_0 is differentiable, such that λ'_0 is uniformly bounded above and below by strictly positive constants. Assume that $x \mapsto \Phi(x; \beta_0)$ is differentiable with a bounded derivative in a neighborhood of x . Let $\bar{\theta}_{n,x}$ be defined in (22) and define*

$$\eta_{n,x}(u, \delta, z) = \mathbb{1}_{E_n} \left(\delta a_{n,x}(u) - e^{\beta'_0 z} \int_0^u a_{n,x}(v) d\Lambda_0(v) \right), \quad u \in [0, \tau_H]. \tag{27}$$

where $a_{n,x}$ is defined in (17) and E_n is the event from lemma 3.1. Let k satisfy (8). Then, it holds

$$\int \{ \bar{\theta}_{n,x}(u, \delta, z) - \eta_{n,x}(u, \delta, z) \} d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) = O_p(b^{-3/2}n^{-13/18}) + O_p(n^{-1/2}) \tag{28}$$

We are now in the position to state our first main result.

Theorem 3.5. *Suppose that (A1)–(A3) hold. Fix $x \in (0, \tau_h)$. Assume that λ_0 is $m \geq 2$ times continuously differentiable in x , such that λ'_0 is uniformly bounded above and below by strictly positive constants. Moreover, assume that $t \mapsto \Phi(t; \beta_0)$ is differentiable with a bounded derivative in a neighborhood of x and let k satisfy (8). Let $\tilde{\lambda}_n^{\text{SG}}$ be defined in (11) and assume that $n^{1/(2m+1)}b \rightarrow c > 0$. Then, it holds*

$$n^{m/(2m+1)} \left(\tilde{\lambda}_n^{\text{SG}}(x) - \lambda_0(x) \right) \xrightarrow{d} N(\mu, \sigma^2),$$

where

$$\mu = \frac{(-c)^m}{m!} \lambda_0^{(m)}(x) \int_{-1}^1 k(y) y^m dy \quad \text{and} \quad \sigma^2 = \frac{\lambda_0(x)}{c \Phi(x; \beta_0)} \int k^2(u) du. \tag{29}$$

Furthermore,

$$n^{m/(2m+1)} \left(\tilde{\lambda}_n^{SG}(x) - \tilde{\lambda}_n^{SM}(x) \right) \rightarrow 0, \tag{30}$$

in probability, where $\tilde{\lambda}_n^{SM}(x)$ is defined in (10), so that $\tilde{\lambda}_n^{SM}(x)$ has the same limiting distribution as $\tilde{\lambda}_n^{SG}(x)$.

Proof. Choose $0 < \epsilon < x < M' < M < \tau_H$, so that for n sufficiently large, we have $\epsilon < x - b \leq x + b \leq M'$. Consider the event E_n from lemma 3.1 and choose $\xi_1, \xi_2 > 0$ and ξ_3 , such that it satisfies (65). We write

$$\begin{aligned} \tilde{\lambda}_n^{SG}(x) &= \int k_b(x - u) d\tilde{\Lambda}_n(u) \\ &= \int k_b(x - u) d\Lambda_0(u) + \mathbb{1}_{E_n} \int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_0)(u) \\ &\quad + \mathbb{1}_{E_n^c} \int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_0)(u). \end{aligned} \tag{31}$$

Because $\mathbb{1}_{E_n^c} \rightarrow 0$ in probability, the third term on the right hand side tends to zero in probability. For the first term, we obtain from a change of variable, a Taylor expansion, and the properties of the kernel:

$$\begin{aligned} &n^{m/(2m+1)} \left\{ \int k_b(x - u) \lambda_0(u) du - \lambda_0(x) \right\} \\ &= n^{m/(2m+1)} \int_{-1}^1 k(y) \{ \lambda_0(x - by) - \lambda_0(x) \} dy \\ &= n^{m/(2m+1)} \int_{-1}^1 k(y) \left\{ -\lambda_0'(x)by + \dots + \frac{\lambda_0^{(m-1)}(x)}{(m-1)!} (-by)^{m-1} + \frac{\lambda_0^{(m)}(\xi_n)}{m!} (-by)^m \right\} dy \\ &\rightarrow \frac{(-c)^m}{m!} \lambda_0^{(m)}(x) \int_{-1}^1 k(y) y^m dy, \end{aligned} \tag{32}$$

with $|\xi_n - x| < b|y|$. Finally, for the second term on the right hand side of (31), lemmas 3.1 to 3.4 yield that

$$\begin{aligned} &n^{m/(2m+1)} \mathbb{1}_{E_n} \int k_b(x - u) d(\tilde{\Lambda}_n - \Lambda_0)(u) \\ &= n^{m/(2m+1)} \int \eta_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) + o_p(1). \end{aligned} \tag{33}$$

For the first term on the right hand side of (33), we can write

$$\begin{aligned} &n^{m/(2m+1)} \int \eta_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \\ &= n^{m/(2m+1)} \mathbb{1}_{E_n} \int \frac{\delta k_b(x - u)}{\Phi(u; \beta_0)} d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \\ &\quad - n^{m/(2m+1)} \mathbb{1}_{E_n} \int e^{\beta_0' z} \int_0^u a_{n,x}(v) d\Lambda_0(v) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z). \end{aligned} \tag{34}$$

We will show that the first term on the right hand is asymptotically normal and the second term tends to zero in probability. Define $Y_{n,i} = n^{-(m+1)/(2m+1)} \Delta_i k_b(x - T_i) / \Phi(T_i; \beta_0)$, so that the first term on the right hand side of (34) can be written as

$$\mathbb{1}_{E_n} n^{m/(2m+1)} \int \frac{\delta k_b(x - u)}{\Phi(u; \beta_0)} d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) = \mathbb{1}_{E_n} \sum_{i=1}^n (Y_{n,i} - \mathbb{E}[Y_{n,i}]).$$

Using (3), together with a Taylor expansion and the boundedness assumptions on the derivatives of λ_0 and $\Phi(x; \beta_0)$, we have

$$\begin{aligned} & \sum_{i=1}^n \text{Var}(Y_{n,i}) \\ &= n^{-1/(2m+1)} \left\{ \int \frac{k_b^2(x - u)}{\Phi(u; \beta_0)^2} dH^{uc}(u) - \left(\int \frac{k_b(x - u)}{\Phi(u; \beta_0)} dH^{uc}(u) \right)^2 \right\} \\ &= n^{-1/(2m+1)} \left\{ \frac{1}{b} \int_{-1}^1 k^2(y) \frac{\lambda_0(x - by)}{\Phi(x - by; \beta_0)} dy - \left(\int k_b(x - u) \lambda_0(u) du \right)^2 \right\} \\ &= \frac{\lambda_0(x)}{c \Phi(x; \beta_0)} \int_{-1}^1 k^2(y) dy - n^{-1/(2m+1)} \int_{-1}^1 y k^2(y) \left[\frac{d}{dx} \frac{\lambda_0(x)}{\Phi(x; \beta_0)} \right]_{x=\xi_y} dy + o(1) \\ &= \frac{\lambda_0(x)}{c \Phi(x; \beta_0)} \int_{-1}^1 k^2(y) dy + o(1). \end{aligned} \tag{35}$$

Moreover, $|Y_{n,i}| \leq n^{-(m+1)/(2m+1)} \Phi(M; \beta_0)^{-1} \sup_{x \in [-1, 1]} k(x)$, so that $\sum_{i=1}^n \mathbb{E}[|Y_{n,i}|^2 \mathbb{1}_{\{|Y_{n,i}| > \epsilon\}}] \rightarrow 0$, for any $\epsilon > 0$, because $\mathbb{1}_{\{|Y_{n,i}| > \epsilon\}} = 0$, for n sufficiently large. Consequently, by Lindeberg central limit theorem, and the fact that $\mathbb{1}_{E_n} \rightarrow 1$ in probability, we obtain

$$\mathbb{1}_{E_n} n^{m/(2m+1)} \int \frac{\delta k_b(x - u)}{\Phi(u; \beta_0)} d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \rightarrow N(0, \sigma^2). \tag{36}$$

For the second term on the right hand side of (34), write

$$n^{m/(2m+1)} \int e^{\beta_0 z} \int_0^u a_{n,x}(v) d\Lambda_0(v) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) = \sum_{i=1}^n (\tilde{Y}_{n,i} - \mathbb{E}[\tilde{Y}_{n,i}]).$$

where

$$\tilde{Y}_{n,i} = n^{-(m+1)/(2m+1)} e^{\beta_0 z_i} \int_0^{T_i} \frac{k_b(x - v)}{\Phi(v; \beta_0)} d\Lambda_0(v).$$

We have

$$\sum_{i=1}^n \text{Var}(\tilde{Y}_{n,i}) \leq \sum_{i=1}^n \mathbb{E}[\tilde{Y}_{n,i}^2] \leq n^{-1/(2m+1)} \int e^{2\beta_0 z} \left(\int_0^u \frac{k_b(x - v)}{\Phi(v; \beta_0)} d\Lambda_0(v) \right)^2 d\mathbb{P}(u, \delta, z),$$

where the integral on the right hand side is bounded by

$$\left(\int_{x-b}^{x+b} \frac{k_b(x-v)}{\Phi(v; \beta_0)} d\Lambda_0(v) \right)^2 \Phi(0; 2\beta_0) \leq \frac{\Phi(0; 2\beta_0)}{\Phi^2(M; \beta_0)} \left(\int_{x-b}^{x+b} k_b(x-v) d\Lambda_0(v) \right)^2 = O(1).$$

Hence, the second term on the right hand side of (34) tends to zero in probability. Together with (31), (32) and (36), this proves the first part of the theorem.

For the SMLE, we can follow the same approach and obtain similar results as those in lemmas 3.1 to 3.4. The arguments are more or less the same as those used to prove lemmas 3.1 to 3.4. We briefly sketch the main differences. First, instead of $\hat{\Lambda}_n$, we now use

$$\hat{\Lambda}_n(x) = \int_0^x \hat{\lambda}_n(u) du$$

in (15). Then, because the maximum likelihood estimator is defined as the left slope of the greatest convex minorant of a cumulative sum diagram that is different from the one corresponding to the Grenander-type estimator, lemmas 3.1 and 3.2 will hold with a different event \hat{E}_n and $\hat{\Psi}_{n,x}$ will have a simpler form (see lemmas B.1–B.2 and definition (S10) in Supporting Information). Similar to the proof of lemma 3.3, the proof of its counterpart for the maximum likelihood estimator (see lemma B.8 in Supporting Information) is quite technical and involves bounds on the tail probabilities of the inverse process corresponding to $\hat{\lambda}_n$ (lemma B.5), used to obtain the analogue of (26) (lemma B.6). Moreover, the inverse process related to the maximum likelihood estimator is defined by

$$\hat{U}_n(a) = \operatorname{argmin}_{x \in [T(1), T(n)]} \{V_n(x) - a\hat{W}_n(x)\}, \tag{37}$$

where V_n and \hat{W}_n are defined in (9), and we get a slightly different bound on the tail probabilities of \hat{U}_n (compare lemma 6.3 and lemma B.5 in Supporting Information). The reason is that the martingale decomposition of the process $V_n(t) - a\hat{W}_n(t)$ has a simpler form. The counterpart of lemma 3.4 (see lemma B.10 in Supporting Information) is established in the same way, replacing $\tilde{\lambda}_n$ by $\hat{\lambda}_n$. For details, we refer to Section B in Supporting Information.

From (31) and (33), we have that

$$\begin{aligned} n^{m/(2m+1)} \tilde{\lambda}_n^{\text{SG}}(x) &= n^{m/(2m+1)} \int k_b(x-u) d\Lambda_0(u) \\ &+ n^{m/(2m+1)} \int \eta_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) + o_p(1) \end{aligned} \tag{38}$$

where $\eta_{n,x}$ is defined in (27) and where

$$n^{m/(2m+1)} \int \eta_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \rightarrow N(0, \sigma^2). \tag{39}$$

Similarly, from the results in Section B of Supporting Information, we have that there exists an event \hat{E}_n , such that

$$\begin{aligned} n^{m/(2m+1)} \tilde{\lambda}_n^{\text{SM}}(x) &= n^{m/(2m+1)} \int k_b(x-u) d\Lambda_0(u) \\ &+ n^{m/(2m+1)} \int \hat{\eta}_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) + o_p(1), \end{aligned} \tag{40}$$

where $\hat{\eta}_{n,x}$ is defined in (27) with \hat{E}_n instead of E_n , where $\mathbb{1}_{\hat{E}_n} \rightarrow 1$ in probability, and where

$$n^{m/(2m+1)} \int \hat{\eta}_{n,x}(u, \delta, z) d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \rightarrow N(0, \sigma^2). \tag{41}$$

Together with (39) and (41), this means that

$$\begin{aligned} & n^{m/(2m+1)} \left(\tilde{\lambda}_n^{\text{SG}}(x) - \hat{\lambda}_n^{\text{SM}}(x) \right) \\ &= \left(\mathbb{1}_{\hat{E}_n^c} \mathbb{1}_{E_n} - \mathbb{1}_{E_n^c} \mathbb{1}_{\hat{E}_n} \right) \\ &\quad \times n^{m/(2m+1)} \int \left\{ \delta a_{n,x}(u) - e^{\beta'_0 z} \int_0^u a_{n,x}(v) d\Lambda_0(v) \right\} d(\mathbb{P}_n - \mathbb{P})(u, \delta, z) + o_p(1) \\ &= \mathbb{1}_{\hat{E}_n^c} O_p(1) - \mathbb{1}_{E_n^c} O_p(1) + o_p(1) = o_p(1), \end{aligned}$$

because $\mathbb{1}_{\hat{E}_n^c} \rightarrow 0$ and $\mathbb{1}_{E_n^c} \rightarrow 0$ in probability. □

Note that in the special case $\beta_0 = 0$ and $m = 2$, we recover theorem 3.2 in Lopuhaä & Musta (2017b) and theorem 11.8 in Groeneboom & Jongbloed (2014), for the right censoring model without covariates. The fact that $\tilde{\lambda}_n^{\text{SG}}(x)$ and $\hat{\lambda}_n^{\text{SM}}(x)$ are asymptotically equivalent does not come as a surprise, because for the corresponding isotonic estimators according to theorem 2 in Lopuhaä & Nane (2013), for $x \in (0, \tau_H)$ fixed, $n^{1/3} (\tilde{\lambda}_n(x) - \hat{\lambda}_n(x)) \rightarrow 0$, in probability. However, we have not been able to exploit this fact, and we have established the asymptotic equivalence in (30) by obtaining the expansions in (38) and (40) separately for each estimator.

Remark 3.6. The estimators considered in theorem 3.5 are based on the partial maximum likelihood estimator $\hat{\beta}_n$, which defines the Breslow estimator, see (6), and the cumulative sum diagram from which the SMLE is determined, see (9). However, theorem 3.5 remains true, if $\hat{\beta}_n$ is any estimator that satisfies

$$\hat{\beta}_n - \beta_0 \rightarrow 0, \text{ a.s., and } \sqrt{n}(\hat{\beta}_n - \beta_0) = O_p(1) \tag{42}$$

In particular, this holds for the partial MLE for β_0 . See, e.g., theorems 3.1 and 3.2 in Tsiatis (1981). When proving consistency of the bootstrap, we are not able to establish bootstrap versions of theorems 3.1 and 3.2 in Tsiatis (1981), but, in view of this remark, it is sufficient to assume the bootstrap version of (42).

4. Numerical results for pointwise confidence intervals

In this section, we illustrate the finite sample performance of the two estimators considered previously by constructing pointwise confidence intervals for the baseline hazard rate. We consider two different procedures: the first one relies on the limit distribution and the second one is a bootstrap based method. In all the simulations, we use the triweight kernel function, which means that the degree of smoothness is $m = 2$. The reason for choosing a second-order kernel is that higher order kernels may also take negative values, which then might lead to non monotone estimators for the baseline hazard.

4.1. Asymptotic confidence intervals

From theorem 3.5, it can be seen that the asymptotic $100(1 - \alpha)\%$ -confidence intervals at the point $x_0 \in (0, \tau_H)$ are of the form

$$\lambda_n^{SI}(x_0) - n^{-2/5} \{ \hat{\mu}_n(x_0) \pm \hat{\sigma}_n(x_0) q_{1-\alpha/2} \},$$

where $q_{1-\alpha/2}$ is the $(1 - \alpha/2)$ quantile of the standard normal distribution, $\lambda_n^{SI}(x_0)$ is the smooth isotonic estimator at hand (SG or SMLE) and $\hat{\sigma}_n(x_0)$, $\hat{\mu}_n(x_0)$ are corresponding plug-in estimators of the asymptotic mean and standard deviation, respectively. However, from the expression of the asymptotic mean in theorem 3.5 for $m = 2$, it is obvious that obtaining the plug-in estimators requires estimation of the second derivative of λ_0 . Because accurate estimation of derivatives is a hard problem, we choose to avoid it by using undersmoothing. This procedure is to be preferred above bias estimation, because it is computationally more convenient and leads to better results (see also Hall, 1992; Groeneboom & Jongbloed, 2015; Cheng *et al.*, 2006). Undersmoothing consists of using a bandwidth of a smaller order than the optimal one (in our case $n^{-1/5}$). As a result, the bias of $n^{2/5}(\lambda_n^{SI}(x_0) - \lambda_0(x_0))$, which is of the order $n^{2/5}b^2$ (32), will converge to zero. On the other hand, the asymptotic variance is $n^{-1/5}b^{-1}\sigma^2$ (see (35) with $m = 2$). For example, with $b = n^{-1/4}$, asymptotically $n^{2/5}(\lambda_n^{SI}(x_0) - \lambda_0(x_0))$ behaves like a normal distribution with mean of the order $n^{-1/10}$ and variance $n^{1/20}\sigma^2$. Hence, the confidence interval becomes

$$\lambda_n^{SI}(x_0) \pm n^{-3/8} \hat{\sigma}_n(x_0) q_{1-\alpha/2}, \tag{43}$$

where

$$\hat{\sigma}_n(x_0) = \frac{\lambda_n^{SI}(x_0)}{c \Phi_n(x_0; \hat{\beta}_n)} \int_{-1}^1 k(y)^2 dy. \tag{44}$$

Note that undersmoothing leads to confidence intervals of asymptotic length $O_P(n^{-3/8})$, while the optimal ones would be of length $O_P(n^{-2/5})$. In our simulations, the event times are generated from a Weibull baseline distribution with shape parameter 1.5 and scale 1. The real valued covariate and the censoring time are chosen to be uniformly distributed on the interval $(0, 1)$ and we take $\beta_0 = 0.5$. We note that this setup corresponds to around 35% uncensored observations. Confidence intervals are calculated at the point $x_0 = 0.5$ using 10,000 sets of data and we take bandwidth $b = cn^{-1/4}$, with $c = 1$, and kernel function $k(u) = (35/32)(1 - u^2)^3 \mathbb{1}_{\{|u| \leq 1\}}$.

It is important to note that the performance depends strongly on the choice of the constant c , because the asymptotic length is inversely proportional to c (44). This means that by choosing a smaller c , we get wider confidence intervals, and as a result, higher coverage probabilities. However, it is not clear which would be the optimal choice of such a constant. This is actually a common problem in the literature (see for example Cheng *et al.*, 2006 and González-Manteiga *et al.*, 1996). As indicated in Müller & Wang (1990), cross-validation methods that consider a trade-off between bias and variance suffer from the fact that the variance of the estimator increases as one approaches the endpoint of the support. This is even enforced in our setting, because the bias is also decreasing when approaching the endpoint of the support. We tried a locally adaptive choice of the bandwidth, as proposed in Müller & Wang (1990), by minimizing an estimator of the Mean Squared Error, but in our setting, this method did not lead to better results. A simple choice is to take c equal to the range of the data (Groeneboom & Jongbloed, 2015), which in our case corresponds to $c = 1$.

Table 1 shows the performance of the estimators. The four columns corresponding to SG and SMLE list the average length (AL) and the coverage probabilities (CP) of the confidence intervals given in (43) for various sample sizes. Results indicate that the SMLE behaves slightly better, but as the sample size increases, its behaviour becomes comparable with that of the SG estimator. Even though the coverage probabilities are below the nominal level of 95%,

Table 1. The AL and the CP for 95% pointwise confidence intervals of the baseline hazard rate at the point $x_0 = 0.5$ based on the asymptotic distribution.

n	SG		SMLE		SG ₀		SMLE ₀		Kernel		Grenander	
	AL	CP	AL	CP	AL	CP	AL	CP	AL	CP	AL	CP
50	1.411	0.732	1.583	0.751	1.281	0.915	1.426	0.944	1.458	0.727	0.980	0.440
100	0.996	0.740	1.101	0.796	0.984	0.941	1.057	0.958	1.055	0.756	0.757	0.500
500	0.545	0.824	0.563	0.857	0.538	0.949	0.559	0.977	0.560	0.822	0.449	0.615
1,000	0.421	0.852	0.430	0.883	0.419	0.957	0.430	0.979	0.429	0.845	0.359	0.657
5,000	0.232	0.910	0.234	0.916	0.232	0.969	0.234	0.981	0.234	0.884	0.215	0.764

SG and SMLE use $\hat{\beta}_n$, while SG₀ and SMLE₀ use β_0 . AL, average length; CP, coverage probabilities; SMLE, smoothed maximum likelihood estimator.

smoothing leads to significantly more accurate results in comparison with the non-smoothed Grenander-type estimator given in the last two columns of Table 1. The confidence intervals for the Grenander-type estimator are constructed on the basis of theorem 2 in Lopuhaä & Nane (2013), i.e., they are of the form $\tilde{\lambda}_n(x_0) \pm n^{-1/3}\hat{C}_n(x_0)q_{1-\alpha/2}(\mathbb{Z})$, where

$$\hat{C}_n(x_0) = \left(\frac{4\tilde{\lambda}_n(x_0)\tilde{\lambda}'_n(x_0)}{\Phi_n(x_0; \hat{\beta}_n)} \right)^{1/3}$$

$q_\alpha(\mathbb{Z})$ is the α -quantile of the distribution of $\mathbb{Z} = \operatorname{argmin}_{t \in \mathbb{R}} \{W(t) + t^2\}$, with W as a standard two-sided Brownian motion starting from zero. In particular, $q_{0.975}(\mathbb{Z}) = 0.998181$. The main advantage of using the non-smoothed Grenander-type estimator is that it does not involve the choice of a tuning parameter. However, the performance is not satisfactory, because we still need to estimate the derivative of λ_0 , which is difficult if the estimator of λ_0 is a step function. Here, we use the slope of the segment $[\tilde{\lambda}_n(T_{(i)}, \tilde{\lambda}_n(T_{(i+1)})]$ on the interval $[T_{(i)}, T_{(i+1)}]$ that contains x_0 .

We also compare the performance of the SG estimator and the SMLE with that of the ordinary (non-monotone) kernel estimator

$$\lambda_n^s(x_0) = \int k_b(x_0 - u) d\Lambda_n(u),$$

which is shown in columns 10–11 of Table 1. We note that the kernel estimator coincides with the naive estimator that approximates the isotonized smoothed Breslow estimator, see Section 4 in Lopuhaä & Musta (2017a). In their proof of theorem 4.3, it is shown that λ_n^s exhibits a limit distribution that coincides with the one of the smooth estimators in theorem 3.5. Also, the numerical results in Table 1 confirm that the performance of the kernel estimator is comparable with that of the smoothed isotonic estimators. However, we notice that the latter ones have slightly better coverage probabilities and shorter confidence intervals.

Moreover, as noticed in Lopuhaä & Musta (2017a), estimation of the parameter β_0 also has a great effect on the accuracy of the results. The columns 6–9 of Table 1 show that if we use the true value of β_0 in the computation of the estimators, the coverage probabilities increase significantly, but in this case, the confidence intervals for the SMLE become too conservative. Although the partial ML estimator $\hat{\beta}_n$ is a standard estimator for the regression coefficients, the efficiency results are only asymptotic. As pointed out in Cox & Oakes (1984) and Ren & Zhou (2011), for finite samples, the use of the partial likelihood leads to a loss of accuracy. Recently, Ren & Zhou (2011) introduced the MLE for β_0 obtained by joint maximization of the loglikelihood in the Cox model over both β and λ_0 . It was shown that for small and moderate

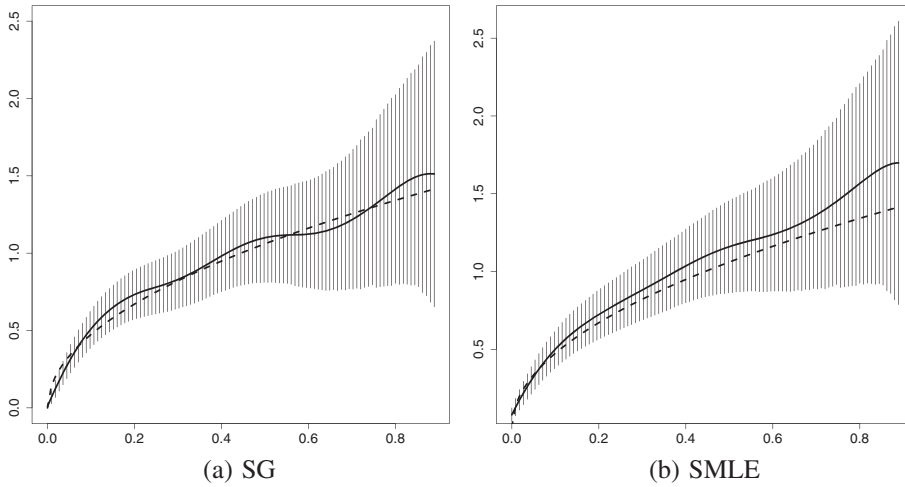


Fig. 2. 95% pointwise confidence intervals based on the asymptotic distribution for the baseline hazard rate using undersmoothing. SMLE, smoothed maximum likelihood estimator.

sample sizes, the joint MLE for β_0 performs better than $\hat{\beta}_n$. However, in our case, using this estimator instead of $\hat{\beta}_n$, does not bring any essential difference in the coverage probabilities.

Pointwise confidence intervals, for a fixed sample size $n = 500$, at different points of the support are illustrated in Figure 2. The results are again comparable and the common feature is that the length increases as we move to the left boundary. This is due to the fact that the length is proportional to the asymptotic standard deviation, which in this case turns out to be increasing, $\sigma^2(x) = 1.5\sqrt{x}/(c\Phi(x; \beta_0))$. Note that $\Phi(x; \beta_0)$ defined in (2) is decreasing.

4.2. Bootstrap confidence intervals

In an attempt to improve the coverage probabilities, we also construct bootstrap confidence intervals. Studies on bootstrap confidence intervals in the Cox model are investigated in Burr (1994) and Xu *et al.* (2014). In the latter paper, the authors investigate several bootstrap procedures for the Cox model. We will use one (method M5) of the two proposals for a smooth bootstrap that had the best performance and were recommended by the authors.

We fix the covariates and we generate the event time X_i^* from a smooth estimate for the cdf of X conditional on Z_i :

$$\hat{F}_n(x | Z_i) = 1 - \exp \left\{ -\Lambda_n^S(x) e^{\hat{\beta}'_n Z_i} \right\},$$

where Λ_n^S is the smoothed Breslow estimator

$$\Lambda_n^S(x) = \int k_b(x - u) \Lambda_n(u) du.$$

The censoring times C_i^* are generated from the Kaplan–Meier estimate \hat{G}_n . Then we take $T_i^* = \min(X_i^*, C_i^*)$ and $\Delta_i^* = \mathbf{1}_{\{X_i^* \leq C_i^*\}}$. For constructing the confidence intervals, we take 1,000 bootstrap samples (T_i^*, Δ_i^*, Z_i) , and for each bootstrap sample, we compute the smoothed Grenander-type estimate $\hat{\lambda}_n^{SG,*}(x_0)$ and the smoothed maximum likelihood estimate $\hat{\lambda}_n^{SM,*}(x_0)$. Here, the kernel function is the same as before and the bandwidth is taken to be $b = n^{-1/5}$. Then, the $100(1 - \alpha)\%$ confidence interval is given by

$$[q_{\alpha/2}^*(x_0), q_{1-\alpha/2}^*(x_0)], \tag{45}$$

where $q_{\alpha}^*(x_0)$ is the α -percentile of the 1,000 values of the estimates $\tilde{\lambda}_n^{SG,*}(x_0)$ or $\hat{\lambda}_n^{SM,*}(x_0)$.

The average length and the empirical coverage for 1,000 iterations and different sample sizes are reported in Table 2. We observe that bootstrap confidence intervals behave better than confidence intervals in Table 1, i.e., the coverage probabilities are closer to the nominal level of 95%. Comparing also with the two alternative estimators considered in Lopuhaä & Musta (2017a), we notice that the SMLE and the MSLE have better coverage probabilities than the smoothed Grenander-type and isotonized Breslow estimator, respectively.

In order to provide some theoretical evidence for the consistency of the method, we would like to establish that, given the data $(T_1, \Delta_1, Z_1), \dots, (T_n, \Delta_n, Z_n)$, it holds

$$n^{2/5} (\lambda_n^{SI,*}(x) - \lambda_n^{SI}(x)) \xrightarrow{d} N(\tilde{\mu}, \sigma^2), \tag{46}$$

for some $\tilde{\mu} \in \mathbb{R}$ (possibly different from μ in theorem 3.5) and σ^2 as in (29), where λ_n^{SI} is one of the smooth isotonic estimators at hand and $\lambda_n^{SI,*}$ is the same estimator computed for the bootstrap sample. A detailed investigation of (46) is beyond the scope of this paper. Nevertheless, in view of Remark 3.6, we are able to obtain (46) for the smoothed Grenander estimator, if $\hat{\beta}_n^* - \hat{\beta}_n \rightarrow 0$, for almost all sequences $(T_i^*, \Delta_i^*, Z_i), i = 1, 2, \dots$, conditional on the sequence $(T_i, \Delta_i, Z_i), i = 1, 2, \dots$, and $\sqrt{n}(\hat{\beta}_n^* - \hat{\beta}_n) = O_p(1)$. By the latter, we mean that for all $\epsilon > 0$, there exists $M > 0$, such that

$$\limsup_{n \rightarrow \infty} P_n^* (\sqrt{n} |\hat{\beta}_n^* - \hat{\beta}_n| > M) < \epsilon, \quad \mathbb{P} - \text{almost surely.}$$

where P_n^* is the measure corresponding to the distribution of (T^*, Δ^*, Z) conditional on the data $(T_1, \Delta_1, Z_1), \dots, (T_n, \Delta_n, Z_n)$, with $T^* = (\min(X^*, C^*))$ and $\Delta^* = \mathbb{1}_{\{X^* \leq C^*\}}$, Z , where X^* conditional on Z has distribution function $\hat{F}_n(x | Z)$ and C^* has distribution function \hat{G}_n . To prove (46), we mimic the proof of theorem 3.5, which means that one needs to establish the bootstrap versions of lemmas 3.1–3.4. A brief sketch of the arguments is provided in Appendix C of Supporting Information.

Then, we can approximate the distribution of $n^{2/5}(\lambda_0(x_0) - \lambda_n^{SI}(x_0))$ by the distribution of $n^{2/5}(\lambda_n^{SI,*}(x_0) - \lambda_n^{SI}(x_0)) - (\tilde{\mu} + \mu)$. Consequently, we can write

$$\begin{aligned} P_n^* \{q_{\alpha/2}^*(x_0) \leq \lambda_n^{SI,*}(x) \leq q_{1-\alpha/2}^*(x_0)\} \\ = P_n^* \left\{ \lambda_0(x_0) \in \left[q_{\alpha/2}^*(x_0) - n^{-2/5}(\tilde{\mu} + \mu), q_{1-\alpha/2}^*(x_0) - n^{-2/5}(\tilde{\mu} + \mu) \right] \right\} \end{aligned}$$

Table 2. The AL and the CP for the 95% bootstrap confidence intervals of the baseline hazard rate at the point $x_0 = 0.5$, using the tri-weight kernel and $b = n^{-2/5}$.

n	SMLE		SG	
	AL	CP	AL	CP
100	1.870	0.948	1.376	0.899
500	0.730	0.942	0.660	0.892
1,000	0.521	0.960	0.487	0.902
5,000	0.247	0.957	0.239	0.938

AL, average length; CP, coverage probabilities; SMLE, smoothed maximum likelihood estimator.

Table 3. The AL and the CP for the 95% bootstrap confidence intervals of the baseline hazard rate at the point $x_0 = 0.5$, using the tri-weight kernel and $b = n^{-1/4}$.

n	SMLE		SG	
	AL	CP	AL	CP
100	1.901	0.954	1.415	0.900
500	0.749	0.951	0.672	0.918
1,000	0.540	0.950	0.501	0.924
5,000	0.262	0.965	0.252	0.952

AL, average length; CP, coverage probabilities; SMLE, smoothed maximum likelihood estimator.

This means that we should actually take $[q_{\alpha/2}^*(x_0), q_{1-\alpha/2}^*(x_0)] - n^{-2/5}(\tilde{\mu} + \mu)$ instead of (45). The use of (45) avoids bias estimation. However, because the effect of the bias is of the order $n^{-2/5}$, the results are still satisfactory. In order to further reduce the effect of the bias, we also investigated the possibility of constructing bootstrap confidence intervals with undersmoothing, i.e. we repeat the previous procedure with bandwidth $b = n^{-1/4}$. Results are shown in Table 3. We notice that the length of the confidence interval increases slightly and the coverage probabilities improve significantly. To summarize, also the bootstrap confidence intervals are affected by the choice of the bandwidth, but the results are more satisfactory in comparison with the ones in Table 1.

5. Discussion

In this paper, we considered smooth estimation under monotonicity constraints of the baseline hazard rate in the Cox model. We investigated the asymptotic behaviour of two estimators, which are the kernel smoothed versions of the monotone MLE and a Grenander-type estimator. The main result is that they are asymptotically equivalent with a normal limit distribution at rate $n^{-m/(2m+1)}$, where m is the degree of smoothness assumed for the baseline hazard. Two other methods that combine smoothing and isotonization for estimation of the baseline hazard in the Cox model were considered in Lopuhaä & Musta (2017a). As shown in theorems 3.6 and 4.4 in Lopuhaä & Musta (2017a), the smoothed Grenander-type estimator, the SMLE and the isotonized kernel estimator are all asymptotically equivalent, while the MSLE exhibits a different asymptotic bias (which might be smaller or larger than the one of the previous three estimators). This means that, from the theoretical point of view, there is no reason to prefer one estimator with respect to the other (apart from the fact that the kernel smoothed estimators are differentiable while the other two are usually only continuous).

The method used to establish asymptotic normality for the estimators in this paper is quite different from the ones in Lopuhaä & Musta (2017a). In the latter paper, the isotonization step was performed after a smoothing step. As a consequence, the resulting estimators are asymptotically equivalent to corresponding naive estimators that are combinations of ordinary kernel type estimators, to which standard techniques apply. This approach does not apply to the smoothed isotonic estimators in this paper. Alternatively, we followed the approach from Groeneboom & Jongbloed (2014) based on L_2 -bounds for the isotonic estimator. The approach had to be adapted at several points leading to L_2 -bounds that are suboptimal, but sufficient for our purposes.

Furthermore, we investigated also the finite sample performance of these estimators by constructing pointwise confidence intervals. First, making use of the theoretical results, we

construct pointwise confidence intervals based on the limit distribution with undersmoothing to avoid bias estimation. Results confirm the comparable behaviour of the four methods and favour the use of the smoothed isotonic estimators instead of the unsmoothed Grenander-type estimator or the non-isotonic kernel estimator. However, coverage probabilities are far from the nominal level and strongly depend on the choice of the bandwidth and the accuracy in the estimation of the regression coefficient β_0 . Because most of the well-known methods to overcome these problems do not seem to work in our setting, a thorough investigation is still needed for improving the performance of the confidence intervals. Instead, we choose to exploit pointwise confidence intervals based on bootstrap procedures. As it turns out, the simple percentile bootstrap works better than the studentized one. Such a phenomenon was also observed in Burr (1994). The four estimators, the SMLE, the smoothed Grenander-type estimator, the MSLE and the isotonized smoothed Breslow estimator, again exhibit comparable behaviour, but the SMLE and the MSLE have slightly better coverage probabilities. The performance is satisfactory, but still further investigation is required for bandwidth selection and correcting the asymptotic bias, which might improve the results.

6. Proofs

Proof of Lemma 3.1. Define $D_n^{(1)}(x; \beta) = \partial\Phi_n(x; \beta)/\partial\beta$ and let $D_{nj}^{(1)}(x; \beta)$ be the j th component of $D_n^{(1)}(x; \beta)$, for $j = 1, \dots, p$. Then according to the proof of lemma 3(iv) in Lopushaä & Nane (2013), for any sequence β_n^* , such that $\beta_n^* \rightarrow \beta_0$ almost surely, it holds

$$\limsup_{n \rightarrow \infty} \sup_{x \in \mathbb{R}} |D_n^{(1)}(x; \beta_n^*)| < \infty.$$

In fact, from its proof, it can be seen that

$$\begin{aligned} \sup_{x \in \mathbb{R}} |D_{nj}^{(1)}(x; \beta_n^*)| &\leq \sum_{I_k \subseteq I} \left[\frac{1}{n} \sum_{i=1}^n |Z_i| e^{\gamma'_k Z_i} \right] \rightarrow \sum_{I_k \subseteq I} \mathbb{E} \left[|Z| e^{\gamma'_k Z} \right] \\ &< 2^p \sup_{|\beta - \beta_0| \leq \epsilon} \mathbb{E} \left[|Z| e^{\beta' Z} \right] < \infty \end{aligned}$$

with probability 1, where the summations are over all subsets $I_k = \{i_1, \dots, i_k\}$ of $I = \{1, \dots, p\}$, and γ_k is the vector consisting of coordinates $\gamma_{kj} = \beta_{0j} + \epsilon/(2\sqrt{p})$, for $j \in I_k$, and $\gamma_{kj} = \beta_{0j} - \epsilon/(2\sqrt{p})$, for $j \in I \setminus I_k$. Therefore,

$$\sup_{x \in \mathbb{R}} |D_n^{(1)}(x; \beta_n^*)| \leq \sqrt{p} \sum_{I_k \subseteq I} \left(\frac{1}{n} \sum_{i=1}^n |Z_i| e^{\gamma'_k Z_i} \right) \rightarrow \sqrt{p} \sum_{I_k \subseteq I} \mathbb{E} \left[|Z| e^{\gamma'_k Z} \right]$$

with probability one. Hence, if for some $\xi_1 > 0$,

$$E_{n,1} = \left\{ \left| \sqrt{p} \sum_{I_k \subseteq I} \left(\frac{1}{n} \sum_{i=1}^n |Z_i| e^{\gamma'_k Z_i} \right) - \sqrt{p} \sum_{I_k \subseteq I} \mathbb{E} \left[|Z| e^{\gamma'_k Z} \right] \right| \leq \xi_1 \right\}, \tag{47}$$

then $\mathbb{1}_{E_{n,1}} \rightarrow 1$ in probability. Moreover, on this event, we have

$$\sup_{x \in \mathbb{R}} |D_n^{(1)}(x; \beta_n^*)| \leq \sqrt{p} \sum_{I_k \subseteq I} \mathbb{E} \left[|Z| e^{\gamma'_k Z} \right] + \xi_1, \tag{48}$$

i.e., $\sup_{x \in \mathbb{R}} |D_n^{(1)}(x; \beta_n^*)|$ is bounded uniformly in n . For $\xi_2, \xi_3, \xi_4 > 0$ and $0 < M < \tau_H$ define

$$\begin{aligned}
 E_{n,2} &= \left\{ n^{2/3} |\hat{\beta}_n - \beta_0|^2 < \xi_2 \right\}, & E_{n,3} &= \left\{ \sup_{x \in [0, M]} |\tilde{\Lambda}_n(x) - \Lambda_0(x)| < \xi_3 \right\}, \\
 E_{n,4} &= \left\{ n^{1/3} \sup_{x \in \mathbb{R}} |\Phi_n(x; \beta_0) - \Phi(x; \beta_0)| \leq \xi_4 \right\}, & E_{n,5} &= \{T_{(n)} > M\},
 \end{aligned}
 \tag{49}$$

where $T_{(n)}$ denotes the last observed time. Because $\sqrt{n}(\hat{\beta}_n - \beta_0) = O_p(1)$ (see theorem 3.2 in Tsiatis (1981)), together with (7) and lemma 4 in Lopuhaä & Nane (2013), it follows that $\mathbb{1}_{E_n} \rightarrow 1$ in probability, for the event $E_n = E_{n,1} \cap E_{n,2} \cap E_{n,3} \cap E_{n,4} \cap E_{n,5}$.

From the definitions of $a_{n,x}$, $\theta_{n,x}$ and H^{uc} , in (17), (18) and (1), respectively, we have

$$\begin{aligned}
 \int \theta_{n,x}(u, \delta, z) d\mathbb{P}(u, \delta, z) &= \mathbb{1}_{E_n} \left\{ \int a_{n,x}(u) dH^{uc}(u) \right. \\
 &\quad \left. - \int e^{\hat{\beta}'_n z} \int_{v=0}^u a_{n,x}(v) d\tilde{\Lambda}_n(v) d\mathbb{P}(u, \delta, z) \right\}.
 \end{aligned}$$

Then, by applying Fubini's theorem, together with (3), we obtain

$$\begin{aligned}
 &\int \theta_{n,x}(u, \delta, z) d\mathbb{P}(u, \delta, z) \\
 &= \mathbb{1}_{E_n} \left\{ \int a_{n,x}(u) dH^{uc}(u) - \int a_{n,x}(v) \int_{u=v}^\infty e^{\hat{\beta}'_n z} d\mathbb{P}(u, \delta, z) d\tilde{\Lambda}_n(v) \right\} \\
 &= \mathbb{1}_{E_n} \left\{ \int a_{n,x}(u) dH^{uc}(u) - \int a_{n,x}(v) \Phi(v; \hat{\beta}_n) d\tilde{\Lambda}_n(v) \right\} \\
 &= \mathbb{1}_{E_n} \left\{ \int \frac{k_b(x-u)}{\Phi(u; \beta_0)} dH^{uc}(u) - \int k_b(x-u) \frac{\Phi(u; \hat{\beta}_n)}{\Phi(u; \beta_0)} d\tilde{\Lambda}_n(u) \right\} \\
 &= \mathbb{1}_{E_n} \left\{ - \int k_b(x-u) d(\tilde{\Lambda}_n - \Lambda_0)(u) + \int k_b(x-u) \left(1 - \frac{\Phi(u; \hat{\beta}_n)}{\Phi(u; \beta_0)} \right) d\tilde{\Lambda}_n(u) \right\}.
 \end{aligned}$$

The mean value theorem yields

$$\begin{aligned}
 \int k_b(x-u) \left| 1 - \frac{\Phi(u; \hat{\beta}_n)}{\Phi(u; \beta_0)} \right| d\tilde{\Lambda}_n(u) &= \int k_b(x-u) \frac{|\Phi(u; \beta_0) - \Phi(u; \hat{\beta}_n)|}{\Phi(u; \beta_0)} d\tilde{\Lambda}_n(u) \\
 &\leq |\hat{\beta}_n - \beta_0| \sup_{y \in \mathbb{R}} \left| \frac{\partial \Phi(y; \beta^*)}{\partial \beta} \right| \frac{\tilde{\lambda}_n^{SG}(x)}{\Phi(x+b; \beta_0)},
 \end{aligned}$$

with $|\beta^* - \beta_0| \leq |\hat{\beta}_n - \beta_0|$. According to lemma 3(iii) in Lopuhaä & Nane (2013), for $\epsilon > 0$ from (A2),

$$\sup_{y \in \mathbb{R}} \left| \frac{\partial \Phi(y; \beta^*)}{\partial \beta} \right| < \sup_{y \in \mathbb{R}} \sup_{|\beta - \beta_0| < \epsilon} \left| \frac{\partial \Phi(y; \beta)}{\partial \beta} \right| < \infty.$$

Furthermore, there exists $M < \tau_H$, such that for sufficiently large n , we have $x + b \leq M$. This yields the following bound $\Phi(x + b; \beta_0) \geq \Phi(M; \beta_0) > 0$. Moreover, according to (12), $\tilde{\lambda}_n^{SG}(x) \rightarrow \lambda_0(x)$ with probability one. Because $|\hat{\beta}_n - \beta_0| = O_p(n^{-1/2})$ (see theorem 3.1 in Tsiatis (1981)), it follows that

$$\mathbb{1}_{E_n} \int k_b(x - u) \left| 1 - \frac{\Phi(u; \hat{\beta}_n)}{\Phi(u; \beta_0)} \right| d\tilde{\Lambda}_n(u) = O_p(n^{-1/2}),$$

which finishes the proof. □

Proof of Lemma 3.2. By means of Fubini's theorem

$$\begin{aligned} & \int \bar{\theta}_{n,x}(u, \delta, z) d\mathbb{P}_n(u, \delta, z) \\ &= \int \delta \bar{\Psi}_{n,x}(u) d\mathbb{P}_n(u, \delta, z) - \int e^{\hat{\beta}'_n z} \int_{v=0}^u \bar{\Psi}_{n,x}(v) d\tilde{\Lambda}_n(v) d\mathbb{P}_n(u, \delta, z) \\ &= \int \delta \bar{\Psi}_{n,x}(u) d\mathbb{P}_n(u, \delta, z) - \int \bar{\Psi}_{n,x}(v) \int \mathbb{1}_{\{u \geq v\}} e^{\hat{\beta}'_n z} d\mathbb{P}_n(u, \delta, z) d\tilde{\Lambda}_n(v) \\ &= \mathbb{1}_{E_n} \left\{ \int \mathbb{1}_{[x-b, x+b]}(u) \delta \frac{\bar{a}_{n,x} \bar{\Phi}_n(u; \hat{\beta}_n)}{\Phi_n(u; \hat{\beta}_n)} d\mathbb{P}_n(u, \delta, z) - \int_{x-b}^{x+b} \bar{a}_{n,x} \bar{\Phi}_n(v; \hat{\beta}_n) d\tilde{\Lambda}_n(v) \right\} \\ &= \mathbb{1}_{E_n} \sum_{i=0}^m \bar{a}_{n,x} \bar{\Phi}_n(\tau_i + 1; \hat{\beta}_n) \left\{ \int \frac{\mathbb{1}_{(\tau_i, \tau_{i+1}]}(u) \delta}{\Phi_n(u; \hat{\beta}_n)} d\mathbb{P}_n(u, \delta, z) - (\tilde{\Lambda}_n(\tau_{i+1}) - \tilde{\Lambda}_n(\tau_i)) \right\} \end{aligned}$$

and (23) follows from the characterization of the Breslow estimator in (6). □

To obtain suitable bounds for (26), we will establish bounds on the tail probabilities of $\tilde{U}_n(a)$ defined in (24). To this end, we consider a suitable martingale that will approximate the process $\Lambda_n - \Lambda_0$. For $i = 1, 2, \dots, n$, let $N_i(t) = \mathbb{1}_{\{X_i \leq t\}} \Delta_i$ be the right continuous counting process for the number of observed failures on $(0, t]$ and $Y_i(t) = \mathbb{1}_{\{T_i \geq t\}}$ be the at-risk process. Then, for each $i = 1, 2, \dots, n$, $M_i(t) = N_i(t) - A_i(t)$, with $A_i(t) = \int_0^t Y_i(s) e^{\beta'_0 Z_i} d\Lambda_0(s)$, is a mean zero martingale with respect to the filtration

$$\mathcal{F}_t^n = \sigma \{ \mathbb{1}_{\{X_i \leq s\}} \Delta_i, \mathbb{1}_{\{T_i \geq s\}}, Z_i : 1 \leq i \leq n, 0 \leq s \leq t \}.$$

(e.g., see kalbfleisch & Prentice, 2002). Furthermore, it is square integrable, because

$$\mathbb{E} [M_i(t)^2] \leq 2 + 2 \int_0^t \mathbb{E} [\mathbb{1}_{\{T_i \geq s\}} e^{2\beta'_0 Z_i}] \lambda_0^2(s) ds \leq 2 + 2\tau_H \lambda_0^2(\tau_H) \Phi(0; 2\beta_0) < \infty.$$

Finally, it has predictable variation process $\langle M_i \rangle = A_i(t)$ (e.g., see Gill, 1984 or theorem 2 of Appendix B in Shorack & Wellner, 1986). For each $n \geq 1$, define

$$\mathbb{N}_n(t) = \sum_{i=1}^n N_i(t), \quad \mathbb{A}_n(t) = \sum_{i=1}^n A_i(t), \quad \mathbb{M}_n(t) = \mathbb{N}_n(t) - \mathbb{A}_n(t). \tag{50}$$

Then $\mathbb{M}_n(t)$ is a mean zero square integrable martingale with predictable variation process

$$\langle \mathbb{M}_n \rangle(t) = \sum_{i=1}^n \langle M_i \rangle(t) = \sum_{i=1}^n \int_0^t \mathbb{1}_{\{T_i \geq s\}} e^{\beta'_0 Z_i} d\Lambda_0(s) = \int_0^t n \Phi_n(s; \beta_0) d\Lambda_0(s),$$

where Φ_n is defined in (4).

Lemma 6.1. *Suppose that (A1)–(A2) hold. Let $0 < M < \tau_H$ and let Φ be defined in (2). Then, the process*

$$\mathbb{B}_n(t) = \int_0^{t \wedge M} \frac{1}{n\Phi(s; \beta_0)} d\mathbb{M}_n(s) \tag{51}$$

is a mean zero, square integrable martingale with respect to the filtration \mathcal{F}_t^n . Moreover, \mathbb{B}_n has predictable variation process

$$\langle \mathbb{B}_n \rangle(t) = \int_0^{t \wedge M} \frac{\lambda_0(s)\Phi_n(s; \beta_0)}{n\Phi^2(s; \beta_0)} ds.$$

Proof. Write

$$\mathbb{B}_n(t) = \int_0^t Y_n(s) d\mathbb{M}_n(s), \quad \text{where } Y_n(s) = \frac{\mathbb{1}_{\{s \leq M\}}}{n\Phi(s; \beta_0)},$$

and $\mathbb{M}_n = \mathbb{N}_n - \mathbb{A}_n$. We apply theorem B.3.1c in Shorack & Wellner (1986) with Y, H, M, N and A , replaced by $\mathbb{B}_n, Y_n, \mathbb{M}_n, \mathbb{N}_n$ and \mathbb{A}_n , respectively. In order to check the conditions of this theorem, note that Y_n is a predictable process satisfying $|Y_n(t)| < \infty$, almost surely, for all $t \geq 0$, and that

$$\begin{aligned} \int_0^t Y_n(s) d\mathbb{A}_n(s) &= \sum_{i=1}^n \int_0^t \frac{\mathbb{1}_{\{s \leq M\}}}{n\Phi(s; \beta_0)} \mathbb{1}_{\{T_i \geq s\}} e^{\beta'_0 Z_i} d\Lambda_0(s) \\ &= \int_0^t \frac{\mathbb{1}_{\{s \leq M\}}}{\Phi(s; \beta_0)} \Phi_n(s; \beta_0) d\Lambda_0(s) < \infty, \quad \text{a.s.} \end{aligned}$$

Moreover, because for $s \leq M$ we have $\Phi(s; \beta_0) \geq \Phi(M; \beta_0) > 0$, it follows that

$$\begin{aligned} \mathbb{E} \left[\int_0^\infty Y_n^2(s) d\langle \mathbb{M}_n \rangle(s) \right] &= \mathbb{E} \left[\int_0^\infty \frac{\mathbb{1}_{\{s \leq M\}}}{n\Phi^2(s; \beta_0)} \Phi_n(s; \beta_0) d\Lambda_0(s) \right] \\ &\leq \frac{\lambda_0(\tau_H)M}{n^2\Phi^2(M; \beta_0)} \sum_{i=1}^n \mathbb{E} \left[e^{\beta'_0 Z_i} \right] < \infty, \end{aligned}$$

because of the assumption (A2). It follows from theorem B.3.1c in Shorack & Wellner (1986) that \mathbb{B}_n is a square integrable martingale with mean zero and predictable variation process

$$\langle \mathbb{B}_n \rangle(t) = \int_0^t Y_n^2(s) d\langle \mathbb{M}_n \rangle(s) = \int_0^t \frac{\mathbb{1}_{\{s \leq M\}}}{n\Phi^2(s; \beta_0)} \Phi_n(s; \beta_0) d\Lambda_0(s),$$

where Φ and Φ_n are defined in (2) and (4), respectively. □

It is straightforward to verify that for $t \in [0, M]$ and $M < T_{(n)}$,

$$\Lambda_n(t) - \Lambda_0(t) = \mathbb{B}_n(t) + R_n(t), \tag{52}$$

where

$$R_n(t) = \int_0^t \frac{\Phi_n(s; \beta_0)}{\Phi(s; \beta_0)} d\Lambda_0(s) - \Lambda_0(t) + \int_0^t \left(\frac{1}{\Phi_n(s; \hat{\beta}_n)} - \frac{1}{\Phi(s; \beta_0)} \right) dH_n^{uc}(s), \tag{53}$$

with

$$H_n^{uc}(x) = \int \delta \mathbb{1}_{\{t \leq x\}} d\mathbb{P}_n(t, \delta, z). \tag{54}$$

For establishing suitable bounds on the tail probabilities of $\tilde{U}_n(a)$, we need the following result for the process \mathbb{B}_n , which is comparable with condition (A2) in Durot (2007).

Lemma 6.2. *Suppose that (A1)–(A2) hold. Let $0 < M < \tau_H$ and let \mathbb{B}_n be defined as in (51). Then, there exists a constant $C > 0$ such that, for all $x > 0$ and $t \in [0, M]$,*

$$\mathbb{E} \left[\sup_{u \in [0, M], |t-u| \leq x} (\mathbb{B}_n(u) - \mathbb{B}_n(t))^2 \right] \leq \frac{C x}{n}.$$

Proof. The proof is similar to that of theorem 3 in Durot (2007). First, consider the case $t \leq u \leq t + x$. According to lemma 6.1, \mathbb{B}_n is a martingale. Hence, by Doob’s inequality, we have

$$\begin{aligned} \mathbb{E} \left[\sup_{u \in [0, M], t \leq u \leq t+x} (\mathbb{B}_n(u) - \mathbb{B}_n(t))^2 \right] &\leq 4\mathbb{E} \left[(\mathbb{B}_n((t+x) \wedge M) - \mathbb{B}_n(t))^2 \right] \\ &= 4\mathbb{E} \left[\mathbb{B}_n((t+x) \wedge M)^2 - \mathbb{B}_n(t)^2 \right] \\ &= 4\mathbb{E} \left[\int_t^{(t+x) \wedge M} \frac{\Phi_n(s; \beta_0) \lambda_0(s)}{n\Phi^2(s; \beta_0)} ds \right] \tag{55} \\ &\leq \frac{4\lambda(M)x}{n\Phi^2(M; \beta_0)} \mathbb{E} [\Phi_n(0; \beta_0)], \end{aligned}$$

where according to (A2),

$$\mathbb{E} [\Phi_n(0; \beta_0)] = \frac{1}{n} \sum_{i=1}^n \mathbb{E} [e^{\beta'_0 Z_i}] \leq C,$$

for some $C > 0$. This proves the lemma for the case $t \leq u \leq t + x$.

For the case $t - x \leq u \leq t$, we can write

$$\begin{aligned} \mathbb{E} \left[\sup_{u \in [0, M], t-x \leq u \leq t} (\mathbb{B}_n(u) - \mathbb{B}_n(t))^2 \right] &= \mathbb{E} \left[\sup_{0 \vee (t-x) \leq u \leq t} (\mathbb{B}_n(u) - \mathbb{B}_n(t))^2 \right] \\ &\leq 2\mathbb{E} \left[(\mathbb{B}_n(t) - \mathbb{B}_n(0 \vee (t-x)))^2 \right] + 2\mathbb{E} \left[\sup_{0 \vee (t-x) \leq u < t} (\mathbb{B}_n(u) - \mathbb{B}_n(0 \vee (t-x)))^2 \right]. \end{aligned}$$

Then similar to (55), the right hand side is bounded by

$$\begin{aligned} &2\mathbb{E} \left[(\mathbb{B}_n(t) - \mathbb{B}_n(0 \vee (t-x)))^2 \right] + 8\mathbb{E} \left[(\mathbb{B}_n(t) - \mathbb{B}_n(0 \vee (t-x)))^2 \right] \\ &= 10\mathbb{E} \left[\mathbb{B}_n(t)^2 - \mathbb{B}_n(0 \vee (t-x))^2 \right] = 10\mathbb{E} \left[\int_{0 \vee (t-x)}^t \frac{\Phi_n(s; \beta_0) \lambda_0(s)}{n\Phi^2(s; \beta_0)} ds \right] \\ &\leq \frac{10\lambda(M)x}{n\Phi^2(M; \beta_0)} \mathbb{E} [\Phi_n(0; \beta_0)] \leq \frac{Cx}{n}, \end{aligned}$$

for some $C > 0$. This concludes the proof. □

In what follows, let $0 < M < \tau_H$. Moreover, let U be the inverse of λ_0 on $[\lambda_0(0), \lambda_0(M)]$, i.e.,

$$U(a) = \begin{cases} 0 & a < \lambda_0(0); \\ \lambda_0^{-1}(a) & a \in [\lambda_0(0), \lambda_0(M)]; \\ M & a > \lambda_0(M). \end{cases} \tag{56}$$

Note that U is continuous and differentiable on $(\lambda_0(0), \lambda_0(M))$, but it is different from the inverse of λ_0 on the entire interval $[\lambda_0(0), \lambda_0(\tau_H)]$.

Lemma 6.3. *Suppose that (A1)–(A2) hold. Let $0 < M < \tau_H$ and let \tilde{U}_n and U be defined in (24) and (56), respectively. Suppose that H^{uc} , defined in (1), has a bounded derivative h^{uc} on $[0, M]$ and that λ'_0 is bounded below by a strictly positive constant. Then, there exists an event E_n , such that $\mathbb{1}_{E_n} \rightarrow 1$ in probability, and a constant K such that, for every $a \geq 0$ and $x > 0$,*

$$\mathbb{P}(\{|\tilde{U}_n(a) - U(a)| \geq x\} \cap E_n \cap \{\tilde{U}_n(a) \leq M\}) \leq K \max\left\{\frac{1}{nx^3}, \frac{1}{n^3x^5}\right\}, \tag{57}$$

for n sufficiently large.

Note that lemmas 6.2 and 6.3 correspond to theorem 3(i) and lemma 2 in Durot (2007). It is useful to spend some words on the restriction to the event $E_n \cap \{\tilde{U}_n(a) \leq M\}$. The event $\{\tilde{U}_n(a) \leq M\}$ is implicit in Durot (2007), because there the Grenander-type estimator is defined by only considering Λ_n on a compact interval not containing the end point of the support. The event E_n is needed in our setup because of the presence of the covariates, which lead to more complicated processes, and because we require (25) for $p = 2$.

Proof of Lemma 6.3. First, we note that from the definition of U and the fact that \tilde{U}_n is increasing, it follows that $|\tilde{U}_n(a) - U(a)| \leq |\tilde{U}_n(\lambda_0(0)) - U(\lambda_0(0))|$, if $a \leq \lambda_0(0)$, and

$$\mathbb{1}_{\{\tilde{U}_n(a) \leq M\}} |\tilde{U}_n(a) - U(a)| \leq \mathbb{1}_{\{\tilde{U}_n(a) \leq M\}} |\tilde{U}_n(\lambda_0(M)) - U(\lambda_0(M))|, \quad \text{if } a \geq \lambda_0(M).$$

Hence, it suffices to prove (57) only for $a \in [\lambda_0(0), \lambda_0(M)]$. Let E_n be the event from lemma 3.1. We start by writing

$$\begin{aligned} &\mathbb{P}(\{|\tilde{U}_n(a) - U(a)| \geq x\} \cap E_n \cap \{\tilde{U}_n(a) \leq M\}) \\ &= \mathbb{P}(\{U(a) + x \leq \tilde{U}_n(a) \leq M\} \cap E_n) + \mathbb{P}(\{\tilde{U}_n(a) \leq U(a) - x\} \cap E_n). \end{aligned} \tag{58}$$

First, consider the first probability on the right hand side of (58). It is zero, if $U(a) + x > M$. Otherwise, if $U(a) + x \leq M$, then $x \leq M$ and

$$\begin{aligned} &\mathbb{P}(\{U(a) + x \leq \tilde{U}_n(a) \leq M\} \cap E_n) \\ &\leq \mathbb{P}(\{\Lambda_n(y) - ay \leq \Lambda_n(U(a)) - aU(a), \text{ for some } y \in [U(a) + x, M]\} \cap E_n) \\ &\leq \mathbb{P}\left(\left\{\inf_{y \in [U(a)+x, M]} (\Lambda_n(y) - ay - \Lambda_n(U(a)) + aU(a)) \leq 0\right\} \cap E_n\right). \end{aligned}$$

From Taylor’s expansion, we obtain $\Lambda_0(y) - \Lambda_0(U(a)) \geq (y - U(a))a + c(y - U(a))^2$, where $c = \inf_{t \in [0, \tau_F]} \lambda'_0(t)/2 > 0$, so that with (52), the probability on the right hand side is bounded by

$$\mathbb{P}\left(\left\{\inf_{y \in [U(a)+x, M]} (\mathbb{B}_n(y) - \mathbb{B}_n(U(a)) + R_n(y) - R_n(U(a)) + c(y - U(a))^2) \leq 0\right\} \cap E_n\right).$$

Let $i \geq 0$ be such that $M - U(a) \in [x2^i, x2^{i+1})$, and note that, on the event E_n one has $T_{(n)} \geq M$. Therefore, if $U(a) < y \leq M$, then $y \leq T_{(n)}$ and $U(a) < T_{(n)}$. It follows that the previous probability can be bounded by

$$\sum_{k=0}^i \mathbb{P}\left(\left\{\sup_{y \in I_k} (|\mathbb{B}_n(y) - \mathbb{B}_n(U(a))| + |R_n(y) - R_n(U(a))|) \geq c x^2 2^{2k}\right\} \cap E_n\right),$$

where the supremum is taken over $y \in [0, M]$, such that $y - U(a) \in [x2^k, x2^{k+1})$. Using that $\mathbb{P}(X + Y \geq \epsilon) \leq \mathbb{P}(X \geq \epsilon/2) + \mathbb{P}(Y \geq \epsilon/2)$, together with the Markov inequality, we can bound this probability by

$$4 \sum_{k=0}^i (c^2 x^4 2^{4k})^{-1} \mathbb{E} \left[\sup_{y \leq M, y-U(a) \in [x2^k, x2^{k+1})} |\mathbb{B}_n(y) - \mathbb{B}_n(U(a))|^2 \right] + 8 \sum_{k=0}^i (c^3 x^6 2^{6k})^{-1} \mathbb{E} \left[\sup_{y < M, y-U(a) \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} |R_n(y) - R_n(U(a))|^3 \right]. \tag{59}$$

We have

$$\mathbb{E} \left[\sup_{y < M, y-U(a) \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} |R_n(y) - R_n(U(a))|^3 \right] \leq 4 \mathbb{E} \left[\sup_{y < M, y-U(a) \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} \left| \int_{U(a)}^y \left(\frac{\Phi_n(s; \beta_0)}{\Phi(s; \beta_0)} - 1 \right) \lambda_0(s) ds \right|^3 \right] + 4 \mathbb{E} \left[\sup_{y < M, y-U(a) \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} \left| \int_{U(a)}^y \left(\frac{1}{\Phi_n(s; \hat{\beta}_n)} - \frac{1}{\Phi(s; \beta_0)} \right) dH_n^{uc}(s) \right|^3 \right]. \tag{60}$$

For the first term in the right hand side of (60), we have

$$\mathbb{E} \left[\sup_{y < M, y-U(a) \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} \left| \int_{U(a)}^y \left(\frac{\Phi_n(s; \beta_0)}{\Phi(s; \beta_0)} - 1 \right) \lambda_0(s) ds \right|^3 \right] \leq \mathbb{E} \left[\mathbb{1}_{E_n} \left(\int_{U(a)}^{(U(a)+x2^{k+1}) \wedge M} \frac{|\Phi_n(s; \beta_0) - \Phi(s; \beta_0)|}{\Phi(s; \beta_0)} \lambda_0(s) ds \right)^3 \right] \leq \frac{x^3 2^{3(k+1)} \lambda_0^3(M)}{\Phi(M; \beta_0)^3} \mathbb{E} \left[\mathbb{1}_{E_n} \sup_{s \in [0, M]} |\Phi_n(s; \beta_0) - \Phi(s; \beta_0)|^3 \right] \leq \frac{x^3 2^{3(k+1)} \lambda_0^3(M) \xi_4}{n \Phi(M; \beta_0)^3},$$

where we have used (49). In order to bound the second term on the right hand side of (60), note that on the event E_n ,

$$\begin{aligned} \sup_{x \in \mathbb{R}} |\Phi_n(x; \hat{\beta}_n) - \Phi(x; \beta_0)| &\leq \sup_{x \in \mathbb{R}} |\Phi_n(x; \hat{\beta}_n) - \Phi_n(x; \beta_0)| + \sup_{x \in \mathbb{R}} |\Phi_n(x; \beta_0) - \Phi(x; \beta_0)| \\ &\leq |\hat{\beta}_n - \beta_0| \sup_{x \in \mathbb{R}} |D_n^{(1)}(x; \beta^*)| + \frac{\xi_4}{n^{1/3}} \leq \frac{\sqrt{\xi_2 L} + \xi_4}{n^{1/3}}. \end{aligned} \tag{61}$$

In particular, for sufficiently large n , we have $\sup_{x \in \mathbb{R}} |\Phi_n(x; \hat{\beta}_n) - \Phi(x; \beta_0)| \leq \Phi(M; \beta_0)/2$, which yields that, for $x \in [0, M]$,

$$\Phi_n(x; \hat{\beta}_n) \geq \Phi(x; \beta_0) - \frac{1}{2} \Phi(M; \beta_0) \geq \frac{1}{2} \Phi(M; \beta_0). \tag{62}$$

Using (61), on the event E_n , for n sufficiently large, we can write

$$\begin{aligned} \sup_{s \in [0, M]} \left| \frac{1}{\Phi_n(s; \hat{\beta}_n)} - \frac{1}{\Phi(s; \beta_0)} \right| &\leq \sup_{s \in [0, M]} \frac{|\Phi_n(s; \hat{\beta}_n) - \Phi(s; \beta_0)|}{\Phi_n(s; \hat{\beta}_n) \Phi(s; \beta_0)} \\ &\leq \frac{2}{\Phi^2(M; \beta_0)} \sup_{s \in [0, M]} |\Phi_n(s; \hat{\beta}_n) - \Phi(s; \beta_0)| \\ &\leq C n^{-1/3}, \end{aligned}$$

for some $C > 0$. Consequently, for the second term in the right hand side of (60), we obtain

$$\begin{aligned} &\mathbb{E} \left[\sup_{y < M, y - U(a) \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} \left| \int_{U(a)}^y \left(\frac{1}{\Phi_n(s; \hat{\beta}_n)} - \frac{1}{\Phi(s; \beta_0)} \right) dH_n^{uc}(s) \right|^3 \right] \\ &\leq \frac{C^3}{n} \mathbb{E} \left[\mathbb{1}_{E_n} \left(\frac{1}{n} \sum_{i=1}^n \Delta_i \mathbb{1}_{\{T_i \in [U(a), (U(a) + x2^{k+1}) \wedge M]\}} \right)^3 \right] \leq \frac{C^3}{n^4} \mathbb{E}[N^3], \end{aligned}$$

where N is a binomial distribution with probability of success

$$\gamma = H^{uc}((U(a) + x2^{k+1}) \wedge M) - H^{uc}(U(a)) \leq \sup_{s \in [0, M]} |h^{uc}(s)| x2^{k+1}.$$

Furthermore,

$$\mathbb{E}[N^3] = n\gamma(1 - 3\gamma + 3n\gamma + 2\gamma^2 - 3n\gamma^2 + n^2\gamma^2) \leq \begin{cases} 7n\gamma & , \text{if } n\gamma \leq 1; \\ 7n^3\gamma^3 & , \text{if } n\gamma > 1. \end{cases}$$

Using lemma 6.2 and the bound in (59), for the first probability on the right hand side of (58), it follows that there exist $K_1, K_2 > 0$, such that for all $a \geq 0, n \geq 1$ and $x > 0$,

$$\begin{aligned} &\mathbb{P}(\{U(a) + x \leq \tilde{U}_n(a) \leq M\} \cap E_n) \\ &\leq K_1 \sum_{k=0}^i \frac{x2^{k+1}}{nx^4 2^{4k}} + K_2 \sum_{k=0}^i \max \left\{ \frac{x2^{k+1}}{n^3 x^6 2^{6k}}, \frac{x^3 2^{3(k+1)}}{nx^6 2^{6k}} \right\} \\ &\leq \frac{2K_1}{nx^3} \sum_{k=0}^{\infty} 2^{-3k} + \max \left\{ \frac{2K_2}{n^3 x^5} \sum_{k=0}^{\infty} 2^{-5k}, \frac{8K_2}{nx^3} \sum_{k=0}^{\infty} 2^{-3k} \right\} \leq K \max \left\{ \frac{1}{nx^3}, \frac{1}{n^3 x^5} \right\}. \end{aligned} \tag{63}$$

We proceed with the second probability on the right hand side of (58). We can assume $x \leq U(a)$, because otherwise $\mathbb{P}(\tilde{U}_n(a) \leq U(a) - x) = 0$. We have

$$\begin{aligned} & \mathbb{P}(\{\tilde{U}_n(a) \leq U(a) - x\} \cap E_n) \\ & \leq \mathbb{P}\left(\left\{\inf_{y \in [0, U(a) - x]} [\Lambda_n(y) - ay - \Lambda_n(U(a)) + aU(a)] \leq 0\right\} \cap E_n\right). \end{aligned}$$

Let $i \geq 0$ be such that $U(a) \in [x2^i, x2^{i+1})$. By a similar argument used to obtain the bound (59), this probability is bounded by

$$\begin{aligned} & 4 \sum_{k=0}^i (c^2 x^4 2^{4k})^{-1} \mathbb{E} \left[\sup_{y \leq U(a), U(a) - y \in [x2^k, x2^{k+1})} |\mathbb{B}_n(y) - \mathbb{B}_n(U(a))|^2 \right] \\ & + 8 \sum_{k=0}^i (c^3 x^6 2^{6k})^{-1} \mathbb{E} \left[\sup_{y \leq U(a), U(a) - y \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} |R_n(y) - R_n(U(a))|^3 \right]. \end{aligned} \tag{64}$$

In the same way as in the first case, we also have

$$\mathbb{E} \left[\sup_{y \leq U(a), U(a) - y \in [x2^k, x2^{k+1})} \mathbb{1}_{E_n} |R_n(y) - R_n(U(a))|^3 \right] \leq K_2 \max \left\{ \frac{x2^{k+1}}{n^3}, \frac{x^3 2^{3(k+1)}}{n} \right\}.$$

Exactly as in (63), lemmas 6.2 and (64) imply that

$$\mathbb{P}(\{\tilde{U}_n(a) \leq U(a) - x\} \cap E_n) \leq K \max \left\{ \frac{1}{nx^3}, \frac{1}{n^3 x^5} \right\},$$

for some positive constant K . Together with (58) and (63), this finishes the proof. □

Lemma 6.4. *Suppose that (A1)–(A2) hold. Let $0 < \epsilon < M' < M < \tau_H$ and suppose that H^{uc} , defined in (1), has a bounded derivative h^{uc} on $[0, M]$. Let $\tilde{\lambda}_n$ be the Grenander-type estimator of a nondecreasing baseline hazard rate λ_0 , which is differentiable with λ'_0 bounded above and below by strictly positive constants. Let E_n be the event from lemma 3.1 and take ξ_3 in (49) such that*

$$0 < \xi_3 < \frac{1}{8} \min \left\{ (M - M')^2, \epsilon^2 \right\} \inf_{x \in [0, \tau_H]} \lambda'_0(x). \tag{65}$$

Then, there exists a constant C such that, for n sufficiently large,

$$\sup_{t \in [\epsilon, M']} \mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} (\lambda_0(t) - \tilde{\lambda}_n(t))^2 \right] \leq C.$$

Proof. It is sufficient to prove that there exist some constants $C_1, C_2 > 0$, such that for each $n \in \mathbb{N}$ and each $t \in (\epsilon, M']$, we have

$$\mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} \left\{ (\tilde{\lambda}_n(t) - \lambda_0(t))_+ \right\}^2 \right] \leq C_1, \tag{66}$$

$$\mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} \left\{ (\lambda_0(t) - \tilde{\lambda}_n(t))_+ \right\}^2 \right] \leq C_2. \tag{67}$$

Let us first consider (66). We will make use of the following result

$$\begin{aligned} \mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} \left\{ (\tilde{\lambda}_n(t) - \lambda_0(t))_+ \right\}^2 \right] &= 2 \int_0^\infty \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) \geq x \right) x \, dx \\ &= 2 \int_0^{2\eta} \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) \geq x \right) x \, dx \\ &\quad + 2 \int_{2\eta}^\infty \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) \geq x \right) x \, dx \\ &\leq 4\eta^2 + 2 \int_{2\eta}^\infty \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) > x/2 \right) x \, dx \\ &\leq 4\eta^2 + 4 \int_\eta^\infty \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) > x \right) x \, dx \end{aligned}$$

for a fixed $\eta > 0$. We distinguish between the cases $a + n^{-1/3}x \leq \lambda_0(M)$ and $a + n^{-1/3}x > \lambda_0(M)$, where $a = \lambda_0(t)$. We prove that, in the first case, there exist a positive constant C such that for all $t \in (\epsilon, M']$ and $n \in \mathbb{N}$, $\mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) > x \right) \leq C/x^3$, for all $x \geq \eta$, and in the second case $\mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) > x \right) = 0$. Then (66) follows immediately.

First, assume $a + n^{-1/3}x \leq \lambda_0(M)$. By the switching relation, we get

$$\begin{aligned} \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) > x \right) &= \mathbb{P} \left(\left\{ \tilde{\lambda}_n(t) > a + n^{-1/3}x \right\} \cap E_n \right) \\ &= \mathbb{P} \left(\left\{ \tilde{U}_n(a + n^{-1/3}x) < t \right\} \cap E_n \right). \end{aligned}$$

Because $a + n^{-1/3}x \leq \lambda_0(M)$, we have $U(a + n^{-1/3}x) \geq M > t$. Furthermore, $\{ \tilde{U}_n(a + n^{-1/3}x) < t \} \subset \{ \tilde{U}_n(a + n^{-1/3}x) < M \}$. Hence, together with lemma 6.3, we can write

$$\begin{aligned} &\mathbb{P} \left(\left\{ \tilde{U}_n(a + n^{-1/3}x) < t \right\} \cap E_n \right) \\ &\leq \mathbb{P} \left(\left\{ \left| U(a + n^{-1/3}x) - \tilde{U}_n(a + n^{-1/3}x) \right| > U(a + n^{-1/3}x) - t \right\} \right. \\ &\quad \left. \cap E_n \cap \left\{ \tilde{U}_n(a + n^{-1/3}x) < M \right\} \right) \tag{68} \\ &\leq K \max \left\{ \frac{1}{n \left(U(a + n^{-1/3}x) - t \right)^3}, \frac{1}{n^3 \left(U(a + n^{-1/3}x) - t \right)^5} \right\} \leq \frac{C}{x^3}, \end{aligned}$$

because $U(a + n^{-1/3}x) - t = U'(\xi_n)n^{-1/3}x$, for some $\xi_n \in (a, a + n^{-1/3}x)$, where $U'(\xi_n) = \lambda'_0(\lambda_0^{-1}(\xi_n))^{-1} \geq 1/\sup_{t \in [0, \tau_H]} \lambda'_0(t) > 0$.

Next, consider the case $a + n^{-1/3}x > \lambda_0(M)$. Note that we cannot argue as in the previous case, because for $a + n^{-1/3}x > \lambda_0(M)$, we always have $U(a + n^{-1/3}x) = M$, so that we loose the dependence on x . However, if $n^{1/3}(\tilde{\lambda}_n(t) - \lambda_0(t)) > x$, then for each $y > t$, we have

$$\tilde{\Lambda}_n(y) - \tilde{\Lambda}_n(t) \geq \tilde{\lambda}_n(t)(y - t) > (a + n^{-1/3}x)(y - t),$$

where $a = \lambda_0(t)$. In particular, for $y = \tilde{M} = M' + (M - M')/2$, we obtain

$$\begin{aligned} & \mathbb{P} \left\{ n^{1/3} \mathbb{1}_{E_n} (\tilde{\lambda}_n(t) - \lambda_0(t)) > x \right\} \\ & \leq \mathbb{P} \left(\left\{ \tilde{\Lambda}_n(\tilde{M}) - \tilde{\Lambda}_n(t) > (a + n^{-1/3}x)(\tilde{M} - t) \right\} \cap E_n \right) \\ & \leq \mathbb{P} \left(\left\{ \tilde{\Lambda}_n(\tilde{M}) - \tilde{\Lambda}_n(t) - (\Lambda_0(\tilde{M}) - \Lambda_0(t)) > \right. \right. \\ & \quad \left. \left. (a + n^{-1/3}x)(\tilde{M} - t) - (\Lambda_0(\tilde{M}) - \Lambda_0(t)) \right\} \cap E_n \right) \\ & \leq \mathbb{P} \left(\left\{ 2 \sup_{x \in [0, M]} |\tilde{\Lambda}_n(x) - \Lambda_0(x)| > (a + n^{-1/3}x - \lambda_0(\tilde{M}))(\tilde{M} - t) \right\} \cap E_n \right), \end{aligned} \tag{69}$$

also using that $\Lambda_0(\tilde{M}) - \Lambda_0(t) \geq \lambda_0(\tilde{M})(\tilde{M} - t)$. Furthermore, because $a + n^{-1/3}x > \lambda_0(M)$, it follows from (65) that

$$(a + n^{-1/3}x - \lambda_0(\tilde{M}))(\tilde{M} - t) \geq \frac{1}{4}(M - M')^2 \inf_{x \in [0, \tau_H]} \lambda'_0(x) \geq 2\xi_3, \tag{70}$$

so that, by the definition of ξ_3 in (49), the probability on the right hand side (69) is zero. This concludes the proof of (66).

Next, we have to deal with (67). Arguing as in the proof of (66), we obtain

$$\mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} \left\{ (\lambda_0(t) - \tilde{\lambda}_n(t))_+ \right\}^2 \right] \leq \eta^2 + 2 \int_\eta^\infty \mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\lambda_0(t) - \tilde{\lambda}_n(t)) \geq x \right) x \, dx,$$

for a fixed $\eta > 0$, where

$$\mathbb{P} \left(n^{1/3} \mathbb{1}_{E_n} (\lambda_0(t) - \tilde{\lambda}_n(t)) \geq x \right) = \mathbb{P} \left(\left\{ \tilde{U}_n(a - n^{-1/3}x) \geq t \right\} \cap E_n \right),$$

with $a = \lambda_0(t)$. First of all, we can assume that $a - n^{-1/3}x \geq 0$, because otherwise $\mathbb{P} \{ \tilde{\lambda}_n(t) \leq a - n^{-1/3}x \} = 0$. Because $t = U(a)$, as before, we write

$$\begin{aligned} & \mathbb{P} \left(\left\{ \tilde{U}_n(a - n^{-1/3}x) \geq t \right\} \cap E_n \right) \\ & \leq \mathbb{P} \left(\left\{ \left| \tilde{U}_n(a - n^{-1/3}x) - U(a - n^{-1/3}x) \right| \geq t - U(a - n^{-1/3}x) \right\} \cap E_n \right). \end{aligned}$$

In order to apply lemma 6.3, we intersect with the event $\tilde{U}_n(a - n^{-1/3}x) \leq M$. Note that

$$\mathbb{P} \left(\left\{ \tilde{U}_n(a - n^{-1/3}x) > M \right\} \cap E_n \right) \leq \mathbb{P} \left(\left\{ \tilde{\lambda}_n(M) \leq a - n^{-1/3}x \right\} \cap E_n \right) = 0.$$

This can be seen as follows. If $\tilde{\lambda}_n(M) \leq a - n^{-1/3}x$, then for each $y < M$, we have

$$\tilde{\Lambda}_n(M) - \tilde{\Lambda}_n(y) \leq \tilde{\lambda}_n(M)(M - y) \leq (a - n^{-1/3}x)(M - y).$$

In particular, for $y = \tilde{M} = M' + (M - M')/2$, similar to (69), we obtain

$$\begin{aligned} & \mathbb{P} \left(\left\{ \tilde{\lambda}_n(M) \leq a - n^{-1/3}x \right\} \cap E_n \right) \\ & \leq \mathbb{P} \left(\left\{ 2 \sup_{x \in [0, M]} |\tilde{\Lambda}_n(x) - \Lambda_0(x)| \geq (-a + n^{-1/3}x + \lambda_0(\tilde{M}))(M - \tilde{M}) \right\} \cap E_n \right). \end{aligned}$$

Because $a = \lambda_0(t) \leq \lambda_0(M')$, we can argue as in (70) and conclude that the probability on the right hand side is zero. It follows that

$$\begin{aligned} & \mathbb{P}\left(\left\{\tilde{U}_n(a - n^{-1/3}x) \geq t\right\} \cap E_n\right) \\ & \leq \mathbb{P}\left(\left\{\left|\tilde{U}_n(a - n^{-1/3}x) - U(a - n^{-1/3}x)\right| \geq t - U(a - n^{-1/3}x)\right\} \right. \\ & \qquad \qquad \qquad \left. \cap E_n \cap \left\{\tilde{U}_n(a - n^{-1/3}x) \leq M\right\}\right) \\ & \leq K \max \left\{ \frac{1}{n(t - U(a - n^{-1/3}x))^3}, \frac{1}{n^3(t - U(a - n^{-1/3}x))^5} \right\}. \end{aligned}$$

To bound the right hand side, we have to distinguish between $a - n^{-1/3}x > \lambda_0(0)$ and $a - n^{-1/3}x \leq \lambda_0(0)$. If $a - n^{-1/3}x > \lambda_0(0)$, then the right hand side is bounded by K/x^3 , because $t - U(a - n^{-1/3}x) = U'(\xi_n)n^{-1/3}x$, for some $\xi_n \in (a - n^{-1/3}x, a)$, where $U'(\xi_n) = \lambda'_0(\lambda_0^{-1}(\xi_n))^{-1} \geq 1/\sup_{t \in [0, \tau_H]} \lambda'_0(t) > 0$. Otherwise, if $a - n^{-1/3}x \leq \lambda_0(0)$, then we are done because then $\mathbb{P}\left(n^{1/3}\mathbb{1}_{E_n}(\lambda_0(t) - \tilde{\lambda}_n(t)) \geq x\right) = 0$. This can be seen as follows. When $a - n^{-1/3}x \leq \lambda_0(0)$, then for each $y < t$, we have

$$\tilde{\Lambda}_n(t) - \tilde{\Lambda}_n(y) \leq \tilde{\lambda}_n(t)(t - y) \leq (a - n^{-1/3}x)(t - y).$$

In particular, for $y = \epsilon' = \epsilon/2$, we obtain

$$\begin{aligned} & \mathbb{P}\left(n^{1/3}\mathbb{1}_{E_n}\left(\lambda_0(t) - \tilde{\lambda}_n(t)\right) \geq x\right) \\ & \leq \mathbb{P}\left(\left\{\tilde{\Lambda}_n(t) - \tilde{\Lambda}_n(\epsilon') \leq (a - n^{-1/3}x)(t - \epsilon')\right\} \cap E_n\right) \\ & \leq \mathbb{P}\left(\left\{\tilde{\Lambda}_n(t) - \tilde{\Lambda}_n(\epsilon') - (\Lambda_0(t) - \Lambda_0(\epsilon'))\right. \right. \\ & \qquad \qquad \qquad \left. \left. \leq (a - n^{-1/3}x)(t - \epsilon') - (\Lambda_0(t) - \Lambda_0(\epsilon'))\right\} \cap E_n\right) \\ & \leq \mathbb{P}\left(\left\{2 \sup_{x \in [0, M]} |\tilde{\Lambda}_n(x) - \Lambda_0(x)| \geq (-a + n^{-1/3}x)(t - \epsilon') + \lambda_0(\epsilon')(t - \epsilon')\right\} \cap E_n\right). \end{aligned}$$

Because $a - n^{-1/3}x \leq \lambda_0(0)$, we can argue as in (70),

$$\begin{aligned} (-a + n^{-1/3}x + \lambda_0(\epsilon'))(t - \epsilon') & \geq (\lambda_0(\epsilon') - \lambda_0(0))(\epsilon - \epsilon') \\ & \geq \frac{1}{4}\epsilon^2 \inf_{x \in [0, \tau_H]} \lambda'_0(x) \geq 2\xi_3, \end{aligned} \tag{71}$$

and conclude that the probability on the right hand side is zero. This concludes the proof of (67). □

Lemma 6.5. *Suppose that (A1)–(A2) hold. Fix $x \in (0, \tau_h)$. Let $0 < \epsilon < x < M' < M < \tau_H$ and suppose that H^{uc} , defined in (1), has a bounded derivative h^{uc} on $[0, M]$. Let $\tilde{\lambda}_n$ be the Grenander-type estimator of a nondecreasing baseline hazard rate λ_0 , which is differentiable with λ'_0 bounded above and below by strictly positive constants. Let E_n be the event from lemma 3.1 and assume that ξ_3 satisfies (65). Then*

$$\mathbb{1}_{E_n} \int_{x-b}^{x+b} (\lambda_0(t) - \tilde{\lambda}_n(t))^2 dt = O_p(bn^{-2/3}).$$

Proof. Markov’s inequality and Fubini, yield

$$\begin{aligned} & \mathbb{P} \left(b^{-1}n^{2/3} \mathbb{1}_{E_n} \int_{x-b}^{x+b} (\lambda_0(t) - \tilde{\lambda}_n(t))^2 dt > K \right) \\ & \leq \frac{1}{K} \mathbb{E} \left[b^{-1}n^{2/3} \mathbb{1}_{E_n} \int_{x-b}^{x+b} (\lambda_0(t) - \tilde{\lambda}_n(t))^2 dt \right] \\ & \leq \frac{2}{K} \sup_{t \in [x-b, x+b]} \mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} (\lambda_0(t) - \tilde{\lambda}_n(t))^2 \right]. \end{aligned}$$

For n sufficiently large $[x - b, x + b] \subset [\epsilon, M']$, so that according to lemma 6.4, the right hand side is bounded by $2C/K$, for some constant $C > 0$. This proves the lemma. \square

Proof of Lemma 3.3. Take $x < M < \tau_H$ and n sufficiently large such that $x + b \leq M$. With $\bar{a}_{n,x} \bar{\Phi}_n$ defined in (19), we have

$$\begin{aligned} & \int \{ \bar{\theta}_{n,x}(u, \delta, z) - \theta_{n,x}(u, \delta, z) \} d\mathbb{P}(u, \delta, z) \\ & = \mathbb{1}_{E_n} \int \mathbb{1}_{[x-b, x+b]}(u) \delta \left(\frac{\bar{a}_{n,x} \bar{\Phi}_n(u; \hat{\beta}_n)}{\Phi_n(u; \hat{\beta}_n)} - a_{n,x}(u) \right) d\mathbb{P}(u, \delta, z) \\ & \quad - \mathbb{1}_{E_n} \int e^{\hat{\beta}'_n z} \int_0^u (\bar{\Psi}_{n,x}(v) - a_{n,x}(v)) d\tilde{\Lambda}_n(v) d\mathbb{P}(u, \delta, z) \tag{72} \\ & = \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\frac{\bar{a}_{n,x} \bar{\Phi}_n(u; \hat{\beta}_n)}{\Phi_n(u; \hat{\beta}_n)} - a_{n,x}(u) \right) dH^{uc}(u) \\ & \quad - \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\frac{\bar{a}_{n,x} \bar{\Phi}_n(v; \hat{\beta}_n)}{\Phi_n(v; \hat{\beta}_n)} - a_{n,x}(v) \right) \Phi(v; \hat{\beta}_n) d\tilde{\Lambda}_n(v) \end{aligned}$$

using Fubini, the definition of Φ in (2), and the fact that $\bar{a}_{n,x} \bar{\Phi}_n$ and $a_{n,x}$ are zero outside $[x - b, x + b]$. Write $\hat{\Phi}_n(u) = \Phi_n(u; \hat{\beta}_n)$, $\hat{\Phi}(u) = \Phi(u; \hat{\beta}_n)$, and $\Phi_0(u) = \Phi(u; \beta_0)$. Then the right hand side can be written as

$$\mathbb{1}_{E_n} \int_{x-b}^{x+b} \frac{a_{n,x}(\hat{A}_n(u)) \hat{\Phi}_n(\hat{A}_n(u)) - a_{n,x}(u) \hat{\Phi}_n(u)}{\hat{\Phi}_n(u)} \left(\Phi_0(u) \lambda_0(u) - \hat{\Phi}(u) \tilde{\lambda}_n(u) \right) du,$$

where $\hat{A}_n(u)$ is defined in (20). The Cauchy–Schwarz inequality then yields

$$\begin{aligned} & \left| \int \{ \bar{\theta}_{n,x}(u, \delta, z) - \theta_{n,x}(u, \delta, z) \} d\mathbb{P}(u, \delta, z) \right| \\ & \leq \mathbb{1}_{E_n} \left\| \frac{(a_{n,x} \circ \hat{A}_n)(\hat{\Phi}_n \circ \hat{A}_n) - a_{n,x} \hat{\Phi}_n}{\hat{\Phi}_n} \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2} \left\| (\Phi_0 \lambda_0 - \hat{\Phi} \tilde{\lambda}_n) \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2}. \tag{73} \end{aligned}$$

Furthermore,

$$\begin{aligned}
 & \mathbb{1}_{E_n} \left\| \frac{(a_{n,x} \circ \hat{A}_n)(\hat{\Phi}_n \circ \hat{A}_n) - a_{n,x} \hat{\Phi}_n}{\hat{\Phi}_n} \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2} \\
 & \leq 2 \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\frac{k_b(x - \hat{A}_{n,x}(u))}{\Phi_0(\hat{A}_n(u))} - \frac{k_b(x - u)}{\Phi_0(u)} \right)^2 du \\
 & \quad + 2 \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\frac{k_b(x - \hat{A}_n(u))}{\Phi_0(\hat{A}_n(u))} \right)^2 \frac{(\hat{\Phi}_n(\hat{A}_n(u)) - \hat{\Phi}_n(u))^2}{\hat{\Phi}_n(u)^2} du \\
 & \leq 2 \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\frac{d}{dy} \frac{k_b(x - y)}{\Phi_0(y)} \Big|_{y=\xi_u} \right)^2 (\hat{A}_n(u) - u)^2 du \\
 & \quad + \mathbb{1}_{E_n} \frac{c_1}{b^2 \hat{\Phi}_n(M)^2} \int_{x-b}^{x+b} (\hat{\Phi}_n(\hat{A}_n(u)) - \hat{\Phi}_n(u))^2 du \\
 & \leq \mathbb{1}_{E_n} \frac{c_2}{b^4} \int_{x-b}^{x+b} (\hat{A}_n(u) - u)^2 du + \mathbb{1}_{E_n} \frac{c_1}{b^2 \hat{\Phi}_n(M)^2} \int_{x-b}^{x+b} (\hat{\Phi}_n(\hat{A}_n(u)) - \hat{\Phi}_n(u))^2 du,
 \end{aligned} \tag{74}$$

for some constants $c_1, c_2 > 0$, where we use the boundedness of k' , $d\Phi(x; \beta_0)/dx$ and $1/\Phi(x; \beta_0)$ on $[0, x + b] \subseteq [0, M]$. Then, because $\lambda_0(u) - \lambda_0(\hat{A}_n(u)) = \lambda'_0(\xi)(u - \hat{A}_n(u))$ and λ'_0 is bounded and strictly positive on $[0, M] \supseteq [x - b, x + b]$, there exists a constant $K > 0$ such that

$$|u - \hat{A}_n(u)| \leq K |\lambda_0(u) - \lambda_0(\hat{A}_n(u))|.$$

If $u \in (\tau_i, \tau_{i+1}]$ and $\hat{A}_n(u) > \tau_i$, then $\tilde{\lambda}_n(u) = \tilde{\lambda}_n(\hat{A}_n(u))$ and we obtain

$$\begin{aligned}
 |u - \hat{A}_n(u)| & \leq K |\lambda_0(u) - \tilde{\lambda}_n(u)| + K |\tilde{\lambda}_n(\hat{A}_n(u)) - \lambda_0(\hat{A}_n(u))| \\
 & \leq 2K |\lambda_0(u) - \tilde{\lambda}_n(u)|.
 \end{aligned} \tag{75}$$

This holds also in the case $\hat{A}_n(u) = \tau_i$, simply because $|\lambda_0(u) - \lambda_0(\hat{A}_n(u))| \leq |\lambda_0(u) - \tilde{\lambda}_n(u)|$. As a result, using lemma 6.5, for the first term on the right hand side of (74), we derive that

$$\mathbb{1}_{E_n} \frac{1}{b^4} \int_{x-b}^{x+b} (\hat{A}_n(u) - u)^2 du \leq \frac{C}{b^4} \mathbb{1}_{E_n} \int_{x-b}^{x+b} (\lambda_0(u) - \tilde{\lambda}_n(u))^2 du = O_P(b^{-3}n^{-2/3}). \tag{76}$$

For the second term on the right hand side of (74), we find

$$\begin{aligned}
 \left| \Phi_n(\hat{A}_n(u); \hat{\beta}_n) - \Phi_n(u; \hat{\beta}_n) \right| & \leq 2 \sup_{x \in \mathbb{R}} \left| \Phi_n(x; \hat{\beta}_n) - \Phi_n(x; \beta_0) \right| + \left| \Phi(\hat{A}_n(u); \beta_0) - \Phi(u; \beta_0) \right| \\
 & \quad + 2 \sup_{x \in \mathbb{R}} |\Phi_n(x; \beta_0) - \Phi(x; \beta_0)| \\
 & \leq 2 |\hat{\beta}_n - \beta_0| \sup_{x \in \mathbb{R}} \left| D_n^{(1)}(x; \beta^*) \right| + |\Phi'(\xi; \beta_0)| |\hat{A}_n(u) - u| \\
 & \quad + 2 \sup_{x \in \mathbb{R}} |\Phi_n(x; \beta_0) - \Phi(x; \beta_0)|,
 \end{aligned}$$

which, using (48), (5) and $|\hat{\beta}_n - \beta_0| = O_p(n^{-1/2})$ (see theorem 3.2 in Tsiatis, 1981), leads to

$$\begin{aligned} & b^{-2} \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\Phi_n(\hat{A}_n(u); \hat{\beta}_n) - \Phi_n(u; \hat{\beta}_n) \right)^2 du \\ & \leq 8b^{-1} \mathbb{1}_{E_n} |\hat{\beta}_n - \beta_0|^2 \sup_{x \in \mathbb{R}} \left| D_n^{(1)}(x; \beta^*) \right|^2 \\ & \quad + 2b^{-2} \mathbb{1}_{E_n} \sup_{s \in [x-b, x+b]} \Phi'(s; \beta_0) \int_{x-b}^{x+b} \left(\hat{A}_n(u) - u \right)^2 du \\ & \quad + 8b^{-1} \sup_{x \in \mathbb{R}} |\Phi_n(x; \beta_0) - \Phi(x; \beta_0)|^2 \\ & = O_p(b^{-1}n^{-1}) + O_p(b^{-1}n^{-2/3}) + O_p(b^{-1}n^{-1}) = O_p(b^{-1}n^{-2/3}). \end{aligned}$$

Consequently, from (74) together with (62), for the first term on the right hand side of (73), we obtain

$$\begin{aligned} \mathbb{1}_{E_n} \left\| \frac{(a_{n,x} \circ \hat{A}_n)(\hat{\Phi}_n \circ \hat{A}_n) - a_{n,x} \hat{\Phi}_n}{\hat{\Phi}_n} \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2}^2 &= O_p(b^{-3}n^{-2/3}) + O_p(b^{-1}n^{-2/3}) \\ &= O_p(b^{-3}n^{-2/3}). \end{aligned}$$

For the second term on the right hand side of (73), we first write

$$\begin{aligned} & \left\| (\Phi_0 \lambda_0 - \hat{\Phi} \tilde{\lambda}_n) \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2} \\ & \leq \left\| (\Phi_0 - \hat{\Phi}) \lambda_0 \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2} + \left\| (\lambda_0 - \tilde{\lambda}_n) \hat{\Phi} \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2} \end{aligned} \tag{77}$$

On the event E_n , we find

$$\begin{aligned} \mathbb{1}_{E_n} \left\| (\Phi_0 - \hat{\Phi}) \lambda_0 \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2}^2 &\leq 2b \mathbb{1}_{E_n} |\hat{\beta}_n - \beta_0|^2 \sup_{x \in \mathbb{R}} \left| D_n^{(1)}(x; \beta^*) \right|^2 \sup_{u \in [0, M]} \lambda_0(u) \\ &= O_p(bn^{-1}), \end{aligned}$$

and

$$\begin{aligned} \mathbb{1}_{E_n} \left\| (\lambda_0 - \tilde{\lambda}_n) \hat{\Phi} \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2}^2 &\leq \Phi(0, \hat{\beta}_n) \mathbb{1}_{E_n} \int_{x-b}^{x+b} \left(\lambda_0(u) - \tilde{\lambda}_n(u) \right)^2 du \\ &= O_p(bn^{-2/3}), \end{aligned}$$

due to lemma 6.5. It follows that

$$\mathbb{1}_{E_n} \left\| (\Phi_0 \lambda_0 - \hat{\Phi} \tilde{\lambda}_n) \mathbb{1}_{[x-b, x+b]} \right\|_{\mathcal{L}_2} = O_p(b^{1/2}n^{-1/3}).$$

Together with (73), this concludes the proof. □

To establish lemma 3.4, we need a slightly stronger version of lemma 6.4. Note that, in order to have the uniform result in (78), we loose a factor $n^{2/9}$ with respect to the bound in lemma 6.4. This might not be optimal, but it is sufficient for our purposes.

Lemma 6.6. *Suppose that (A1)–(A2) hold. Let $0 < \epsilon < M' < M < \tau_H$ and suppose that H^{uc} , defined in (1), has a bounded derivative h^{uc} on $[0, M]$. Let $\tilde{\lambda}_n$ be the Grenander-type estimator of a nondecreasing baseline hazard rate λ_0 , which is differentiable with λ'_0 bounded*

above and below by strictly positive constants. Let E_n be the event from lemma 3.1 and assume that ξ_3 satisfies (65). Then, there exists a constant $C > 0$, such that, for each $n \in \mathbb{N}$,

$$\mathbb{E} \left[n^{4/9} \mathbb{1}_{E_n} \sup_{t \in (\epsilon, M']} \left(\lambda_0(t) - \tilde{\lambda}_n(t) \right)^2 \right] \leq C. \tag{78}$$

Proof. We decompose $(\epsilon, M']$ in m intervals $(c_k, c_{k+1}]$, where $c_k = \epsilon + k(M' - \epsilon)/m$, for $k = 0, 1, \dots, m$, and $m = (M' - \epsilon)n^{2/9}$. Then, we have

$$\sup_{t \in (\epsilon, M']} \left(\lambda_0(t) - \tilde{\lambda}_n(t) \right)^2 = \max_{0 \leq k \leq m-1} \sup_{t \in (c_k, c_{k+1}]} \left(\lambda_0(t) - \tilde{\lambda}_n(t) \right)^2.$$

On the other hand, the fact that λ_0 is differentiable with bounded derivative implies that

$$\begin{aligned} & \sup_{t \in (c_k, c_{k+1}]} \left(\lambda_0(t) - \tilde{\lambda}_n(t) \right)^2 \\ & \leq 2 \sup_{t \in (c_k, c_{k+1}]} \left(\lambda_0(t) - \lambda_0(c_{k+1}) \right)^2 + 2 \sup_{t \in (c_k, c_{k+1}]} \left(\lambda_0(c_{k+1}) - \tilde{\lambda}_n(t) \right)^2 \\ & \leq 2 \left(\sup_{u \in [0, M']} \lambda'_0(u) \right)^2 (c_k - c_{k+1})^2 \\ & \quad + 2 \max \left\{ \left(\lambda_0(c_{k+1}) - \tilde{\lambda}_n(c_k) \right)^2, \left(\lambda_0(c_{k+1}) - \tilde{\lambda}_n(c_{k+1}) \right)^2 \right\} \\ & \leq 2 \left(\sup_{u \in [0, M']} \lambda'_0(u) \right)^2 \frac{(M' - \epsilon)^2}{m^2} \\ & \quad + \max_{0 \leq k \leq m} \left(\lambda_0(c_k) - \tilde{\lambda}_n(c_k) \right)^2 + \max_{0 \leq k \leq m-1} \left(\lambda_0(c_{k+1}) - \lambda_0(c_k) \right)^2. \end{aligned}$$

Here, we used that $\tilde{\lambda}_n$ is nondecreasing, and therefore $\sup_{t \in (c_k, c_{k+1}]} \left(\lambda_0(c_{k+1}) - \tilde{\lambda}_n(t) \right)^2$ is achieved either at $t = c_k$ or $t = c_{k+1}$, for $k = 0, 1, \dots, m - 1$. Hence,

$$\begin{aligned} \sup_{t \in (\epsilon, M']} \left(\lambda_0(t) - \tilde{\lambda}_n(t) \right)^2 & \leq 4 \max_{0 \leq k \leq m} \left(\lambda_0(c_k) - \tilde{\lambda}_n(c_k) \right)^2 + 6 \left(\sup_{u \in [0, M']} \lambda'_0(u) \right)^2 \frac{(M' - \epsilon)^2}{m^2} \\ & \leq 4 \max_{0 \leq k \leq m} \left(\lambda_0(c_k) - \tilde{\lambda}_n(c_k) \right)^2 + C_1 n^{-4/9}, \end{aligned}$$

where $C_1 = 6 \left(\sup_{u \in [\epsilon, M']} \lambda'_0(u) \right)^2$. Consequently, using lemma 6.4, we derive

$$\begin{aligned} \mathbb{E} \left[n^{4/9} \mathbb{1}_{E_n} \sup_{t \in (\epsilon, M']} \left(\lambda_0(t) - \tilde{\lambda}_n(t) \right)^2 \right] & \leq 4 \mathbb{E} \left[n^{4/9} \mathbb{1}_{E_n} \max_{0 \leq k \leq m} \left(\lambda_0(c_k) - \tilde{\lambda}_n(c_k) \right)^2 \right] + C_1 \\ & \leq 4n^{-2/9} \sum_{k=0}^m \mathbb{E} \left[n^{2/3} \mathbb{1}_{E_n} \left(\lambda_0(c_k) - \tilde{\lambda}_n(c_k) \right)^2 \right] + C_1 \\ & \leq 4(M' - \epsilon + 1)C + C_1. \end{aligned}$$

This concludes the proof of (78). □

Proof of Lemma 3.4. Take $0 < \epsilon < x < M' < M < \tau_H$. Let n be sufficiently large such that $x + b \leq M' < M < \tau_H$. Denote by R_n the left hand side of (28). Write $\mathbb{G}_n = \sqrt{n}(\mathbb{P}_n - \mathbb{P})$ and decompose $R_n = R_{n1} + R_{n2}$, where

$$R_{n1} = n^{-1/2} \mathbb{1}_{E_n} \int \frac{\delta \mathbb{1}_{[x-b, x+b]}(u)}{\Phi_n(u; \hat{\beta}_n)} \left(\bar{a}_{n,x} \bar{\Phi}_n(u; \hat{\beta}_n) - a_{n,x}(u) \Phi_n(u; \hat{\beta}_n) \right) d\mathbb{G}_n(u, \delta, z),$$

$$R_{n2} = n^{-1/2} \mathbb{1}_{E_n} \int \mathbb{1}_{\{u > x-b\}} \left[e^{\hat{\beta}'_n z} \int_{x-b}^{u \wedge (x+b)} \frac{\bar{a}_{n,x} \bar{\Phi}_n(v; \hat{\beta}_n)}{\Phi_n(v; \hat{\beta}_n)} d\bar{\Lambda}_n(v) - e^{\beta'_0 z} \int_{x-b}^{u \wedge (x+b)} a_{n,x}(v) d\Lambda_0(v) \right] d\mathbb{G}_n(u, \delta, z).$$

Choose $\eta > 0$. We prove separately that there exists $\nu > 0$, such that

$$\limsup_{n \rightarrow \infty} \mathbb{P} \left(b^{3/2} n^{13/18} |R_{n1}| > \nu \right) \leq \eta$$

$$\limsup_{n \rightarrow \infty} \mathbb{P} \left(n^{1/2} |R_{n2}| > \nu \right) \leq \eta. \tag{79}$$

We consider the following events.

$$\mathcal{A}_{n1} = \left\{ \tilde{\lambda}_n(M) > K_1 \right\},$$

$$\mathcal{A}_{n2} = \left\{ \sup_{t \in [\epsilon, M']} \left| \lambda_0(t) - \tilde{\lambda}_n(t) \right| > K_2 n^{-2/9} \right\}, \tag{80}$$

where $K_1, K_2 > 0$, and let $\mathcal{A}_n = \mathcal{A}_{n1} \cup \mathcal{A}_{n2}$. Because $\tilde{\lambda}_n(M) = O_p(1)$, we can choose $K_1 > 0$, such that $\mathbb{P}(\mathcal{A}_{n1}) \leq \eta/3$, and from lemma 6.6, we find that we can choose $K_2 > 0$, such that $\mathbb{P}(\mathcal{A}_{n2}) \leq \eta/3$, so that $\mathbb{P}(\mathcal{A}_n) \leq 2\eta/3$. First, consider R_{n1} . Because

$$\mathbb{P} \left(b^{3/2} n^{13/18} |R_{n1}| > \nu \right) \leq \mathbb{P}(\mathcal{A}_n) + \mathbb{P} \left(\left\{ b^{3/2} n^{13/18} |R_{n1}| > \nu \right\} \cap \mathcal{A}_n^c \right) \leq 2\eta/3 + b^{3/2} n^{13/18} \nu^{-1} \mathbb{E} \left[|R_{n1}| \mathbb{1}_{\mathcal{A}_n^c} \right]. \tag{81}$$

It suffices to show that there exists $\nu > 0$, such that $b^{3/2} n^{13/18} \nu^{-1} \mathbb{E} \left[|R_{n1}| \mathbb{1}_{\mathcal{A}_n^c} \right] \leq \eta/3$, for all n sufficiently large. Write

$$w(u) = \frac{1}{\Phi_n(u; \hat{\beta}_n)} \left(a_{n,x}(\hat{A}_n(u)) \Phi_n(\hat{A}_n(u); \hat{\beta}_n) - a_{n,x}(u) \Phi_n(u; \hat{\beta}_n) \right) = \frac{a_{n,x}(\hat{A}_n(u))}{\Phi_n(u; \hat{\beta}_n)} \left(\Phi_n(\hat{A}_n(u); \hat{\beta}_n) - \Phi(\hat{A}_n(u); \beta_0) \right) + \frac{a_{n,x}(u)}{\Phi_n(u; \hat{\beta}_n)} \left(\Phi(u; \beta_0) - \Phi_n(u; \hat{\beta}_n) \right) + \frac{1}{\Phi_n(u; \hat{\beta}_n)} \left(a_{n,x}(\hat{A}_n(u)) \Phi(\hat{A}_n(u); \beta_0) - a_{n,x}(u) \Phi(u; \beta_0) \right).$$

We will argue that the function $W_n = b^2 n^{2/9} w$ is uniformly bounded and of bounded variation. Because of (61), $n^{1/3}(\Phi_n(\hat{A}_n(u); \hat{\beta}_n) - \Phi(\hat{A}_n(u); \beta_0))$ and $n^{1/3}(\Phi(u; \beta_0) - \Phi_n(u; \hat{\beta}_n))$ are uniformly bounded. Moreover, they are of bounded variation, as being the difference of two monotone functions. Similarly, $1/\Phi_n(u; \hat{\beta}_n)$ is of bounded variation and on the event E_n it is also uniformly bounded. Furthermore, by the definition of $a_{n,x}$, we have

$$a_{n,x}(\hat{A}_n(u)) \Phi(\hat{A}_n(u); \beta_0) - a_{n,x}(u) \Phi(u; \beta_0) = k_b \left(x - \hat{A}_n(u) \right) - k_b(x - u).$$

This is a function of bounded variation, such that multiplied by $b^2n^{2/9}$, it is uniformly bounded on the event \mathcal{A}_n^c , because using (75), we obtain

$$\begin{aligned} |k_b(x - \hat{A}_n(u)) - k_b(x - u)| &\leq b^{-2}|\hat{A}_n(u) - u| \sup_{x \in [-1, 1]} |k'(x)| \\ &\leq 2Kb^{-2}|\tilde{\lambda}_n(u) - \lambda_0(u)| \sup_{x \in [-1, 1]} |k'(x)| \\ &\leq b^{-2}n^{-2/9}2KK_2 \sup_{x \in [-1, 1]} |k'(x)|. \end{aligned} \tag{82}$$

Finally, $ba_{n,x}(u) = bk_b(x - u)/\Phi(u; \beta_0)$ is also a function of bounded variation, as being the product of a function of bounded variation $bk_b(x - u)$ with the monotone function $1/\Phi(u; \beta_0)$, and it is uniformly bounded. Then, because $ba_{n,x}(\hat{A}_n(u))$ is the composition of an increasing function with a function of bounded variation that is uniformly bounded, it is also a function of bounded variation and uniformly bounded. As a result, being the sum and product of functions of bounded variation that are uniformly bounded, $W_n = b^2n^{2/9}w$ belongs to the class $\mathcal{B}_{\tilde{K}}$ of functions of bounded variation, uniformly bounded by some constant \tilde{K} . Consequently, it holds

$$\begin{aligned} R_{n1} &= n^{-1/2}\mathbb{1}_{E_n} \int \delta\mathbb{1}_{[x-b, x+b]}(u)w(u) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \\ &= b^{-2}n^{-13/18}\mathbb{1}_{E_n} \int \delta\mathbb{1}_{[x-b, x+b]}(u)W_n(u) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z). \end{aligned}$$

Let $\mathcal{B}_{\tilde{K}}$ be the class of functions of bounded variation on $[0, M]$, that are uniformly bounded by $\tilde{K} > 0$, and let $\mathcal{G}_n = \{\zeta_{B,n} : B \in \mathcal{B}_{\tilde{K}}\}$, where $\zeta_{B,n}(u, \delta) = \delta\mathbb{1}_{[x-b, x+b]}(u)B(u)$. Then, $\delta\mathbb{1}_{[x-b, x+b]}W_n$ is a member of the class \mathcal{G}_n , which has envelope $F_n(u, \delta) = \tilde{K}\delta\mathbb{1}_{[x-b, x+b]}(u)$. Furthermore, if $J(\delta, \mathcal{G}_n)$ is the corresponding entropy-integral (see Section 2.14 in van der Vaart & Wellner, 1996), then according to lemma A.1 in Supporting Information, $J(\delta, \mathcal{G}_n) \leq \int_0^\delta \sqrt{1 + C/\epsilon} d\epsilon$, for some $C > 0$. Consequently, together with theorem 2.14.1 in van der Vaart & Wellner (1996), we obtain that

$$\begin{aligned} \mathbb{E}[|R_{n1}| \mathbb{1}_{\mathcal{A}_n^c}] &\leq b^{-2}n^{-13/18}\mathbb{E} \sup_{\zeta \in \mathcal{G}_n} \left| \int \zeta_{B,n}(u, \delta, z) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \right| \\ &\leq KJ(1, \mathcal{G}_n) \|F_n\|_{L_2(\mathbb{P})} b^{-2}n^{-13/18} \\ &\leq K'(H^{uc}(x + b) - H^{uc}(x - b))^{1/2} b^{-2}n^{-13/18} \leq K''b^{-3/2}n^{-13/18}, \end{aligned}$$

because H^{uc} is absolutely continuous. As a result,

$$b^{3/2}n^{13/18}\nu^{-1}\mathbb{E}[|R_{n1}| \mathbb{1}_{\mathcal{A}_n^c}] \leq \frac{K''}{\nu} \leq \eta/3$$

for sufficiently large ν . This proves the first part of (79).

We proceed with R_{n2} . Similar to (81),

$$\mathbb{P}\left(n^{1/2}|R_{n2}| > \nu\right) \leq 2\eta/3 + n^{1/2}\nu^{-1}\mathbb{E}[|R_{n2}| \mathbb{1}_{\mathcal{A}_n^c}], \tag{83}$$

and it suffices to show that there exists $\nu > 0$, such that $n^{1/2}\nu^{-1}\mathbb{E}[|R_{n2}| \mathbb{1}_{\mathcal{A}_n^c}] \leq \eta/3$, for all n sufficiently large. We write

$$n^{1/2}R_{n2} = \mathbb{1}_{E_n} \int \left(e^{\beta'_n z} r_{1,n}(u) - e^{\beta'_0 z} r_{2,n}(u) \right) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z),$$

where

$$r_{1,n}(u) = \mathbb{1}_{\{u > x-b\}} \int_{x-b}^{u \wedge (x+b)} \frac{a_{n,x}(\hat{A}_n(v))}{\Phi_n(v; \hat{\beta}_n)} \Phi_n(\hat{A}_n(v); \hat{\beta}_n) \tilde{\lambda}_n(v) dv,$$

$$r_{2,n}(u) = \mathbb{1}_{\{u > x-b\}} \int_{x-b}^{u \wedge (x+b)} a_{n,x}(v) \lambda_0(v) dv,$$

are both monotone functions, uniformly bounded by some constant C on the event $\mathcal{A}_n^c \cap E_n$. Let \mathcal{M}_C be the class of monotone functions bounded uniformly by $C > 0$, and let $\mathcal{G}_n = \{\zeta_{r,\beta}(u, z) : r \in \mathcal{M}_C, \beta \in \mathbb{R}^P, |\beta - \beta_0| \leq \xi_2\}$, where ξ_2 is chosen as in (49) and $\zeta_{r,\beta}(u, z) = r(u)e^{\beta'z}$. Then $e^{\hat{\beta}'_n z} r_{1,n}(u)$ is a member of the class \mathcal{G}_n , which has envelope

$$F_n(u, z) = C \exp \left\{ \sum_{j=1}^p (\beta_{0,j} - \sigma_n) z_j \vee (\beta_{0,j} + \sigma_n) z_j \right\},$$

with $\sigma_n = \sqrt{\xi_2 n^{-2/3}}$ as the envelope of \mathcal{G}_n . If $J_{[\cdot]}(\delta, \mathcal{G}_n, L_2(\mathbb{P}))$ is the bracketing integral (see Section 2.14 in van der Vaart & Wellner, 1996), then according to lemma A.2 in Supporting Information, $J_{[\cdot]}(\delta, \mathcal{G}_n, L_2(\mathbb{P})) \leq \int_0^\delta \sqrt{1 + C/\epsilon} d\epsilon$, for some $C > 0$. Hence, together with theorem 2.14.2 in van der Vaart & Wellner (1996), we obtain

$$\begin{aligned} & \mathbb{E} \left[\left| \mathbb{1}_{\mathcal{A}_n^c \cap E_n} \int e^{\hat{\beta}'_n z} r_{1,n}(u) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \right| \right] \\ & \leq \mathbb{E} \sup_{\zeta \in \mathcal{G}_n} \left| \int \zeta_{r,\beta}(u, z) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \right| \\ & \leq K J_{[\cdot]}(1, \mathcal{G}_n, L_2(\mathbb{P})) \|F_n\|_{L_2(\mathbb{P})} \leq K', \end{aligned}$$

for some $K' > 0$. We conclude that,

$$v^{-1} \mathbb{E} \left[\left| \mathbb{1}_{\mathcal{A}_n^c \cap E_n} \int e^{\hat{\beta}'_n z} r_{1,n}(u) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \right| \right] \leq \frac{K'}{v} \leq \eta/6,$$

for sufficiently large v . In the same way, it can also be proved

$$v^{-1} \mathbb{E} \left[\left| \mathbb{1}_{\mathcal{A}_n^c \cap E_n} \int e^{\beta_0' z} r_{2,n}(u) d\sqrt{n}(\mathbb{P}_n - \mathbb{P})(u, \delta, z) \right| \right] \leq \frac{K}{v} \leq \eta/6$$

for sufficiently large v , concluding the proof of (83) and therefore the second part of (79). \square

Supporting Information

Supplement to ‘‘Smoothed isotonic estimators of a monotone baseline hazard in the Cox model’’.

- Supplement A: Entropy bounds for the smoothed Grenander-type estimator.
- Supplement B: Smooth maximum likelihood estimator.
- Supplement C: Consistency of the bootstrap.

References

- Burr, D. (1994). A comparison of certain bootstrap confidence intervals in the Cox model. *J. Amer. Statist. Assoc.* **89**, 1290–1302.
- Cheng, M.-Y., Hall, P. & Tu, D. (2006). Confidence bands for hazard rates under random censorship. *Biometrika* **93**, 357–366.
- Chung, D. & Chang, M. N. (1994). An isotonic estimator of the baseline hazard function in Cox's regression model under order restriction. *Statist. Probab. Lett.* **21**, 223–228.
- Cox, D. R. (1972). Regression models and life-tables. *J. Roy. Statist. Soc. Ser. B* **34**, 187–220.
- Cox, D. R. (1975). Partial likelihood. *Biometrika* **62**, 269–276.
- Cox, D. R. & Oakes, D. (1984). *Analysis of survival data*, Chapman & Hall, London.
- Durot, C. (2007). On the L_p -error of monotonicity constrained estimators. *Ann. Stat.* **35**, 1080–1104.
- Durot, C., Groeneboom, P. & Lopuhaä, H. P. (2013). Testing equality of functions under monotonicity constraints. *J. Nonparametr. Stat.* **25**, 939–970.
- Durot, C., Kulikov, V. N. & Lopuhaä, H. P. (2012). The limit distribution of the L_∞ -error of Grenander-type estimators. *Ann. Stat.* **40**, 1578–1608.
- Durot, C. & Lopuhaä, H. P. (2014). A Kiefer-Wolfowitz type of result in a general setting, with an application to smooth monotone estimation. *Electron. J. Stat.* **8**, 2479–2513.
- Efron, B. (1977). The efficiency of Cox's likelihood function for censored data. *J. Amer. Statist. Assoc.* **72**, 557–565.
- Eggermont, P. P. B. & LaRiccia, V. N. (2000). Maximum likelihood estimation of smooth monotone and unimodal densities. *Ann. Stat.* **28**, 922–947.
- Gill, R. D. (1984). Understanding Cox's regression model: A martingale approach. *J. Amer. Statist. Assoc.* **79**, 441–447.
- González-Manteiga, W., Cao, R. & Marron, J. S. (1996). Bootstrap selection of the smoothing parameter in nonparametric hazard rate estimation. *J. Amer. Statist. Assoc.* **91**, 1130–1140.
- Groeneboom, P., Jongbloed, G. & Witte, B. I. (2010). Maximum smoothed likelihood estimation and smoothed maximum likelihood estimation in the current status model. *Ann. Stat.* **38**, 352–387.
- Groeneboom, P. & Jongbloed, G. (2013). Smooth and non-smooth estimates of a monotone hazard. In *From probability to statistics and back: High-dimensional models and processes*. Institute of Mathematical Statistics.
- Groeneboom, P. & Jongbloed, G. (2014). *Nonparametric estimation under shape constraints*, Cambridge University Press, New York.
- Groeneboom, P. & Jongbloed, G. (2015). Nonparametric confidence intervals for monotone functions. *Ann. Statist.* **43**, 2019–2054.
- Groeneboom, P. & Wellner, J. A. (1992). *Information bounds and nonparametric maximum likelihood estimation*, Birkhäuser Verlag, Basel.
- Hall, P. (1992). Effect of bias estimation on coverage accuracy of bootstrap confidence intervals for a probability density. *Ann. Stat.* **20**, 675–694.
- Kalbfleisch, J. D. & Prentice, R. L. (2002). *The statistical analysis of failure time data*, (2nd edn.), Wiley-Interscience, Hoboken, NJ.
- Lopuhaä, H. P. & Musta, E. (2017a). Isotonized smooth estimators of a monotone baseline hazard in the Cox model. *J. Statist. Plann. Inference* **191**, 43–67.
- Lopuhaä, H. P. & Musta, E. (2017b). Smooth estimation of a monotone hazard and a monotone density under random censoring. *Stat. Neerl.* **71**, 58–82.
- Lopuhaä, H. P. & Nane, G. F. (2013). Shape constrained non-parametric estimators of the baseline distribution in Cox proportional hazards model. *Scand. J. Stat.* **40**, 619–646.
- Mammen, E. (1991). Estimating a smooth monotone regression function. *Ann. Stat.* **19**, 724–740.
- Mukerjee, H. (1988). Monotone nonparametric regression. *Ann. Stat.* **16**, 741–750.
- Müller, H.-G. & Wang, J.-L. (1990). Locally adaptive hazard smoothing. *Probab. Theory Relat. Fields* **85**, 523–538.
- Nane, G. F. (2013). *Shape constrained nonparametric estimation in the Cox model*, Delft University of Technology, Delft.
- Ramsay, J. O. (1998). Estimating smooth monotone functions. *J. R. Stat. Soc. Ser. B Stat. Methodol.* **60**, 365–375.
- Ren, J.-J. & Zhou, M. (2011). Full likelihood inferences in the Cox model: An empirical likelihood approach. *Ann. Inst. Statist. Math.* **63**, 1005–1018.
- Shorack, G. R. & Wellner, J. A. (1986). *Empirical processes with applications to statistics*, Wiley, New York.
- Tsiatis, A. A. (1981). A large sample study of Cox's regression model. *Ann. Stat.* **9**, 93–108.

- van der Vaart, A. W. & van der Laan, M. J. (2003). Smooth estimation of a monotone density. *Statistics* **37**, 189–203.
- van der Vaart, A. W. & Wellner, J. A. (1996). *Weak convergence and empirical processes*, Springer-Verlag, New York.
- van Geloven, N., Martin, I., Damman, P., de Winter, R. J., Tijssen, J. G. & Lopuhaä, H. P. (2013). Estimation of a decreasing hazard of patients with acute coronary syndrome. *Stat. Med.* **32**, 1223–1238.
- Xu, G., Sen, B. & Ying, Z. (2014). Bootstrapping a change-point Cox model for survival data. *Electron. J. Stat.* **8**, 1345–1379.
- Zhang, S. & Karunamuni, R. J. (1998). On kernel density estimation near endpoints. *J. Stat. Plann. Inference* **70**, 301–316.

Received January 2017, in final form December 2017

Eni Musta, Delft Institute of Applied Mathematics, Delft University of Technology, van Mourik Broekmanweg 6, 2628 XE Delft, Netherlands.
E-mail: e.musta@tudelft.nl, h.p.lopuhaa@tudelft.nl