

**Improving Subsurface Asset Failure Predictions for Utility Operators
A Unique Case Study on Cable and Pipe Failures Resulting from Excavation Work**

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1 Improving subsurface assets failure predictions for utility operators

2 *A unique case study on cable and pipe failures from excavation works*

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15 ABSTRACT

16 Utility operators have to rely on predictive analyses regarding the availability of their
17 subsurface assets which highly depend on damages by the increasing amount of excavation
18 works. However, straightforward use of standard statistical techniques, such as logistic
19 regression or Bayesian logistic, does not allow accurate predictions of these rare events.
20 Therefore, in this paper, alternative approaches are investigated. These approaches involve
21 weighting the likelihood as well as over- and under-sampling the data. It was found that
22 these data methods can improve the accuracy of predicting the rare failure events
23 substantially. More specifically, an application based on real data of a Dutch water utility
24 operator showed that: under sampling and weighting improved the balanced accuracy
25 varying between 0.61 and 0.66, whereas the proposed methods resulted in failures
26 predictions between 38% and 58% of the validation dataset. Hence, the proposed methods
27 will enable utility operators to arrive at more accurate forecasts enhancing their asset
28 operation decision making.

29 Word count abstract: 155

30 KEYWORDS

31 Rare event data, Logistic regression, cables and pipe networks, synthetic minority oversampling,
32 weighted sampling, network operator, excavation works, predictive maintenance.

33 INTRODUCTION

34 Uncertainty quantification and risk analysis are of paramount importance in all engineering sectors,
35 therefore also in the subsurface utility sector. It is crucial to understand and account for the
36 stochastic nature of underlying processes in the cable and pipe sector, in order to enable enhanced
37 decision making, for example. Furthermore, subsurface utility companies moved their focus towards
38 more pro-active approaches in risk analysis, by using predictive analyses. Engelhardt et al. (2000) and
39 Tscheikner-Gratl (2016), for example, focused on predicting the deterioration state of cables or pipes
40 before rehabilitation is planned. Likewise, Scholten et al. (2013) combined two models, a
41 rehabilitation and pipe failure model in order to predict the long-term performance of rehabilitation
42 strategies for water mains. It should be noted that rehabilitation in the Netherlands is defined by EN
43 752 as follows: “measures for restoring or upgrading the performance of existing drain and sewer
44 systems” (Tscheikner-Gratl et al. 2016).

45 Cables and pipes are critical infrastructure systems (CISs) which are mostly located in the very
46 crowded subsurface. Especially in urban areas, a typical road includes five to ten infrastructure
47 systems, all owned and managed by different entities, mostly making decisions without any mutual
48 coordination or information sharing (Osman, 2016). Over 1.7 million kilometers of cables and pipes
49 are already situated in the subsurface in the Netherlands and the amount is anticipated to increase
50 as the economy and population are expected to growth, as well as through innovation, e.g.,
51 fiberglass (Groot et al. 2016; Rijksoverheid.nl 2017). Each year, major investments are made in
52 subsurface infrastructure in the Netherlands. The forecasts are that about €100 billion will be
53 invested between 2015 and 2030 (Groot et al. 2016). The investments are made for extension and
54 for rehabilitation of the networks. Rehabilitation contains all preventive maintenance activities,
55 concerning all aspects of the network’s assets (Tscheikner-Gratl 2016). Rehabilitation is always
56 planned for the longer term, therefore infrastructure companies moved their focus toward pro-
57 active approaches, using predictive analyses (Engelhardt et al. 2000; Tscheikner-Gratl 2016).

58 The CISs are spatially interdependent as these are highly interconnected due to the close spatial
59 proximity. Despite the critical function of cables and pipes, over 30,000 cable and pipe failures from
60 excavation works are reported in the Netherlands yearly. Multiple studies have been conducted to
61 reduce the risk of excavation damage. These studies have mainly focused on the impact side. This is
62 remarkable because, based on an extensive cooperation between the network operators and other
63 stakeholders, a binding guideline (CROW500) was formed that seeks to prevent cable and pipe
64 damage from excavation works.

65 In contrast to rehabilitation, planning of repairs is not possible because the failures are unplanned
66 and repairs are often executed almost immediately after failures since cables and pipes have a vital
67 function for a country and its citizens (Tscheikner-Gratl 2016). Failure can be caused by excavation
68 activities. In 2015 more than 530,000 excavation requests and 32,858 damages from excavation
69 works were reported in the Netherlands alone which is 5.7% of all cable and pipe failures (Kabel- en
70 Leiding Overleg 2016). Excavation damage and third-party damage of cables and pipes refers to any
71 damage caused by a person which is not directly associated to the network (Wei and Han 2013). The
72 direct repair costs of the excavation damages are over € 26 million per year, and the indirect costs
73 are estimated to be €100 million per year in the Netherlands alone (Van Mill et al. 2013). Despite the
74 extra guideline and the close spatial proximity between cables and pipes in cities, it is still unexplored
75 what the effect of spatial interdependencies is on the probability of failure from excavation works.
76 This paper aims to address this gap.

77 Failures or damages are modelled as dichotomous events, where failure or damage is denoted by
78 one and zero denotes non-failure (non-damage). Logistic regression (LR) is, in this setting, often
79 selected as the modeling approach, i.e., Hosmer et al. (2013), Kleinbaum and Klein (2010). Logistic
80 regression accounts for the influence of the so-called independent variables on the probability of a
81 given event, i.e., the probability of failure, and it has been shown to have good performance in
82 general (Ariaratnam et al. 2001). The failure or damage is regarded as the dependent variable.

83 Predicting the probability of failures is widely applied in the engineering sector. In contrast, in the
84 subsurface utility sector a scarce number of applications appear to have used logistic regression. For
85 example, logistic regression has been applied to relate scouring potential in a channel to certain
86 independent variables in a study conducted by water resource engineers to enable developing a risk-
87 based design (Tung 1985). Furthermore, the likelihood that a particular infrastructure system (sewer)
88 is in a deficient state was predicted by logistic regression in a setting to demonstrate that the use of
89 logistic regression enables decision makers to prioritize what sewer sections should be inspected
90 (Ariaratnam et al. 2001).

91 The data used in this case study have been provided by Evides Water Company, the second largest
92 water distribution company in the Netherlands, located in Rotterdam. The data have revealed that
93 there were 181 water main failures as compared to 107,500 non-failures, as registered by Evides
94 from 2010 until 2017 in the municipality of Rotterdam. The data on cable and pipe failures from
95 excavation works are therefore very imbalanced. The failures are regarded as a minority, whereas
96 the non-failures as a majority of the data. This phenomenon is often referred to as rare event data or
97 imbalanced data. In practice, numerous engineering sectors, as well as research fields deal with data
98 where the events of interest (failures or damages) are scarce and therefore make the data
99 imbalanced. An extensive list of application domains has been provided by Haixiang et al. (2017). It is
100 noteworthy that none of these reviewed studies have been applied in the subsurface utility sector.

101 Modelling rare event data has been proven to pose significant challenges to standard statistical
102 techniques. In particular, predicting rare events proves to be a challenging endeavor, since standard
103 methods, such as logistic or Bayesian logistic regression fail to accurately predict rare events
104 (Haixiang et al. 2017). Predicting rare events is challenging due to several reasons. Firstly, general
105 accepted performance metrics, such as accuracy and precision induce bias toward the majority class.
106 Secondly, models treat rare events as noise occasionally, and consider them exceptional patterns in
107 the data space and reversely, noise can be incorrectly regarded as minority patterns. A detailed
108 discussion about the challenges posed by the rare event data can be found in Haixiang et al. (2017).

109 Numerous approaches have been proposed over the years to adequately model rare event data. The
110 strategies involve resampling techniques, such as over- and under-sampling methods, as well as
111 hybrid methods. Oversampling methods create new minority samples. One of the best known
112 methods is the synthetic minority over-sampling technique (SMOTE), developed by Chawla et al.
113 (2002). Under-sampling methods discard majority (non-event) samples. The simplest method
114 involves random elimination and has been proposed by Tahir et al. (2009). Hybrid methods entail a
115 combination of over- and under-sampling methods. These approaches are usually referred to as data
116 level methods. Other approaches focused on adapting the techniques or algorithms for the
117 imbalanced data. King and Zeng (2001) have proposed logistic regression for rare event data via the
118 maximization of a weighted log-likelihood function. Other methods have been developed for
119 imbalanced data, for example decision trees and neural networks, which are collectively referred to
120 as classification algorithms for imbalanced learning (Haixiang et al. 2017). An exhaustive review of
121 methods is provided in Haixiang et al. (2017).

122 This study will unveil the challenges of applying standard logistic regression and Bayesian logistic
123 regression to rare event data in the subsurface utility sector. To the authors' best knowledge, logistic
124 regression for rare event data has not been applied in the subsurface utility sector so far. This paper
125 aims to fill this gap in modelling and predicting failures. Moreover, the paper aims to provide
126 guidelines of employing logistic regression with rare event data. Both data and algorithm approaches
127 which accommodate the imbalanced data are considered. The methods are evaluated with respect
128 to standard measures, such as area Under the Receiver Operating Characteristic (ROC) Curve (AUC)
129 and balanced accuracy. Furthermore, since the aim of the study is to predict damages resulting from
130 excavation works, the prediction performance is evaluated on a validation dataset.

131 The remainder of this paper is structured as follows. Further details on the study design and data
132 collection process are presented. The methodology introduced the modelling approaches and
133 discusses the assumptions employed by the methods. Afterwards, the performance of the various

134 rare event data approaches is compared. Lastly, the concluding section provides the summary,
135 discusses the results and recommends future research.

136

137 Study design

138 ***Case Study Area***

139 All subsurface utility operators control Critical infrastructure systems (CISs), which indicates that the
140 network's "incapacity or destruction would have a debilitating impact on the defense and economic
141 security of a nations state" (Ouyang 2014, p. 44). One measure to prevent failures are mandatory
142 excavation requests from which risk assessments follow to analyze conflicts between cables and
143 pipes. In 2015 more than 530,000 excavation requests, from which 32,500 failures from excavation
144 works followed were reported in the Netherlands alone (Kabel- en Leiding Overleg 2016), resulting in
145 € 26 million direct and € 100 million indirect damage.

146 This research has been conducted within the Evides Water Company, the second largest water
147 distribution company in the Netherlands, serving safe and clean drinking water to 2.5 million
148 consumers and businesses in three provinces. Evides only had around 500 pipeline failures in 2016,
149 causing an average unplanned downtime of 6.8 minutes per customer (i.e., household) per year. This
150 research focuses on the municipality of Rotterdam within Evides' Rijnmond area. This is, first of all,
151 due to the availability of other cable and pipe data. Moreover, this is because city centers and old
152 residential areas have a high population and building density, which result in a larger probability of
153 failure from excavation works (Vloerbergh and Beuken 2011).

154 Data resources and processing

155 Many aspects were considered in the data collection process. The study mainly focuses on spatial
156 interdependencies, as these are regarded as important for collocated infrastructures when these are
157 considered for rehabilitation or renewal (Islam and Moselhi 2012). Cable and pipe networks are
158 spatial interdependent, since the state of one network can affect the state of another network by a

159 bidirectional relation (Rinaldi et al. 2001; Utne et al. 2011). From an extensive literature review and
160 three expert interviews within Evides, a list of important variables concerning spatial
161 interdependencies has been considered for data preparation and further analysis. The list is included
162 in Table 1. The variables include information about the horizontal position, diameter and wall
163 material. These variables were collected from different data resources, which are described in the
164 following subsections. A commonality between the databases is that these all use Geographical
165 Information System (GIS), whereby location data is available. This enabled linking the various
166 databases to each other.

167 **Excavation data**

168 Each data entry is obtained from an excavation request, which is mandatory by the Kadaster in the
169 Netherlands before any mechanical excavation activity is started (Kadaster, n.d.). An excavation
170 request contains information such as the location, the type of work, the contractor and the client.
171 Three types of requests are distinguished, that is, orientation-, regular- and emergency requests.
172 Orientation requests are only informing and do not allow parties to start excavating until a regular
173 excavation request is done (Kadaster, n.d.), therefore orientating requests are filtered out of the
174 main analysis. Furthermore, the Kadaster allows KLIC-requests (Cable and Pipe Information Center)
175 up to a polygon of 500 x 500 meters. For clarification, it should be noted that a KLIC-request is
176 defined as the obligatory request that is done before mechanical excavation takes place. It is very
177 likely that the size of the polygon and the number of assets located in it are related. As large
178 polygons will contain multiple assets, it becomes hard to predict what cables or pipes are affected by
179 the planned excavation work. Excavation activities are mostly very local. Therefore, a maximum size
180 (25,000 m²) for the KLIC-polygon is set. Figure 1 depicts the KLIC-requests for this study case.

181

182 **Evides pipes**

183 All network operators possess databases including assets, such as cables or pipes, and so does
184 Evides. Firstly, service connections are removed from the dataset as these are assumed to be right-

185 angled on the distribution cables and pipes, creating a problematic situation when mutual distances
186 between various network types are determined later on. Service connections concern all cables and
187 pipes between the distribution networks and clients' property, both private individuals and
188 companies. Furthermore, the cables or pipes are visualized as 'lines' within GIS, whereby line length
189 can vary from up to 300 'meters' to only a few centimeters. A minimum length of 15 meters has been
190 chosen is set to ensure loose connections at for example crossings are removed.

191

192 **Other cables and pipes**

193 Data from other network operators are of importance as this study focused on spatial
194 interdependencies between cables and pipes. The municipality of Rotterdam made available a 3D
195 city model to enable multiple parties to use their unique database, including cables and pipes. The
196 availability of data is not self-evident, as cables and pipes data are mostly confidential, aiming to
197 prevent malicious damage. For the analysis the foreign assets' locations, the type of the network and
198 the associated diameter were collected.

199 **Buildings**

200 Furthermore, the nearest buildings were linked to ensure whether the other networks were crossing
201 the service connections. Service connections are relevant as failures often occur on smaller crossing
202 connections. The Kadaster possesses such a database called Basic Registration and Buildings (BAG),
203 which includes all building locations in the Netherlands.

204

205 **Failures**

206 In this study, the variable of interest, or the dependent variable, of each sample entry is registered as
207 the failure (one) or non-failure (zero) of an Evides pipe due to a third party. Failures are stored in an
208 Evides database. To identify failures from excavation works, network operators need a method to
209 classify various types of failure, as well as the failure date which indicates whether the failure was in
210 a certain period after the excavation request.

211

212 Data processing

213 Each individual data source has been cleaned already prior to the processing of all the databases into
214 a suitable dataset for the study. During the processing, data were filtered if it could not be connected
215 to the other databases.

216

217 **Data Integration**

218 The most important variables used for linking are the geometry data, possessed by all used
219 databases. failures were linked to the nearest networks within 10 meters. Linking the assets and
220 failures succeeded for all failures. Additionally, the asset's construction date should be before the
221 failure date, which has to be before the asset's removal/out of use date.

222 Second, failures are connected to excavation requests. Where failures are "points", the excavation
223 requests are polygons, whereby a point must be inside the polygon for linking. Furthermore, the
224 failure must have occurred after the excavation request date, but no more than 3 months after. An
225 excavation activity must start within 20 days after application, but not earlier than 3 days after.
226 Considering the duration of maintenance or construction work, the duration of the period may be
227 adapted. The 3-month period follows from an assessment of various maximum periods for
228 connection. Considering the duration of maintenance or construction work, the duration of the
229 period could be adapted. In this way, 256 failures out of the total of 500 excavation failures were
230 connected to an excavation polygon.

231 Third, all items that followed from the prior linking of assets and failures were connected to
232 excavation requests. The connections are made based on similarities in location and date. As a result,
233 often, multiple pipes were linked to one excavation request, as it is likely in a densely populated
234 urban area such as Rotterdam, that multiple pipes are in an area when excavation polygons are up to
235 25,000 m².

236 Because multiple pipes (or cables) could be linked to one KLIC-polygon, the criteria for linking must
237 be considered. For example, should the assets be entirely inside the polygon, is a small intersection
238 enough, or is a combination of both preferred. This optimal situation will differ per network
239 operator, but they all have to consider the same aspect; on the one hand, it is preferred to model
240 balanced data. On the other hand, network operators should try not to lose too much data.

241 Once previous links are succeeded, the relation between the different networks is examined.
242 Therefore, a virtual point on the middle point of each Evides pipe within an excavation polygon is
243 created. From that virtual middle point, the mutual distances to the other surrounding networks and
244 buildings is calculated. To prevent misleading calculations of mutual distances, the short "lines" were
245 filtered as all shapes smaller than 15.0 meters were excluded during the asset preparation already.

246 This was done as the smaller shape lengths are mostly located at crossings where the average mutual
247 distances are hard to determine. The mutual distance has been calculated for all networks within 10
248 meters from the middle point. If any further, it is considered as irrelevant when considering
249 excavation damages, since it is not very likely that for example an excavator deviates that much
250 (>10m) from the actual excavation location.

251 In this way, 107,500 entries were collected from which only 181 resulted in a failure. Less than 10%
252 of all data was found to be entirely complete, which is explained by the maximum distance that has
253 been set for linking. In other words, only 10% of all streets in the sample contain all assessed
254 networks. Because LR only includes complete samples, empty entries have been imputed. Even
255 though a common approach is to use the average of the available observations for missing data, this
256 study requires a differentf approach. As discussed earlier, not availables (NAs) are not necessarily
257 missing, it only refers to the absence of a network type within the maximum measure distance.
258 Therefore, imputing a variable's mean would be inappropriate for this dataset. Instead, a value not
259 present in the dataset should be chosen to use for imputation. Therefore, mutual distance NAs were
260 imputed by 12, whereas 10 meters was the maximum connection range and NA diameters were
261 replaced with 1 (meter). As the cable 'side' is a categorical variable (0 and 1), the NAs will be replaced

262 with number 2. Last, other categorical data, such as responsible party and type of work also contain
263 NA entries. This happens when these variables are not traceable. When that happens, the empty
264 samples are labeled 'unknown'.

265 **Note on the case study**

266 The way in which data have been collected is worthwhile discussing, since it has a large influence on
267 the sample set and therefore on the analysis and results. Firstly, there are various manners in which
268 multiple databases can be linked, as all kinds of criteria for the linking can be used, such as linking all
269 intersecting pipes or only the one pipe with the largest intersection and everything in between. This
270 research aims to retain as many unique situations, while considering the percentage of failures
271 within the sample set which resulted in the selected linking method. Secondly, some data were
272 unavailable, for example the vertical position of the cables and pipes, which is very relevant
273 according to literature (e.g., Riley & Wilson, 2006) and experts. Lastly, the validity of the data is
274 questionable, whereby the actual locations are sometimes not corresponding to the data's location.
275 This was also confirmed when the foreign location data were compared to Evides' own data, from
276 which it was found that more than 5% of the compared data deviated more than 0.4m from the
277 comparable data points in the other data source. Less than 75% had the same location data.

278 PROPOSED METHODOLOGY

279 This study aims to employ logistic regression in order to predict failures from excavation works. Since
280 logistic regression is not able to cope with rare event data, several approaches have been
281 considered. To overcome the class-imbalance problem, data level and algorithm level techniques can
282 be used (Chawla et al. 2004). The data level technique prepares the data by rebalancing the data
283 before the modelling is done. Examples of re-sampling techniques are under-, over- and hybrid
284 sampling (Chawla et al. 2002 2004; He and Garcia 2009; Xiong and Zuo 2018). At the algorithm level,
285 the logistic regression has been adapted via a weighted log-likelihood function (King and Zeng 2001).
286 In general, at the algorithm level, the costs of misclassifying the classes, i.e. cost sensitive learning,

287 allocates high cost for the rare event by adding a weight, to improve the learning ability of the
288 classifiers (Chawla et al. 2004; He and Garcia 2009; King and Zeng 2001; Xiong and Zuo 2018).

289 In this study, three distinct approaches were used to model and predict cable and pipe failures from
290 excavation works. These approaches have been validated and their predictive performance has been
291 compared in order to determine the best approach for the data at hand. Moreover, characteristics of
292 the data at hand have been emphasized in order to provide guidelines for the cable and pipe sector,
293 as well as other sectors within the construction or maintenance industry.

294 The implementation and analysis for this study have been done using programming language R.

295

296 Theoretical background

297 **Logistic regression**

298 As already described in the introduction section, logistic regression is generally accepted for binary
299 outcome statistics (Hosmer et al. 2013) and has been already applied for network operators
300 (Ariaratnam et al. 2001; Tung 1985). Logistic regression assumes that the dependent variable follows
301 a Bernoulli distribution having only two possible outcomes, 0 or 1, where 1 usually denotes failure
302 and 0 non-failure with the probability

$$Y_i \sim \text{Bernoulli}(Y_i | \pi_i) \quad (1)$$

$$P(Y_i = 1) = \pi_i \quad (2)$$

$$P(Y_i = 0) = 1 - \pi_i, \quad (3)$$

303 for $i = 1, \dots, n$ observations and where

$$\pi_i = \frac{1}{1 + e^{-X_i \beta}}, \quad (4)$$

304 where X_i denotes the vector of independent variables, for each observation i and β denotes the
305 vector of parameters. Then $P(Y_i | \pi_i) = \pi_i^{Y_i} (1 - \pi_i)^{1 - Y_i}$ is the random variable that represents the
306 probability of failure (King and Zeng 2001; Monroe 2017). The parameters are estimated by
307 maximum likelihood, where the log-likelihood function simplifies

$$\begin{aligned} \ln L(\beta|y) &= \sum_{Y_i=1} \ln(\pi_i) + \sum_{Y_i=0} \ln(1 - \pi_i) \\ &= - \sum_{i=1}^n \ln(1 + e^{(1-2Y_i)X_i\beta}). \end{aligned} \tag{5}$$

308 The influence of a number of independent variables on the dependent variable is depicted via a logit
 309 transformation. Therefore the model does not require a linear relationship between the independent
 310 variables and the dependent variable, as in the linear regression models. It assumes, nonetheless,
 311 linearity of independent variables and the log odds. Moreover, the residuals do not need to be
 312 normally distributed. The observations are however assumed to be independent. Furthermore, the
 313 independent variables should not exhibit multicollinearity. Multicollinearity entails that one
 314 independent variable can predict another independent variable with a certain accuracy (Hosmer et
 315 al. 2013; Xiong and Zuo 2018).

316 As mentioned in the introduction section, logistic regression does not perform well with rare event
 317 data. Results will be nevertheless provided, for comparison reasons in the results section.

318

319 **Weighting and under sampling**

320 The first proposed rare event data approach is by employing weighting, as well as under-sampling.
 321 This approach addresses therefore the rare event issue both at the data level and at the algorithm
 322 level. This method has been developed for rare event data in political science, related social science
 323 and public health research, and have been proposed by King and Zeng (2001). A major advantage of
 324 the weighting approach is that it is relatively simple to employ. At the algorithm level, instead of
 325 maximizing the standard log-likelihood function, as in the regular logistic regression, a weighted log-
 326 likelihood function is maximized as in equation 6. Then

$$\ln L(\beta|y) = - \sum_{i=1}^n \omega_i \ln(1 + e^{(1-2Y_i)X_i\beta}) \tag{6}$$

327 With equation 1, the weights ω_i can be determined by

$$\omega_i = \omega_1 Y_i + \omega_0 (1 - Y_i), \quad (7)$$

328 where $\omega_1 = \frac{\tau}{\bar{y}}$ and $\omega_0 = \frac{(1-\tau)}{(1-\bar{y})}$, and τ is the population fraction and \bar{y} as the sample fraction (King
329 and Zeng 2001). The population fraction is calculated by the number of failures divided by all
330 available data. On the other hand, the sample fraction is the number of included failures divided by
331 the entire sample size.

332 At data level, it is proposed to include two to five times more zeros than ones, “since the marginal
333 contribution to the explanatory variables’ information content for each additional zero starts to drop
334 as the number of zeros passes the number of ones” (King and Zeng 2001, p. 143). This weighting
335 method has been applied in multiple studies. Similar to King and Zeng (2001), Maalouf et al. (2018)
336 found that weighting has a higher discriminative performance than regular logistic regression. The
337 former predicted wars for political purposes, whereas the latter predicted network intrusions for
338 military networks. Within GIS-based (Geographic Information System) applications, Xiong and Zuo
339 (2018) used the proposed under sampling and prior correction (which is very similar to weighting) to
340 map prospective mineral locations (King and Zeng, 2001). The method has been implemented in the
341 R package `ReLogit`. A disadvantage of the available package for statistical software R is that it does
342 not allow for any goodness of fit tests of the models.

343

344 **SMOTE**

345 The second approach for rare event data is the Synthetic Minority Oversampling Technique (SMOTE),
346 which has been proposed by Chawla et al. (2002). SMOTE addresses the rare event issue at data
347 level. Chawla et al. (2002) suggest over-sampling of the minority with “synthetic” examples instead of
348 over-sampling with replacement. The synthetic samples are generated “along the line segments
349 joining any/all of the k minority class nearest neighbors” (Chawla et al. 2002, p. 328). The required
350 number of over-sampling determines how many neighbors from the k nearest neighbors are
351 randomly chosen. The new samples are generated by taking one vector under consideration and its
352 nearest neighbor, whereby a random point along the line segment between the two points is

353 selected. In this way, a random point within the correct region is selected, which enlarges the
354 minority class, whereby it becomes more general in the sample set (Chawla et al. 2002; He and
355 Garcia 2009). A combination of both, over- and under sampling is recommended, as it reverses the
356 initial bias of the learner towards the majority class into the favor of the minority class. The use of
357 both techniques could improve the classification of data (Chawla et al. 2002).

358 SMOTE has proven to be successful in various applications, such as for mammography, diabetes and
359 oil slicks (Chawla et al. 2002) and because of its success, it has been further improved over the years.
360 For example Borderline-SMOTE, whereby the over sampling is conducted between the borderline
361 minority class samples instead of all minority samples (Han et al. 2005) has been developed. Another
362 example is SMOTE and Tomek, which cleans data by applying Tomek links to the over sampled
363 training set, whereby also majority class examples are removed that form Tomek links (Batista et al.
364 2004). However, this study applied the basic version of SMOTE. A disadvantage of the SMOTE
365 method is the incapacity to include categorical independent variables, since the synthetic generated
366 data is different than the variable's categories. Nonetheless, SMOTE has been generalized to handle
367 both continuous and categorical data. The algorithm is called SMOTE-NC, Synthetic Minority Over-
368 sampling Technique-Nominal Continuous (Chawla et al. 2002).

369

370 **Bayesian Logistic Regression**

371 Lastly, Bayesian logistic regression (BLR) was tested. Firstly, the standard Bayesian logistic regression
372 was employed for the entire dataset. Afterwards, Bayesian logistic regression was combined with
373 under sampling. Bayesian logistic regression entails a Bayesian approach to the multivariate logistic
374 regression model. That is, it starts with a prior distribution on the logistic regression parameters. The
375 posterior distribution is then obtained by multiplying the prior with the likelihood.

376 Bayesian logistic regression naturally compensates for rare event data by adjusting the estimates
377 toward the null hypothesis to reduce the bias in rare event data. If no common pattern is detected
378 within subgroups, Bayesian logistic regression will perform little partial averaging across issues

379 (DuMouchel 2012). BLR has been applied for rare event data before to assess clinical safety data,
380 such as the occurrence of a specific adverse event and other safety related issues (DuMouchel 2012).
381 A major disadvantage is that this approach entails a very large computational performance as it has a
382 high model complexity (Grzenda 2015). Nonetheless, the results of this study show the limitation of
383 the Bayesian logistic regression and points out the need to consider methods for rare event data,
384 similarly to the logistic regression.

385

386 Methodology approach for the study case

387 One of the assumptions implied by the logistic regression is that the independent variables should
388 not show multicollinearity. If the independent variables are correlated, this poses the issue of
389 multicollinearity, which can be easily tested with the Variance Inflation Factor (VIF). Along with
390 multicollinearity, the dataset is checked on complete separation, especially as it often occurs in rare
391 events data (Rainey 2016). Complete separation arises when a dependent variable can be perfectly
392 predicted by one variable or a combination of independent variables (Field 2013). Thirdly, in logistic
393 regression it is recommended for the sample size to satisfy the relation

$$\text{Sample size} = 10 \times \frac{k}{p} \quad (8)$$

394 where k is the number of independent variables and p the proportion of 'positive' cases (Peduzzi et
395 al. 1996). The outcome of the sample size is a rule of thumb, which is kept in mind without any
396 further action.

397 The model selection is a step in the analysis which will help to determine what variables are
398 irrelevant and can be removed, in order to also overcome a too small sample size. Model selection
399 will be done based on goodness of fit test and by employing a stepwise backward elimination
400 procedure based on Akaike Information Criterion (AIC). The goodness of fit of the statistical model is
401 considered, while accounting for the simplicity of the model. Model selection is of importance to
402 prevent the model from being overfitted or underfitted. The former occurs when the model tries to

403 follow noise patterns whereas the latter occurs when the model is not capable to follow the data
404 points tightly enough.

405 The performance of the model is evaluated firstly using the Area Under the Receiver Operating
406 Characteristic (ROC) Curve (AUC), which is a traditionally accepted performance metric in logistic
407 regression. AUC assesses the performance between true positive (sensitivity) and false positive
408 (specificity) error rates (Lee 2000; Swets 1988).

409 Given the objective to predict rare events on cable and pipe networks, the model is also evaluated
410 from a predictive point of view rather than from a fitting perspective. Therefore, a validation step is
411 undertaken by considering a validation set along with a training set. The training set is used to fit the
412 model, which is afterwards used to make predictions for the variable of interest in the test set. The
413 model predictions can subsequently be compared with the values of the variable of interest in the
414 test set. A standard approach in the validation analysis is to use a k-fold cross validation, which uses
415 k-1 folds for training and the remaining fold for validation (Han et al. 2005; Rodríguez et al. 2010).
416 When k=5, this translates to using 80% of the data for training and 20% of data for testing. The k-fold
417 cross validation typically makes use of randomly selected training and test sets and the procedure
418 can be repeated numerous times. The prediction error can then be averaged over all the training sets
419 to account for the predictive power of the statistical model. Finally, stratified random sampling
420 needs to be applied, in order to ensure that the rare data are equally split over the training set and
421 the validation set.

422 The output of the validation step is a confusion matrix, which is used to determine the accuracy,
423 kappa, sensitivity and specificity of the model. Cohen's kappa denotes a measure of agreement.
424 Sensitivity accounts for the proportion of the observed failures that were predicted as failures.
425 Specificity denotes the proportion of the observed non-failures that were predicted as non-failures.
426 The sensitivity and specificity determine the balanced accuracy

$$\text{Balanced Accuracy} = \frac{1}{2}(\text{sensitivity} \times \text{specificity}) \quad (9)$$

427 The balanced accuracy measures the average accuracy from both the minority and majority class. A
428 high standard accuracy and a low balanced accuracy indicates that the standard accuracy is high
429 because of the classifier distribution (Akosa 2017). Lastly, the sensitivity of both the data and the
430 model is tested. The former depends on the sample size, therefore the performance of the model for
431 samples of different sizes is investigated. Moreover, the sensitivity of the model explores how the
432 performance of the model is affected by the number of independent variables.

433 RESULTS

434 The models following from the proposed rare event techniques, that is the weighting, SMOTE, as well
435 as Bayesian logistic regression are compared on various aspects with respect to a standard logistic
436 regression model. The standard model was also used to test the basic assumptions, as well as for the
437 model selection.

438 Logistic regression

439 The original dataset that was identified from the literature review and from interviews accounted for
440 27 independent variables (Table 1), which include 107,000 non-failures and 181 failures. Employing
441 the logistic regression model for the statistical analysis of the original dataset would require almost
442 160,000 samples according to Peduzzi et al. (1996). Therefore, backward elimination based on
443 Akaike's Information Criterion (AIC) was applied to select the variables that were considered
444 statistically significant. In the end, ten significant variables were left in the model (Table 2), which
445 agreed with the proposed sample size of Peduzzi et al. (1996). The basic model has been tested
446 comparing a model including all independent variables and a model with the 10 significant variables.
447 From the Log Likelihood Ratio, which indicates how much of the data is explained by the model, a
448 Chi-square score of 0.40 followed, which is above the significance level ($p < 0.10$) whereby the null
449 hypothesis is accepted (Table 2). The mutual dependence of the variables, called multicollinearity
450 was tested by the Generalized Variance Inflation Factor (GVIF), whereby all variables with a GVIF
451 larger than 2.5 were removed.

452 An overall model performance of the logistic regression resulted in an AUC of 0.60, which is regarded
453 as a poor performance and as failing model (Tape, n.d.). Afterwards, the validity of the model was
454 tested by repeated K-fold cross validation for various test train group ratios. It was found that no
455 failure was predicted at all, resulting in a balanced accuracy of 0.50 and specificity of 1.00 for both
456 models, the all-encompassing model and the model with only 10 significant variables included. This
457 finding is similar to the conclusion of Akosa (2017), also for imbalanced data. To improve the
458 balanced accuracy and hence the model's predictive performance, the rare event techniques
459 introduced in the proposed methodology section, are considered.

460

461 Weighting and under sampling

462 By employing the sampling strategy of King and Zeng (2001), a new sample dataset has been
463 constructed. Different ratios of non-event/event have been considered and the results have been
464 compared. For example a ratio non-event/event of 2 means that there are twice as many non-events
465 (zeros) than events (ones or failures). All suggested ratios that are integer numbers were tested (2, 3,
466 4 and 5 times) and the results are presented in Table 3.

467 The results are obtained by performing a validation step, where the size of the training set was
468 approximately 80% of the entire original dataset. It can be concluded that the best ratio, which is
469 based on the balanced accuracy resulted from dataset where the ratio non-event/event was four.
470 This represents the data sensitivity. The selected ratio also results in a sample set of 905 samples
471 from which only 182 are selected for the test set. In the test set 37 failures are included (20%). Table
472 3 also includes the weights used in maximizing the weighted log-likelihood function.

473 Because of the weighting, the confusion matrix is affected in the desired way. Through the weights,
474 29 percent moved from true negative to other positions since the (rare) failures are considered more
475 important by the model, as shown in Figure 2. Therefore, failures will be predicted more frequently
476 with weighting rather than without weighting, which increases the sensitivity of the model.

477 The validation analysis confirmed that the weighted model predicts failures more accurately than the
478 standard logistic regression model. The specificity was 0.94 and the sensitivity was 0.38, meaning
479 that 38% of the failures were accurately predicted. The specificity and sensitivity result in a balanced
480 accuracy of 0.66 and the AUC, following from the ROC was 0.71. In order to investigate whether the
481 model selection for the standard logistic regression has influenced the results, different models, with
482 different sets of independent variables were considered. No noteworthy differences were found
483 when models with different included variables were considered.

484

485 SMOTE

486 With SMOTE, the dataset will be adjusted by over- and under sampling before the method
487 (presented in the subsection methodology approach for the study case) is employed. Hereby, it is
488 important to realize that the ratio non-failure versus failure should not flip over as this would be
489 opposite to the real situation. Therefore, the non-failure versus failure ratio should be at least one
490 and this is also recommended by Chawla et al. (2002). In Table 4, the ratio of the sample set is shown
491 for different combinations (%) of over- and under sampling. For example, when considering a 100
492 percent under sampling and 100 percent over sampling, one obtains a ratio of 2, meaning twice as
493 many non-failures than failures are included in the sample set. The sample sets that were balanced
494 perfectly (1.00) are bold.

495 For the various ratios, the resulting AUC of the model has been computed. The AUC metric depends,
496 of course, on the sampled data set. Different samples hence provide different results. Therefore, the
497 average AUC of five samples for every over/under sample percentage has been chosen. Considering
498 the previous example (100% over- and under sampling), it would follow that the AUC is 0.68. Table 5
499 covers all the resulting AUC values for all possible combinations of under- and over- sampling. The
500 smallest AUC values is 0.58, whereas the largest AUC values is 0.72. This is attained when the
501 minority class is 200% oversampled, whereas the majority class is under-sampled 250%.

502 Without 'flipping' the dataset's balance and considering the AUC, 200% under sampling and 100%
503 over sampling were selected for the modelling, resulting in an equally balanced training set of 604
504 samples. To validate the model's performance based on the rare event sampling, a validation analysis
505 was also performed. Whereas the training set is balanced, the exceptional quality of SMOTE is that
506 the validation set reflects the real situation with more than 21,000 non-failures and only 31 failures
507 included (0.15%).

508 From the validation analysis, an AUC of 0.74 was found. The K-fold cross validation gave a specificity
509 of 0.63 and a sensitivity of 0.58, meaning that 52 failures out of 90 were accurate predicted.
510 Together, the balanced accuracy of the SMOTE model is 0.58.

511

512 Bayesian Logistic Regression

513 Furthermore, Bayesian logistic regression (BLR) has been tested on the entire dataset, whereby all
514 107,500 non-failure observations were included. It was found that there was no noteworthy
515 difference between the results of standard logistic regression and Bayesian logistic regression on the
516 predictive performance. This means that the balanced accuracy was also 0.50, whereas the
517 sensitivity was zero.

518 As a consequence of the low predictive performance, the BLR model was tested on a smaller sample
519 set, similar to the weighted model as this did also increase the predictive performance of the
520 standard logistic regression model. Once this more balanced sample set of the weighted model is
521 used (4:1 non-failure/failure ratio) for the BLR model, the predictive accuracy increases. The K-fold
522 cross validation step resulted in an increased balanced accuracy of 0.60 and a sensitivity of 0.24.

523

524 Models comparison

525 Considering logistic regression as the first statistical approach enables the comparison of the four
526 models with respect to the standard performance measures, such as AUC, specificity, sensitivity and
527 balanced accuracy. Comparing these results supports decision making on what model should be used

528 for predicting failures resulting from excavation works. It is important to realize that all models
529 included the same independent variables, namely the 10 variables found through the model
530 selection. Using the same variables is essential to compare the models.

531 Table 6 contains these results for all the employed methods. Firstly, with respect to the P-values of
532 the individual variables, the SMOTE and weighted model perform very well, with values equal to 0.02
533 and 0.04 respectively. A disadvantage of the R package for weighting is the disability to perform
534 goodness of fit tests on the model, whereby it becomes more complicated to compare it to other
535 models.

536 As this study aimed to accurately predict cable and pipe failures from excavation works, the
537 validating tests are considered most important. The standard logistic regression model, as well as the
538 Bayesian logistic regression model were found to have a balanced accuracy of 0.50, indicating no
539 predictive accuracy at all for failure. Therefore, the SMOTE, the weighted and under sampled BLR
540 models, which perform better than the other two standard models on most aspects are compared.

541 The SMOTE model was able to accurately predict most failures with a sensitivity of 0.58. Conversely,
542 it has the worst specificity, with 0.63, meaning 37% of all non-failures are predicted as failures. The
543 weighted model under sampled to a 4:1 ratio has a good specificity whereas it predicts 94% of the
544 non-failures correctly. However, this model predicts failures less accurate than the SMOTE model as
545 the sensitivity is 0.38. Lastly, the under samples BLR model has the best specificity (0.97) but the
546 worst sensitivity (0.28).

547 When looking at the 'overall' score, the balanced accuracy, the models score quite similar within a
548 range from 0.60 to 0.66. Based on a subsurface utility operator's requirements, the most preferred
549 model can be selected. If preventive measures for a subsurface utility operator are relatively simple
550 and cheap and the cost of failure is large, then the SMOTE model is recommended. On the other
551 hand, when precautionary actions are expensive and complicated it is recommended to use the
552 under sampled BLR model. Therefore none of the models is pointed out as the 'best' model, under
553 any circumstance.

554 CONCLUSION

555 Over the past years, network operators have moved their focus towards pro-active approaches.
556 Despite the initiative, they were not able to accurately predict excavation failures for unique
557 situations because these failures are rare events. For other sectors, techniques to handle rare event
558 data were already developed and applied. Therefore, rare event data techniques are proposed to
559 network operators in order to enhance the predictive power of the logistic regression models, that
560 are used to predict excavation failures. To overcome the class-imbalance problem, rare event
561 approaches at data and algorithm level have been tested.

562 The proposed method has been applied in a test case concerning predictive modelling for cable and
563 pipe failures from excavation works in Evides, a water distribution company in The Netherlands. At
564 data level, it was found that the application of SMOTE did increase the balanced accuracy of the
565 model by 0.11 as compared to a model based on the initial data. At the algorithm level, combined
566 with under-sampling, weighting was tested and found to improve the balanced accuracy to 0.66. The
567 under sampled BLR model has a balanced accuracy of 0.62.

568 It should be mentioned that the applied techniques which handle rare event data (weighting and
569 SMOTE) have been developed in 2001 and 2002. More advanced techniques have been developed
570 over the past years which could improve the predictive power of logistic regression models even
571 further. An exhaustive overview of all (recent) rare event data techniques has been published by
572 Haixiang et al. (2017). However, the application of the methods in this case study demonstrates the
573 potentials of logistic regression modelling with rare event approaches.

574
575 Employing LR revealed interesting insights into the effect of spatial interdependencies on the
576 probability of failure due to excavation works. Two variables were found to influence the probability
577 of failure from excavation works the most. Firstly, emergency KLIC-requests influence the probability
578 of failure the most. However, it is not startling that immediate repairs increase the probability of
579 failure more than planned maintenance, since the latter enables one to prepare for ease. Secondly,

580 the distance to telecom cables, especially on the building side, also increases the probability of
581 failure considerably. With this respect, it is expected that crossing service connections which are
582 closer to the surface cause the increased probability of failure.

583 Another interesting yet expected finding of this study is the statistical insignificance of the age of
584 pipes, which is found in many studies concerning interdependent critical infrastructures (e.g., Atef
585 and Moselhi 2014; Hokstad et al. 2012) to be a statistically significant variable for failure prediction.
586 Nonetheless, for our case study, it is somewhat to be expected that pipes' age is not expected to be
587 of significant influence for failures due to excavation works, since most mechanical equipment is
588 powerful and will cause damage regardless the pipe's age.

589 Finally, this case study also entail a number of limitations. First of all, despite the novelty of methods
590 in the setting of network operators, the employed sampling techniques are fairly standard. More
591 advanced, recent, techniques might improve the predictive performance of the methods; as
592 mentioned beforehand, a good overview of the most recent developments is included in Haixiang et
593 al. (2017).

594 Furthermore, this study reveals that parties are using emergency KLIC-requests above average. An
595 emergency KLIC-request should, in principle, only be used when excavation work is so urgent that it
596 cannot wait. This could indicate unnecessary use of the requests, which probably occurs because one
597 can start excavation immediately instead of waiting for three days. Currently, emergency KLIC-
598 requests can be used in areas of up to 250,000 m² meters. The authors recommend that the issue
599 of whether emergency KLIC-requests that apply to polygons with areas of up to 250,000 m² be
600 revisited to determine whether they serve an useful purpose. Network operators can probably
601 determine, within a much smaller area, where a failure has occurred. Therefore, it would be
602 advisable to consider a standard size for the KLIC-polygon, so network operators should only point
603 the precise location after which automatically an area of, e.g., 20x20 meters is drawn around it.

604 Furthermore, it is recommended to further study the effect of altering the outcome from failure or
605 non-failure into a numerical value and the implementation of possible consequences. In this way the

606 outcome indicates the 'size' of the probability, whereas it is clear obvious that, e.g., 0.75 indicates a
607 larger probability than 0.51. In the current study, both examples are indicated similarly, namely as
608 failure. Moreover, if possible consequences would be also accounted for, a complete overview of the
609 overall risk analysis would emerge.

610 Finally, it is recommended to do further research on the locations of telecom cables as the model
611 proved that it has a large effect on the probability of failure. Especially the side (street side or
612 building side) where the cables or pipes are located seemed to be very important. It is expected that
613 crossing the service connections, which are closer to the surface causes the high probability of
614 failure. Adjusting the distance from telecom cables to houses could prevent a lot of failures.

615 DATA AVAILABILITY

616 All data and models are proprietary or confidential in nature. All statistical code used during this
617 study is available from the corresponding author.

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Table 1: Coefficient estimates, z-values and p-values of the full data model, including all (not completely separated) variables.

Name of variable	Category	β coef.	z value	Pr(> z)
(Intercept)		-20,34	-0,03	0,98
Size of KLIC polygon		0,00	-0,60	0,55
	Gardening	-0,21	-0,33	0,74
	Cables and pipes	0,69	1,54	0,12
Type of KLIC request (everything else than <i>Emergency</i> is a regular request)	Other	-0,37	-0,70	0,48
	Piling/drilling	0,01	0,02	0,99
	Emergency	2,20	4,96	0,00
Age Evides pipe		0,01	1,31	0,19
Diameter of the (own) pipe		-0,01	-6,00	0,00
Shape length Evides pipe (virtual length)		0,00	0,38	0,71
Difference between the two databases		1,58	2,30	0,02
Diameter of the sewer pipes		-1,19	-2,81	0,00
Distance to gas pipes		-0,07	-1,90	0,06
Gas side	Building	0,19	0,37	0,71
	Street	0,38	0,81	0,42
Diameter district heating		0,34	0,75	0,45
Distance to electricity cables		-0,06	-1,33	0,18
Distance to telecom cables		0,05	1,35	0,18
Distance to cable cables		0,02	0,59	0,56

Total length of Evides pipes in KLIC polygon		0,00	0,11	0,91
	Electricity	-0,05	-0,11	0,91
	Gas	0,29	0,97	0,33
	District	0,81	2,29	0,02
KLIC requested by	heating			
	Sewer	0,42	1,63	0,10
	Telecom	-0,38	-0,90	0,37
	Water	0,23	0,68	0,50
	AC	14,21	0,02	0,99
	GGIJ	13,58	0,02	0,99
	HPE	-0,25	0,00	1,00
Material Evides pipe	PE	13,16	0,02	0,99
	PVC	14,77	0,02	0,99
	ST	15,01	0,02	0,99
Distance to buildings		-0,01	-0,59	0,55
Intersection length of Evides pipe in KLIC polygon		0,00	0,20	0,84
Distance to sewers		-0,03	-0,90	0,37
Sewer side	Building	-1,45	-2,12	0,03
	Street	-1,50	-2,20	0,03
Diameter gas pipe		1,63	2,24	0,03
Distance to district heating		0,01	0,28	0,78
	Building	0,53	0,91	0,37
District heating side	Street	1,05	2,39	0,02
Electricity side	Building	-0,65	-1,16	0,25

	Street	-0,96	-1,81	0,07
Telecom side	Building	1,00	1,91	0,06
	Street	1,86	3,68	0,00
Cable side	Building	0,17	0,42	0,68
	Street	-0,05	-0,11	0,91

730 Note 1: The variables below the significance level ($p \leq 0.10$) are in bold.

731 Note 2: AC (asbestos cement), GGIJ (grey cast iron), HPE (Hard polyethylene), PE (polyethylene), PVC
732 (polyvinyl-chloride), ST (steel).

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Table 2. Ten variables selected for inclusion in models with corresponding P-values and GVIF as followed from the basic model.

Name of variable	Category	β coef.	Pr(> z)	GVIF ^{1/(2*Df)}
Type of KLIC-request	Regular	0,68	0,13	1,20
	Emergency	2,22	0,00	1,20
Diameter of the (own) pipe		-0,01	0,00	1,08
Difference between the two databases		1,46	0,03	1,02
Diameter of the sewer pipes		-0,68	0,01	1,67
Distance to gas pipes		-0,02	0,20	2,17
Excavation work on type	District	0,81	0,10	1,04
	heating			
	Sewer system	0,43	0,30	1,04
District heating side	Building	-0,61	0,08	1,67
	Street	-0,70	0,00	1,67
Electricity side	Building	0,33	0,04	1,60
	Street	0,70	0,01	1,60
Telecom side	Building	-0,90	0,00	1,48
	Street	-0,93	0,00	1,48
Material	Polyethylene	-1,18	0,20	1,02
	Steel	0,73	0,30	1,02

734 Note: The values of the categorical variables shown in the table are the most extreme values.

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738 **Table 3:** Weights following from non-failure/failure ratio and corresponding
AUC and balanced accuracy.

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Ratio non-event / event	Weight		AUC	Balanced accuracy
	Event (1)	Non-event (0)		
2	0.005	1.50	0.69	0,65
3	0.006	1.33	0.69	0.64
4	0.008	1.25	0.76	0.66
5	0.010	1.20	0.66	0.60

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Table 4. Non-failure/failure ratio of sample set for different over- and under-sampling percentages.

Note: The sample sets that are perfectly balanced are in bold.

Under sampling [%]	Over sampling [%]				
	0	50	100	200	300
0					
50		5,67	4,00	3,00	2,67
100		3,00	2,00	1,50	1,33
150		2,00	1,33	1,00	1,13
200		1,50	1,00	0,75	0,67
250		1,22	1,27	0,60	0,54
300		1,00	0,67	0,50	0,45

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749 **Table 5.** Area Under Curve (AUC) for various over and
under-sampling percentages.

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Under sampling [%]	Over sampling [%]				
	0	50	100	200	300
0	0,58				0,65
50		0,65	0,63	0,65	0,66
100		0,62	0,68	0,68	0,66
150		0,66	0,68	0,70	0,69
200		0,68	0,70	0,70	0,69
250		0,63	0,68	0,72	0,67
300	0,64	0,64	0,67	0,67	0,69

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Note: The sample sets that are balanced are in bold.

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Table 6. The five assessed alternatives compared. Above the dotted line are standard and goodness of fit tests, underneath is validation.

Model / test	Full data	SMOTE	Weighted	BLR	Under sampled BLR
Average P-values	0.08	0.02	0.04	0.28	0.42
Average z-score	2.64	3.12	NA	1.85	1.16
LLR (Chi squared)	0.40	6E-11	NA	0.37	0.41
Coefficient determination	0.09	0.07	NA	0.01	0.14
AIC	2070	795	434	1950	656
AUC of ROC	0.60	0.74	0.70	0.72	0.74
Specificity	1	0.63	0.94	1	0.97
Sensitivity	0	0.58	0.38	0	0.28
Balanced accuracy	0.50	0.61	0.66	0.50	0.62

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760 **Double-spaced list of figure captions**

- 761 1. **Figure 1.** The KLIC-requests for the Evides study case in the Rotterdam area. Adapted from
762 Evides (2017).
- 763 2. **Figure 2.** Result of weighting the model; (a): because of weighting, 29% of the predictions
764 moved away from true negative. (b): expected value of the weighted model is larger.

765 **Double-spaced list of table captions**

- 766 1. **Table 2:** The estimate, z-value and p-value of the full data model, including all (not
767 completely separated) variables. The variables below the significance level ($p \leq 0.10$) are
768 bold.
- 769 2. **Table 3.** The ten variables that were selected to be included in the models with the
770 corresponding P-values and GVIF as followed from the basic model. The values of the
771 categorical variables shown in the table are the most extreme values.
- 772 3. **Table 3.** The weights following from the non-failure/failure ratio and the corresponding AUC
773 and balanced accuracy.
- 774 4. **Table 4.** The non-failure/failure ratio of the sample set for different over- and under-
775 sampling percentages.
- 776 5. **Table 5.** The Area Under Curve (AUC) for the various over and under-sampling percentages.
- 777 6. **Table 6.** The five assessed alternatives compared. Above the dotted line are standard and
778 goodness of fit tests, underneath is validation.

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