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A Linear Array of Skewed Dipoles with Asymmetric Radiation Pattern for Angular Filtering

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Abstract—We present a design of a linear array of tilted dipoles to achieve radiation patterns with asymmetric angular filtering characteristics. To realize the asymmetric radiation, the dipole elements are spaced by a distance larger than half a wavelength, thus allowing for grating lobes to occur in the visible region. Moreover, the dipoles are loaded with artificial dielectrics to increase the front-to-back ratio and consequently to enable higher gain in certain desired angular regions. Based on the design, a linear array with 10 elements is manufactured and tested. The measured results show the ability of such an array to achieve stable gain from broadside up to 90 degrees scanning, while implementing a stop-band angular filter for negative scanning angles.

Index Terms—Angular filtering, antenna arrays, pattern asymmetry, tilted dipole array.

I. INTRODUCTION

Modern antenna arrays for radar and communication applications often operate in environments where a multitude of sensors and radiating systems need to co-exist. To avoid interference between different antenna systems, the implementation of angular filtering functions can be beneficial. Moreover, in some of the mentioned applications, it is sometimes not required for the antennas to exhibit a field of view that is symmetric with respect to broadside, but rather a gain profile that is stable over a certain desired angular region. For instance, to improve the system capacity of base-stations antennas, a down-tilt of the radiation towards the ground was employed to increase the signal reception from the mobile device [1], [2]. In satellite communications, tilting the embedded pattern of the individual elements of an antenna array was implemented to achieve a gain enhancement for large scan angles within a limited azimuth region [3], [4]. The entire field of view was then covered by mechanical rotation of the array along its axis.

Angular filters have been realized mainly with frequency selective surfaces or leaky wave structures [5]–[7], with the aim of increasing the directivity and reducing the levels of the side lobes or grating lobes. In [8], [9], rectilinear leaky-wave antennas were synthesized to realized radiation patterns with angular selectivity and asymmetry properties. However, with this concept, the entire array radiates a broad beam with an angular passband filtering function, precluding the possibility to generate highly directive beams that can be scanned within the field of view of interest.

In this work, the proposed approach is to realize an antenna array where the single element exhibits a radiation pattern with angular selectivity, asymmetric with respect to broadside. The resulting active element pattern will filter the array factor of the entire array while scanning, providing high gain only in the desired field of view. Recently in [10] we showed that one effective way to achieve asymmetric active element patterns is by enhancing the directivity of the element (e.g., with a dipole loaded by a parasitic strip as director) and by rotating the array element around their center, as shown in Fig. 1. In [10], the fundamental radiation properties of arrays of stacked dipoles were investigated, based on a spectral method of moments (MoM) analysis. The results are consistent with the general theory of arrays with asymmetric elements given in [11], [12]. Based on the findings provided in [10], we propose here the design of a linear array of tilted dipole elements to achieve asymmetric radiation characteristics. The dipoles are loaded with artificial dielectrics to increase the gain in certain desired angular regions. An implementation of the array based on printed circuit technology (PCB) is proposed, as well as the design of the feed structure. To validate the design, a prototype linear array with 10 elements is manufactured and tested and the measured results are reported.

II. UNIT CELL DESIGN

In [10], the guidelines to design an array with asymmetric radiation properties were discussed. The main unit cell under
The gain is the same plane the dipole. This element is also printed on the metal in Fig. 3(a). Loaded with 3 layers of artificial dielectric (AD) is proposed for the bandwidth, a solution consisting of a tilted dipole element. The simulated E-plane pattern of a single element in free space is reported in Fig. 2(c) depicting the simulated reflection coefficient at 12 GHz, exhibiting a front-to-back ratio of 12 dB. Figure 2(b) shows the simulated reflection coefficient of the single element, based on PCB technology.

A. Single Dipole Element with Parasitic Loading

To enable a simple realization of the flat strip dipole element, we consider an equivalent isolated element where the active dipole and the parasitic strip are printed on a vertically oriented thin dielectric slab. Figure 2(a) shows the considered structure with the characteristic geometrical parameters. The dimensions of the elements are chosen as: \( l = 0.41\lambda_0 \), \( t_p = 0.37\lambda_0 \), \( w = 0.05\lambda_0 \), \( \delta = 0.01\lambda_0 \) and \( d_z = 0.7\lambda_0 \), where \( \lambda_0 \) is the wavelength at 12 GHz. The dielectric slab selected for the design is Rogers RO4530 TM with relative dielectric constant \( \varepsilon_r = 3.66 \) and thickness \( t = 101\mu m \). The dimensions are optimized so that the directivity of the element is maximized. The simulated E-plane pattern of a single element in free space is reported in Fig. 2(b), at 12 GHz, exhibiting a front-to-back ratio of 12 dB. Figure 2(c) depicts the simulated reflection coefficient of the element, showing a rather narrow bandwidth of only 2% centered at 12 GHz, normalized to a low impedance of 10 Ω.

To enhance the front-to-back ratio of the element as well as the bandwidth, a solution consisting of a tilted dipole element loaded with 3 layers of artificial dielectric (AD) is proposed in Fig. 3(a). The AD consists of sub-wavelength metal strips on the same plane of the dipole. This element is also printed on a vertical PCB with a dielectric with the same relative permittivity and thickness as for the stacked dipole solution (\( \varepsilon_r = 3.66 \), \( t = 101\mu m \)). The dimensions, reported in Table I, were tuned to enhance the directivity of the element. The single element E-plane pattern at 12 GHz and the reflection coefficient are shown in Fig. 3(b) and (c), respectively. The dipole loaded with artificial dielectric has a back lobe with −20 dB level and a bandwidth of 6%, with respect to the normalization impedance of 30 Ω. The gain difference between this configuration and a regular dipole is 4.4 dB.

B. Infinite Array of Dipoles Loaded with Artificial Dielectrics

We now consider the element in Fig. 3(a), tilted by an angle \( \alpha \) and embedded in an infinite linear array environment, in the presence of a backing reflector. The resulting unit cell is depicted in Fig. 4(a). The distance between the center of the dipole and the infinite ground plane is \( h_{gp} = 0.25\lambda_0 \) and the total height of the dielectric is \( h = 0.7\lambda_0 \).

To describe the angular filtering function, let us imagine to divide the angular region between −90° and 90° in two portions, one desired, where high gain is wished for, and one undesired, where gain suppression is targeted (Fig. 4(b)). If the angle bounding these two regions is referred to as \( \theta_{\text{drop}} \), from the study done in [10], we can derive an optimal inter-element spacing and inclination angle of the elements to achieve a desired \( \theta_{\text{drop}} \). For example, the choice of \( \theta_{\text{drop}} = -20^\circ \) results in an optimal period of \( d_z = 0.75\lambda_0 \) and an optimal inclination angle of \( \alpha = 40^\circ \). Figure 4(b) reports the simulated active element pattern in the E-plane at 12 GHz. The radiation pattern shows a clear drop in gain in the range \( -90^\circ < \theta < -30^\circ \), a roll-off region centered around the target value \( \theta_{\text{drop}} = -20^\circ \),
and almost constant value for angles between 0° and 90°. The active reflection coefficient at 12 GHz and the active input impedance are shown in Fig. 4(c) and (d), respectively, as a function of the scan angle. It can be noted that the impedance is almost constant with scan angle, which is a consequence of the low mutual coupling between the elements. Indeed, the large interelement spacing (0.75λ₀) yields low coupling, thus the active input impedance is close to the passive input impedance and hardly dependent on the scan angle.

C. Feed Design

The last step of the unit cell design consists in replacing the ideal delta-gap feed with a realistic feeding structure. We employ a microstrip feeding line with a Marchand balun to avoid the excitation of common mode currents. A two quarter-wave section transmission line is used to transform the 30 Ω impedance at the antenna terminals up to 50 Ω at the coaxial connector input. For the sake of simple realization, the horizontal ground plane is replaced by a vertical ground plane printed on the same PCB as the dipole and the feeding lines (see Fig. 5(a)). The parameters of the feed structure are illustrated in Fig. 5(b) and Fig. 5(c) and their values can be found in Table II.

Figure 6(a) shows the simulated active element pattern, comparing directivity and realized gain. The simulation includes the feeding lines and the connector and accounts for the material losses, both metal and dielectric. The difference between directivity and gain is about 0.8 dB, which corresponds to a simulated efficiency of 83%. We can observe that gain levels in the undesired region are about −15 dB below the maximum gain, similarly to the previous results for the ideal feed. Figure 6(b) reports the active input impedance at 12 GHz, versus the scan angle. The impedance is well matched to 50 Ω and marginally varying with the scan angle.

### III. ARRAY PROTOTYPE

Based on the unit cell design presented in the previous section, a finite linear array comprising 10 elements was manufactured (see Fig. 7). A subset of the array S-parameters was measured, i.e. the coupling coefficients of the elements with index 1, 5 and 10 with all the others. This allows to compute the active reflection coefficient of one central element (element 5) and the two edge elements (1 and 10) for different scan angles. The results are shown in Fig. 8. Simulations of the finite array are also reported in the same figure for comparison. The elements show a matching bandwidth of about 10%, which is almost constant when scanning.

The measured gain active element patterns in the E-plane are reported in Fig. 9(a), for a few array elements, at a frequency of 12 GHz. Because of truncation effects in the finite
array, the gain patterns differ for each element. For example, element 1 displays a lower level side-lobe pointing at $-90^\circ$, compared to other elements. All measured radiation patterns closely resemble the active element pattern simulated with the infinite array approximation, also shown in Fig. 9(a). Larger discrepancies occur at angles close to $\pm 90^\circ$. This is due to some reflections from the plastic frame holding the antenna, used for the measurements.

The $H$-plane gain pattern of the central element of the array is shown in Fig. 9(b), comparing simulation with measurements. Also the cross-polarized component is shown in the figure. In fact, in the $E$-plane, the cross-pol is not affected by the tilt of the dipoles nor by the feeding structure, since both the planar and vertical components of the current radiate co-polar fields. However, in the $H$-plane, the cross-polar component increases for angles away from broadside, due to the tilting and the radiating currents.

By summing the measured active elements patterns with the proper phases, we can also estimate the total array patterns. The resulting gain patterns are shown in Fig. 10, compared with simulations. When scanning to $20^\circ$, the grating lobe entering in the visible region can be observed at $-90^\circ$, but its level remains $-10$ dB below the maximum, because it is weighted by the filtering function of the element pattern.

![Image of the 10-element linear array prototype.](image)

**Fig. 7.** Photo of the front and back of the 10-element linear array prototype.

![Simulated and measured active reflection coefficient.](image)

**Fig. 8.** Simulated and measured active reflection coefficient for (a) and (b) element 1, (c) and (d) element 5, and (e) and (f) element 10.

![Active element pattern (gain) of three elements of the array.](image)

**Fig. 9.** (a) Active element pattern (gain) of three elements of the array, compared with infinite array simulations. (b) Co-polar and cross-polar $H$-plane gain pattern of the element 5 of the array, compared with simulations.

![Array pattern.](image)

**Fig. 10.** Measured and simulated array gain patterns for different scan angles: Scan to (a) $\theta = 0^\circ$, (b) $\theta = 20^\circ$, (c) $\theta = 60^\circ$, (d) $\theta = 90^\circ$.

We presented the design of a linear array of dipoles with asymmetric radiation properties. The array elements consist of tilted dipoles with parasitic artificial dielectric layers to enhance their gain. The pattern of such an element can be designed to exhibit a high-gain desired region for angles in the range $\theta_{\text{drop}} < \theta < 90^\circ$ and a low-gain undesired region for $-90^\circ < \theta < \theta_{\text{drop}}$. The angle $\theta_{\text{drop}}$ can be controlled by the inter-element distance, while the difference in gain between the desired and undesired regions can be optimized by the tilt angle of the elements.

**IV. Conclusions**

We presented the design of a linear array of dipoles with asymmetric radiation properties. The array elements consist of tilted dipoles with parasitic artificial dielectric layers to enhance their gain. The pattern of such an element can be designed to exhibit a high-gain desired region for angles in the range $\theta_{\text{drop}} < \theta < 90^\circ$ and a low-gain undesired region for $-90^\circ < \theta < \theta_{\text{drop}}$. The angle $\theta_{\text{drop}}$ can be controlled by the inter-element distance, while the difference in gain between the desired and undesired regions can be optimized by the tilt angle of the elements.
A prototype array based on this concept was presented, showing a good comparison between simulated and measured characteristics.

REFERENCES


