

**Dynamic Adaptive Policymaking for the Sustainable City
The Case of Autonomous Taxis**

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Dynamic Adaptive Policymaking for the Sustainable City:

The Case of Autonomous Taxis

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Overview

- **Urban transport problems and a (potential) solution**
- **What are adaptive policies?**
- **An illustration of an adaptive policy: Implementation of 'autonomous taxis' (ATs)**

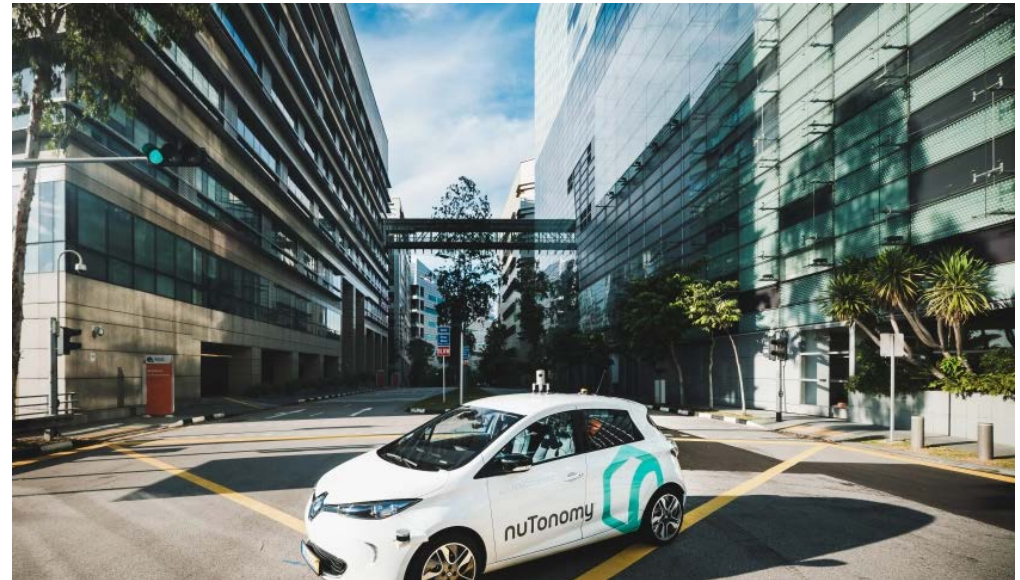
Urban Transport Problems and a (Potential) Solution

- **Problems:**
 - Growing externalities of road traffic (congestion, fatalities, consumption of scarce space, use of energy, emissions)
 - Inefficient use of user-owned vehicles; driver error (human error is the cause of over 90% of all vehicle crashes)
- **Potential solution:**
 - Self-driving vehicles combined with real-time ridesharing
 - Using autonomous vehicle technology, GPS to guide the vehicle, and smartphones for travelers to request and pay for rides
 - i.e. 'autonomous taxis' (AT)



Benefits of ATs

- **Economic benefits:**
 - reduction in traffic accidents
 - reduction in traffic congestion
 - savings in parking costs and land use
- **Environmental benefits:**
 - reductions in emissions and fuel consumption
- **Social benefits:**
 - travel time reductions
 - savings in the cost of vehicles, fuel, insurance, and parking (land use)
 - more comfortable and more convenient traveling



Self-Driving Taxis Hit the Streets of Singapore (Fortune, August 25, 2016)

Status of AT-Implementation

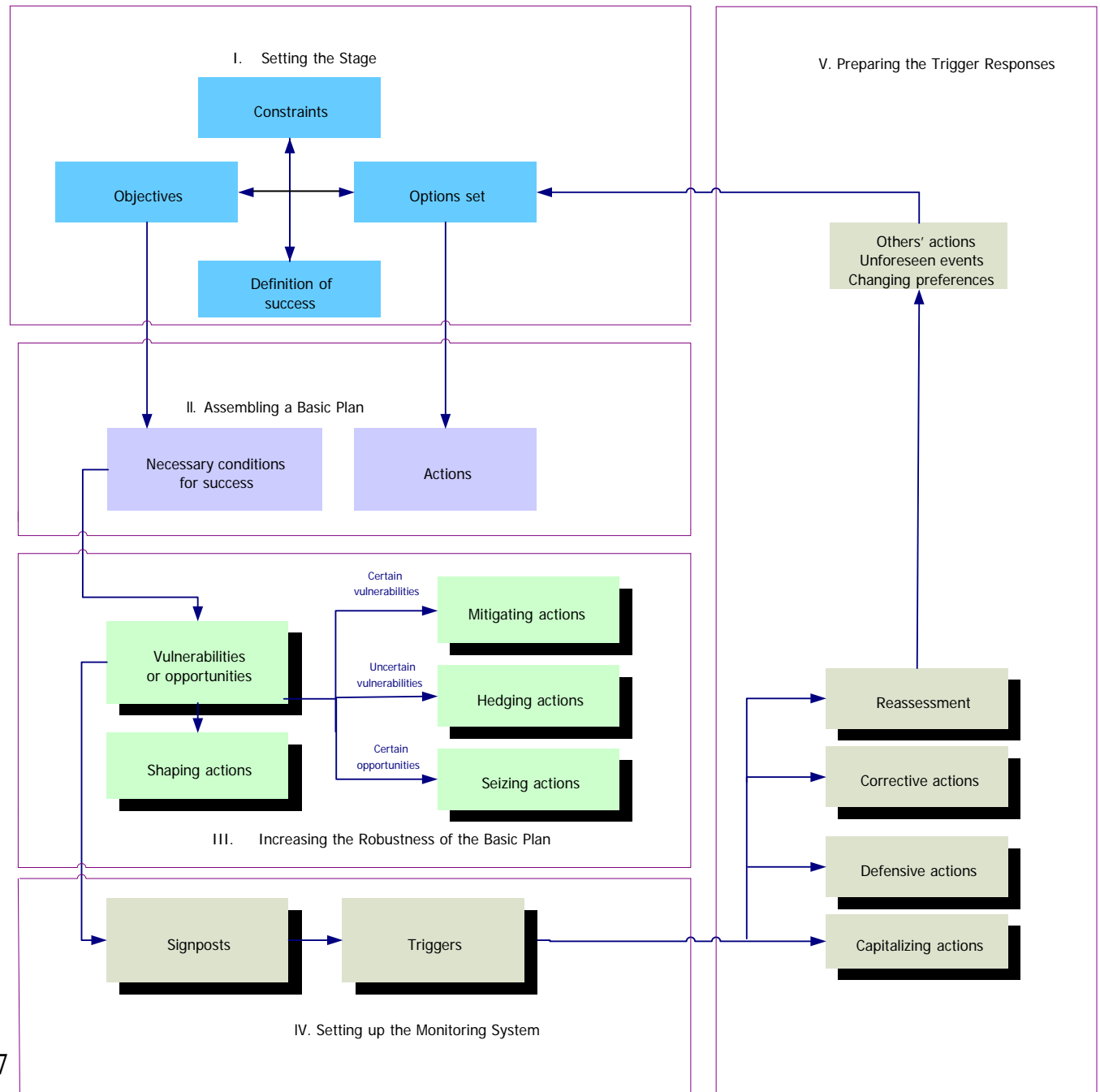
- **Transport policymakers, automakers, shared driving organizations increasingly interested in ATs**
- **AT implementation delayed by a variety of ‘deep uncertainties’ (e.g. technological performance, public acceptance, legal regulations)**
- **Current policymaking:**
 - ‘wait and see’ attitude
 - let AT-implementation be determined by market forces
 - this could slow down the development of ATs and fail to advance general transport policy goals
- **Need for AT-policy course to cope with these uncertainties and get implementation underway**

A New Policymaking Paradigm: Adaptive Policies

- **In this unpredictable, rapidly changing world, it is almost impossible to identify static robust policies**
 - Key assumptions underlying a policy may fail to occur
 - Opportunities may arise that should be seized upon
- **Over time, we gain information that resolves current scenario uncertainties**
 - Industry trends
 - Political and economic developments
 - New technologies
- **In fact, the only way to reduce these uncertainties is to learn by monitoring the system over time**
- **Thus, the best policies will be adaptive**
 - Take those actions now that cannot be deferred (or have ‘no regret’)
 - Prepare to take actions that may become beneficial
 - Monitor changes in the world, and take actions when needed

Designing an Adaptive Plan

[Based on W.E. Walker, S.A. Rahman, J. Cave (2001). "Adaptive policies, policy analysis, and policymaking", *European Journal of Operational Research* 128 : 282-289]



Handling AT-Uncertainties: The Adaptive Approach

- I. Set the stage (objectives, options, constraints)**
- II. Assemble a basic policy and conditions for success**
- III. Increase the robustness of the basic policy**
- IV. Set up a monitoring system**
- V. Prepare trigger responses**

Step I: Setting the Stage

Identify objectives, available policy options, constraints, conditions for success

- **Objectives: make better use of scarce space, reduce congestion improve road traffic safety, improve the environment**
- **Urban transport policy options**
 - **Traditional measures: parking policies, improve public transport, urban road traffic management, spatial policies, etc.**
 - **Innovative measures: active driver support measures, car sharing (such as ATs)**
- **Constraints: costs, public acceptance, safety, etc.**
- **Definition of success: specification of desirable outcomes (specific levels of policy outcomes related to the objectives)**

Step II: Assembling a Basic AT-Policy

- **Specify a promising basic AT-policy**
 - **Implement an Uber-like system in the city**
 - **With ‘conditional’ automated vehicles (driving task automated, but human (taxi-)driver would respond if requested to resume control)**
- **Identify conditions for the success of the basic AT-policy:**
 1. **support by regional/national government and other stakeholders**
 2. **acceptance by taxi drivers, operators, and travelers**
 3. **demand for taxis develops as originally forecast**
 4. **travel supply by other modes develops as originally forecast**
 5. **AT technology performs well**
 6. **ATs perform well in relation to general urban transport goals**

Steps III and IV: Identifying Vulnerabilities of Basic Policy, and Adaptive Responses

- **Vulnerability (uncertain): Travel demand for ATs decreases**
 - (H) Develop plans to expand the AT services to e.g. underserved specific groups/travelers within the urban region and/or to a larger region
 - Specify/monitor lower threshold for travel demand, to trigger expansion plan implementation
- **Opportunity (uncertain): Travel demand for ATs increases**
 - (SZ) Develop plans for expanding the AT-fleet above those planned for in the basic plan
 - Specify/monitor higher threshold for travel demand, to trigger AT-fleet expansion
- **Vulnerability (certain): Opposition by taxi drivers, operators, and travelers**
 - (M) Educate taxi drivers on the benefits of automated driving; subsidize AT-fleet development for the operators; provide campaigns and demos on the benefits of AT-use; assure travelers on the privacy of their information
 - Specify monitor for opposition per group and prepare education campaigns, privacy protection improvements, job training (for displaced taxi drivers)
- **Vulnerability (uncertain): Technology failure**
 - (H) Provide insurance in case of large failure; Establish an AT Safety Board
 - Specify/monitor for technology failures to trigger AT Safety Board investigations

Step V: Implementing the AT- Policy

- **Basic AT-policy, vulnerabilities, and adaptive responses are agreed upon**
- **Basic policy is implemented**
- **Events unfold and signpost information is collected**
- **When a trigger event occurs, adapt the basic policy**
 - **If original objectives/constraints remain in place, take defensive/corrective actions**
 - **Expand AT-fleet in case of too high taxi demand**
 - **Upgrade AT-fleet to full automation in case of technological breakthrough**
 - **Make AT mode part of other upcoming transport modes (e.g. MaaS)**
 - **If event causes re-thinking of objectives/constraints, perform reassessment**
 - **E.g., malfunctioning technology resulted in large accident**
 - **Reassess entire policy; new policy learns from previous experiences**

Conclusions

- **Paradox of policymaking with respect to AT**
 - **Great potential to contribute to urban transport policy goals**
 - **Paralysis in implementation due to large uncertainties related to AT outcomes, their valuation, and other developments**
- **Challenge: To develop innovative approaches for moving forward while handling these uncertainties**
- **Adaptive policies**
 - **Get implementation under way**
 - **Allow adaptations of policy over time as knowledge about AT proceeds and critical events in AT implementation take place, values change, and other external events take place**
 - **Enable learning from experience over time**

Thank You

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