Which Cloud Auto-Scaler Should I Use for my Application?: Benchmarking Auto-Scaling Algorithms
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Rapid elasticity is one of the essential characteristics of cloud computing identified by NIST [17]. Elasticity allows resources to be provisioned and released to scale rapidly out and in ward according to demand. Tens – if not hundreds – of algorithms have been proposed in the literature to automatically achieve elastic provisioning [15, 23, 14, 21, 13, 20, 6, 12, 16, 10]. These algorithms are typically referred to as elasticity algorithms, dynamic provisioning techniques or autoscalers.

While trying to solve the same problem, sometimes with differing assumption, many of these algorithms are either compared to static provisioning or to a predefined QoS target, e.g., predefined response time target, with very little – or no – comparison to previously published work. This reduces the ability of an application owner or a cloud operator to choose and deploy a suitable algorithm from the literature. Many of these algorithms have been tested with one single – real or synthetic – workload in a specific use-case [13, 14, 10]. While all published algorithms are shown to work in the specific use-case they were designed for with the, typically short, workloads tested with, it is seldom the case that the real scenarios will be anything close to the test cases for which the algorithms are shown to work. Bursts occur in workloads occasionally. Workload dynamics change over time and the load-mix of an application significantly affects how provisioning should be done [21].

This work aims to validate and better understand the literature on automated rapid elasticity algorithms under different conditions. We compare 10 auto-scalers from the state-of-the-art, namely, [23, 7, 14, 6, 5, 12, 18, 4, 13, 11, 10, 8]. We obtained the code for five of the auto-scalers from their designers and reimplemented five.

Since cloud applications are heterogeneous in nature with different resource requirements and workload characteristics [19], for this study, we choose a set of representative applications. Each of these applications stress different resources. The set of applications chosen include complex webservices, scientific workflows, big data processing, simple web services, and video streaming. Due to lack of space, we describe only two applications in more details.

1. Scientific applications and workflows. Currently, workflows are widely used to drive complex computations. A workflow (WF) or a Directed Acyclic Graph (DAG) consists of a set of tasks (nodes) which have precedence constraints among them. Any task can start the execution when all of its input dependencies are satisfied. The whole workflow in our setup is considered as a job. The popularity of workflows brings the diversity of their structures, sizes, and resource requirements. For our experiments we use three well known scientific workflows, namely, Montage, LIGO, and SIPHT. Additionally, we consider two generic workflow structures: a star (bag-of-tasks) and a chain. To schedule and execute workflows we use the KOALA scheduler [9] and OpenNebula private cloud which are deployed on the DAS-4 infrastructure. The execution environment for workflow tasks consist of a single head VM and multiple worker VMs.

2. Complex Web-Services. Wikipedia, the free online encyclopedia, is one of the top 10 accessed websites on the Internet [2]. The Wikimedia foundation has open sourced MediaWiki software, a load-balancer and a MySQL database.

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We benchmark the performance of the selected auto-scalers with the chosen applications and quantify the performance based on the following set of metrics.

1. Average Overprovisioning ($\overline{OP}$) is the average number of overprovisioned VMs by the autoscaler per unit time. It is calculated by summing the number of overprovisioned VMs over time ($OP$) and dividing the number by the total time for which the autoscaler was running. A machine is considered overprovisioned if it is of no use for the next 10 minutes. This time window reduces the penalty if an algorithm predicts the future workload well in advance.

2. Average Underprovisioning ($\overline{UP}$) is the average number of underprovisioned VMs by the autoscaler per unit time. It is calculated by summing the number of underprovisioned VMs over time ($UP$) and dividing the number by the total time for which the autoscaler was running. Underprovisioning means that the autoscaler failed to provision the resources required to serve all requests on time.

3. Average number of Oscillations ($\overline{O}$) which is the average number of VMs started or shut-down ($O$) per unit time. The reason to consider ($\overline{O}$) as an important parameter is the cost of starting/stopping a VM. From our experience, starting a machine (physical or virtual) takes from one minute up to several minutes depending on the application running (almost 20 minutes for an ERP application server). This time does not include the time required to transfer the images and any data needed but is rather the time for (virtual) machine boot, network setup and application initiation. Similar time may be required when a machine is shutdown for workload migration and load balancer reconfiguration.

4. Maximum, minimum and, average time required for computing the prediction ($T$). When possible, we also report the computational complexity of each algorithm. These values do not change significantly for the same algorithm with respect to the application managed. We thus report these values for all our experiments and comment on any anomalies in the measured times between experiments.

In addition to these general metrics, we look at application specific metrics for the applications such as response time, throughput and request drop rate for the web services, queue length for the scientific workflows and the big data workload, and jitter in the video streaming workload. The aim of our work is to provide researchers and industries with a better understanding of the current state-of-the-art.²

1. REFERENCES


