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Impacts of replacing a fixed transit line by a Demand Responsive Transit system

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ABSTRACT

The diffusion of the smartphone and the urban sprawl is pushing both private and public actors to revisit the concept of the demand-responsive transit (DRT). Mokumflex is a DRT pilot program that replaced the regular bus service in low-density areas of Amsterdam, the Netherlands, for 12 months. The close collaboration with the private enterprise that conducted the system but also with the local bus operator allowed the authors to have access to precise databases, giving this article empirical information for both the situation before and after the implementation. These insights help to understand DRT systems and support (future) design of DRT and transit systems. A few indicators were chosen for the comparison: distances, ridership, costs, Greenhouse Gases (GHG), emissions and population's perception. The ridership dropped, however, for being "demand-tailored", the mileage per passenger reduced, improving the costs and GHG emissions. In regards to population's perception, the system enjoyed a good evaluation.

1. Introduction

Urbanization is not a recent trend and neither are the challenges it faces. In 1968, the "first truly comprehensive official look at urban transportation in the light of modern technological capabilities to deal with modern urban problems" was published, pointing out the problems that urban planners at that time had to deal with: equality, accessibility, quality of service,

congestion, efficient use of assets, pollution and inadapted institutional framework were some of them and were considered crucial for a proper urban development (HUD, 1968).

Nowadays the spread of cities is still facing similar problems but they were all aggregated under the concept of sustainability and transportation is seen as one major tool to address them (Laws et al., 2009, Feigon et al., 2018). The 5E framework, proposed by van Oort et al. (2017), for example, estimates the value of transit by its economic, environmental and social impacts, but also regarding the effectiveness (transporting people reliably, safely and reducing congestion) and efficiency (good usage of space).

When it comes to analysis of mobility and urbanization, a classic problem is how to serve low-density and dispersed settled areas where regular transit is usually not feasible and demand-responsive transit (DRT) is a possible solution, helping the population to satisfy their mobility needs (Ellis and McCollom, 2009, MOG, 2014). By DRT, this article considers to be a form of transportation, privately or publicly operated, with fixed or dynamically allocated routes and schedules to offer a service that relies on trip pooling to be performing.

The aim of this study is to evaluate the impacts coming from the transformation of a fixed bus line into a demand-responsive system, giving the guidelines of a methodology that will help urban planners in their decision-making process. It is based in information coming from a demand-responsive pilot program called Mokumflex, that was operated in two rural areas of Amsterdam, the Netherlands, between December 2017 and December 2018, whose dataset included information for each requested displacement.

The next section, a literature review of the development of DRT as well as current experiences are presented. The third section is dedicated to a brief explanation of the local context and the program itself. The penultimate part offers the analysis of the outcomes, evaluating different indicators representative of the previous and the current situation.

2. Development of DRT

DRT is not an innovation of the twentieth-first century: the first somehow formal and documented experiment was realized in 1916, in Atlantic City: a jitney service open to the general public that operated in a fixed route picking-up and discharging passengers according to their requests (O'Leary, 1974, ITCFL, 1982).

The following decades met only a shy dissemination of these type of projects with only two more operations being documented until the 60's, when the planet watched the expansion of these transportation systems: starting in North America and followed by Europe during the 70's (ITCFL, 1982). Figure 1 illustrates the technologic developments and the context that helped DRT's in their spread worldwide:

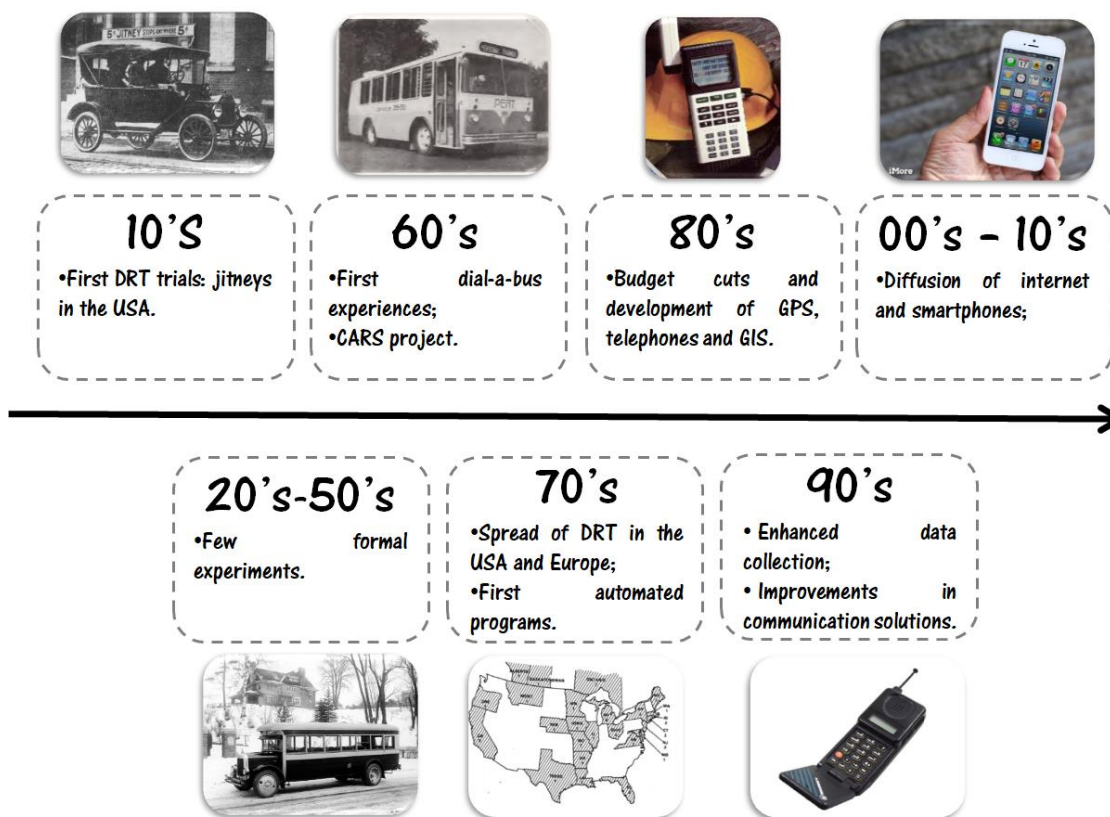


Figure 1: Important technological developments for DRT

The diffusion of DRT started in the 60's: the spread of low-density areas in the US, that generally did not dispose of the same financial resources of the consolidated urban centers, made demand-responsive bus-based system a promising solution (Cole, 1968). The CARS project of the Massachusetts Institute of Technology, aimed the development of a "many-to-many" origins and destinations algorithm to assign efficiently demand, reducing the workforce necessary to provide the offer, making a door-to-door transit system affordable (Wilson et al., 1969). During the 70's, the first automated operations were put into practice: first in Haddonfield, New Jersey, in 1972, followed by Rochester, New York, in 1975 (Strobel, 1982).

The inaugural European experiences date from the end of the 60's and beginning of the 70's, mainly influenced by the North-American initiatives and different travel comportment, telephone, car ownership and disposable income (Webster, 1974). The 80's and 90's saw the improvement of different technologies that enhanced communication and data collection. Adding the limited budget environment, in the USA, the replacement of regular services by shared taxis and dial-a-ride bus options was stimulated (Casey et al., 1991). Concerning the 2000's, the internet allowed important financial and time savings caused by inefficient telephone communication, being considered a promising solution already at that time (Lasdon et al., 2000)

Despite its development, this concept did not meet great acceptance as a substitute for regular transit in situations where the last is not economically viable (Davison et al., 2014). One of the reasons is the nature and objectives of DRT systems: usually, the main motivation for their implementation is to serve weak demands in a more optimized way.

However, to reduce subsidies, the systems have to raise the occupancy but this raise often indicates the necessity of a regular line, therefore limiting their application (Vuchic et al., 1981).

The second decade of the 21st century, however, is embedded into an environment (mainly characterized by the smartphone and significant budget cuts to transit subsidies) that is inviting urban planners to reconsider DRT (Westervelt et al., 2018, Davison et al., 2014). The rediscovery of the concept in current days is being pioneered by the private sector companies and the increasing popularity induced transit agencies to deploy their own pilots (McCoy et al., 2018). The natural development of transportation network companies (TNC), which started operating in 2009, made them start to pool multiple trips in the same vehicle through their software, giving origin to the current DRT systems (Westervelt et al., 2018).

Between 2012 and 2016, some recent DRT companies launched operations just like Via, Kutsuplus, Bridj, Chariot, Padam, Leap, Loup, UberPool, Lyft Lines and Shuttle (Westervelt et al., 2018). Even if ultimately all of these enterprises propose as final and ideal service a shared trip in a car where prices and level of comfort are situated somewhere between regular transit and TNC/ taxis, their business models vary considerably between enterprises and even accordingly to the cities where they are implemented.

Nonetheless, the sustainable business model is still to be found but the reasons are still unclear as enterprises hardly share their data (McCoy et al., 2018). However, some general characteristics of their business model support this statement (Feigon et al., 2018):

- Cost-intensive nature: when compared to TNC companies, DRT experiences are leasing vehicles and paying drivers as employees, which raises its costs;
- Similarity with transit: DRT operators usually provide a transit-like service, without subsidies and for lower demands;
- Low patronage attraction: the system is well understood and accepted by only a few users.

The Netherlands followed this trend: when it comes to stop-to-stop (StS) DRT, recent developments were made firstly, in 2016, in Arnhem-Nijmegen, with Breng flex (Alonso-González et al., 2018) and secondly in 2017, in Helmond and surroundings, with Bravoflex (Hermes, 2019). Figure 2 summarizes some features of contemporary DRT experiences:

Impacts of replacing a fixed transit line by a Demand Responsive Transit system






	Starting year	Nature	Platform	Modality	Scheduling	Routing	Geographic coverage	Nationality
	2012	Public	Website-based	StS	Flexible	Flexible	Area-based	Finnish
	2013	Private	App-based	StS	Flexible	Flexible	Area-based	North-american
	2014	Private	App-based	StS	Flexible	Flexible	Area-based	North-american
	2014	Private	App-based	StS	Fixed	Fixed	Line-based	North-american
	2016	Public	App-based	StS	Flexible	Flexible	Area-based	Dutch

Figure 2: Main features of contemporary DRT operations

In the case of Amsterdam, the Municipality created a pilot program called Mokumflex, which operated between December 2017 and December 2018. Two areas were chosen for the test, based on their limited transit offer and low efficiency, and the project was executed differently in each one:

- In Amsterdam Zuidoost and Weesp, Mokumflex was added to the existing transit offer (provided by the line 49) and ran between December 2017 and December 2018;
- In Amsterdam Noord, Mokumflex completely replaced the public transport (provided by the lines 30 and 31) and ran between February 2018 and December 2018.

As the objective of this article is to evaluate the impacts of the replacement of fixed bus lines for DRT, only the outcomes of Amsterdam Noord will be presented in this article. For further information about the impacts in Amsterdam Zuidoost and Weesp, other indicators and comparisons, please refer to Coutinho (2019). The area served by the lines 30 and 31 is shown in Figure 3.

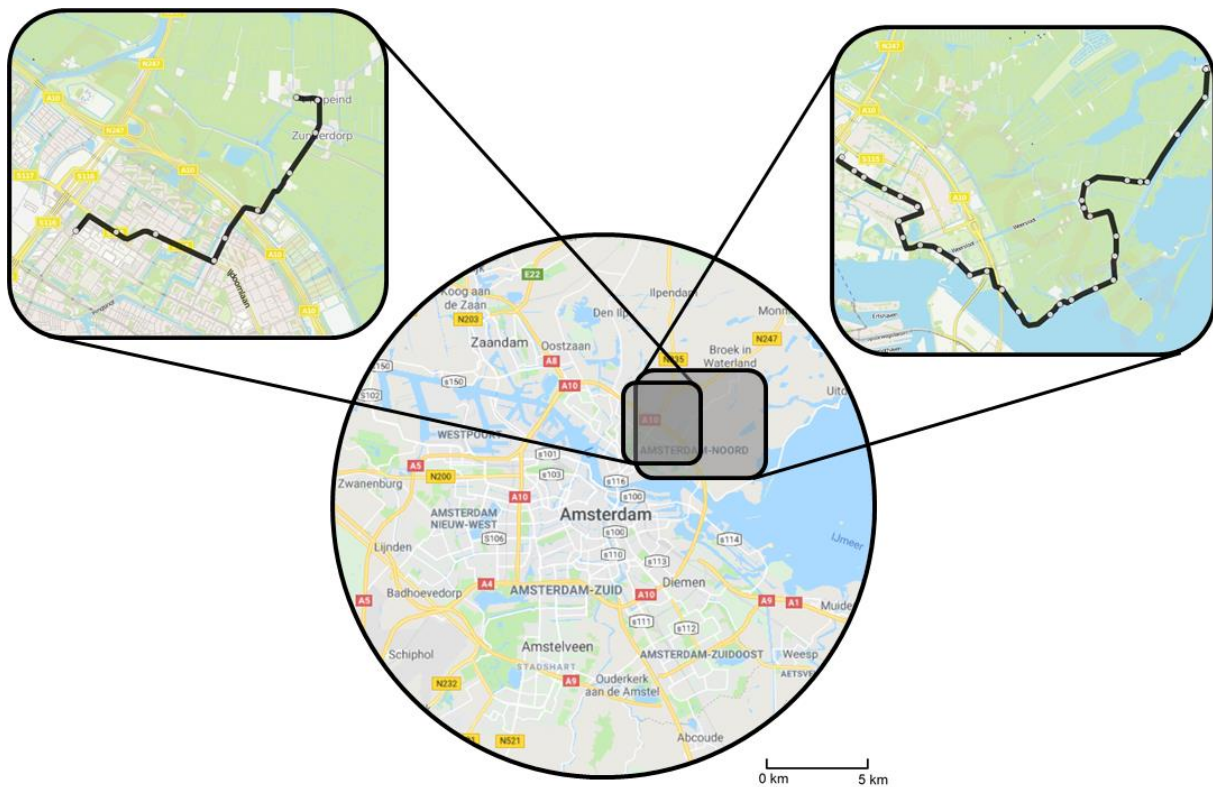


Figure 3: Localization of the previous lines (top left, line 31, top right, line 30)

Source: Google Maps (2018) and Moovit (2018)

While the original fixed bus lines were operated by GVB (the local transit operator) and regulated by Vervoerregio Amsterdam (the transport authority), Mokumflex was operated by RMC, a private enterprise which also operated the paratransit of the region. Since the paratransit is regulated by Gemeente Amsterdam, the Municipality of Amsterdam, the project was regulated by the Municipality, not by GVB. It is important to say that the fleet of Mokumflex was not dedicated, as RMC used these vehicles to also provide paratransit. Figure 4 summarizes some main operational features of both offers.

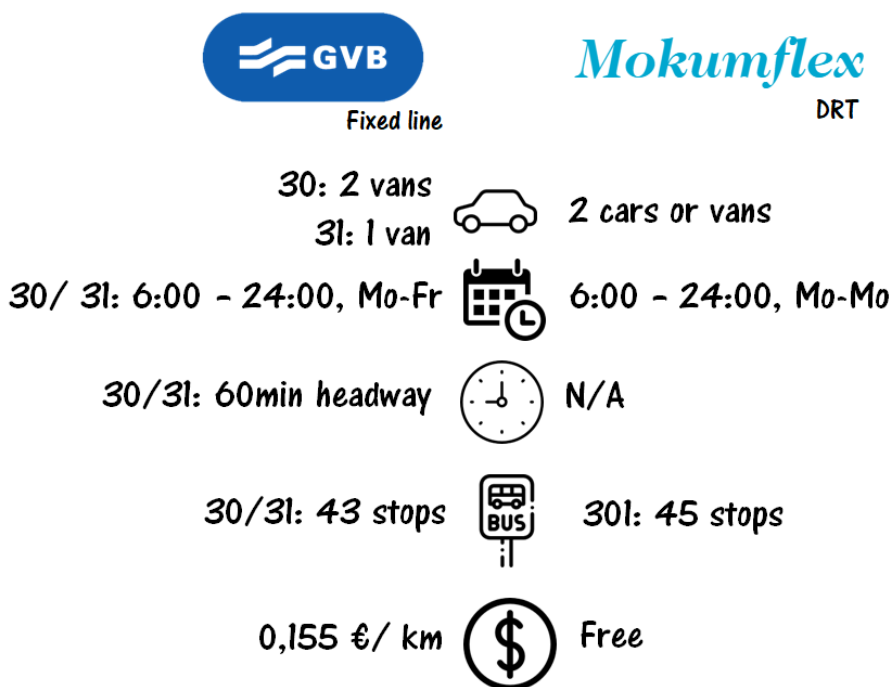


Figure 4: Characteristics and level of service

These results demonstrate that the structure for Mokumflex was leaner: 2 vehicles were capable of serving the areas that previously required 3 vans (disconsidering reserve fleet). However, as will be presented later, the transformation caused a drop in the ridership making this comparison unfair. Also, it is important to note that the pilot extended the operating time-frame as well as the number of stops.

With regard to the large headway of 60 minutes, it was replaced by a demand-based system: the user had to book a trip up to one hour before and the vehicle was supposed to arrive in a 15-minute time-frame around the desired departure time. Finally, while the previous system costed 0,155 €/km (GVB, 2018b), the pilot was free of charge.

3. Data and methodology

As previously mentioned, transit has the capacity to help urban planners to surmount some of the main issues of urban sprawl on the ongoing context. However, not all of the impacts coming from the implementation of mobility projects are considered when designing new transport policies and plans, and, despite the technical capacity that humanity currently dispose of, the main indicators used for evaluations are still traditional metrics, such costs and time saving, for example (Van Oort et al., 2017). This work incorporated, then, a broader set of indicators to compare a regular transit line with a DRT taking into consideration some of the main ideas of sustainability.

3.1 Data sources

Diverse sources were consulted to consolidate the metrics used in the comparisons as this information was not straight available. The first dataset was the one provided by RMC, containing information such as displacing, request and drop-off times, request and drop-off

stops, user's opinion and the ID of the car allocated to this displacement for each request for the whole duration of the pilot program. For the service in Amsterdam Noord, between February 2017 and December 2018, 5.980 requests were recorded, 95% were properly registered (different pick-up and drop-off stations, times and distance travelled superior to 50 meters) and 83% of the displacements were completed (for the rest, the passenger did not show up).

The second most important source was provided by the local transit operator, GVB, containing information about the demands for the regular bus lines via smartcard data, containing tap-in and tap-out information (Van Oort et al. 2015). Finally, other sources of data were the socio-demographic and territorial facts provided by the Dutch Bureau of Statistics, CBS (CBS, 2012), and the national car database, which keep a detailed description about each car registered in the Netherlands and is available in the site of RDW, the Dutch Vehicle Authority (RDW, 2019).

3.2 Methodology to compare fixed transit and DRT

In order to propose a summarized and unbiased comparison between the regular transit and the demand responsive offer, few indicators were prioritized: ridership (passengers/ month), distances (vehicular kilometres/ month), costs (€/ month, €/ passenger and €/ kilometre), GHG emissions (measured in gCO₂Eq/ veh km) and population's perception (obtained from surveys with the users of both systems).

For the DRT, the first two indicators were extracted from the dataset provided by RMC, the operator. While the ridership was straight-forward, the mileage required considerable calculation, as the distance travelled from the place where the vehicle received the request up to the pick-up stop was unknown. To solve this issue, the time when the vehicle started displacing for the pick-up point combined with the average speed of the displacement (represented by 1 in Figure 5) allowed the estimation. By summing this displacing distance with the tripping distance (between stops and represented by 2 in Figure 5) and the one to and from the depot, it was possible to obtain the total mileage.

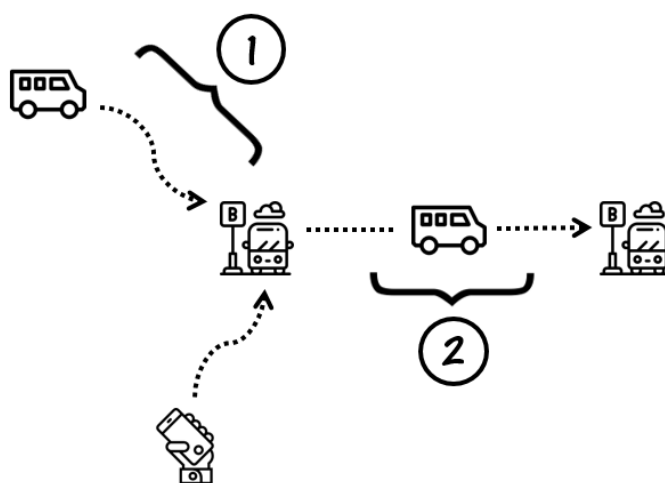


Figure 5: Displacing and tripping distances

Another important feature that deserves explanation is the fleet dimensioning. While for the regular lines the minimum number of vehicles could be estimated based on the headways and schedules, for the DRT it was different. As previously mentioned, since RMC used cars from the paratransit system for the displacements of Mokumflex, the “fleet dimensioning” was based on the “analysis of simultaneity of cars” operating in Mokumflex: for every minute of the pilot, it was checked how many cars were providing trips for Mokumflex in that interval. The results are in Figure 6: Necessary fleet to run Mokumflex

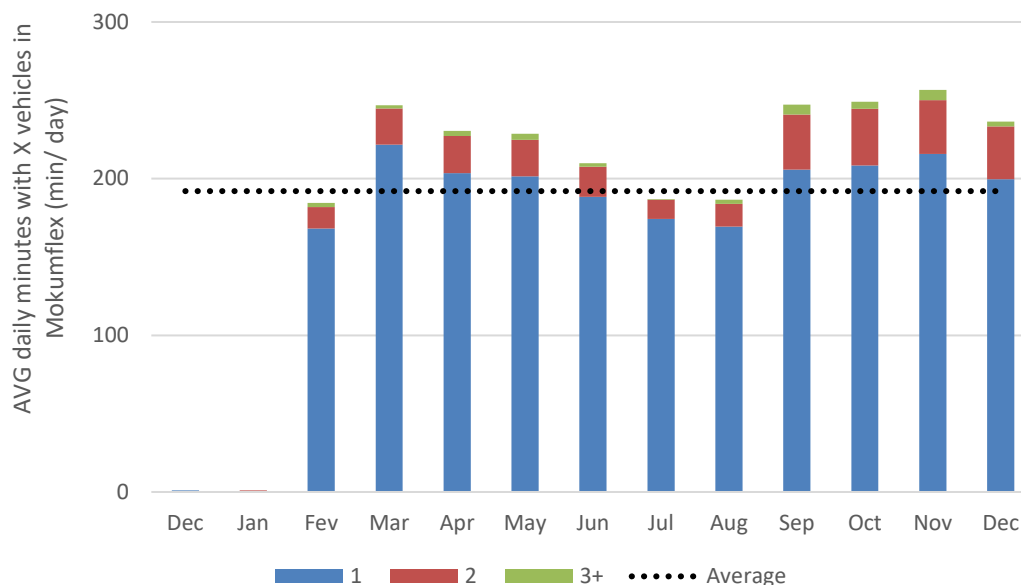


Figure 6: Necessary fleet to run Mokumflex

The average shows that the paratransit cars operated 192 minutes per day for Mokumflex. In 168.5 of those, there was only one car, while in 20.6, there were 2 and the remaining 2.9 minutes saw the presence of 3 or more vehicles. Based on the fact that for more than 98% of the operating minutes there was one or two cars, it was assumed that 2 were enough to provide the displacements (implying additional waiting time for passengers during the mentioned 2.9 minutes)

When it comes to the demand of the previous transit offer, it was provided by the local bus operator, GVB, between February 2018 and December 2018, and the mileage was calculated based on the headways, line length and distances to and from the depot.

Concerning the costs, they were divided in components studied for each vehicle model: depreciation, energy (fuel and, for electric vehicles, battery packs), insurance, interest of the depreciation, maintenance, own risk damage, staff (direct and indirect), storage and taxes.

For Mokumflex, since the vehicles also operated for the paratransit, the costs were divided among the systems: the GPS of the cars demonstrated that they travelled 243,0 km per day whose 136,6 km were for Mokumflex and the remaining 106,4 km for the paratransit. This proportion was applied to divide the distance-based costs. Finally, no opportunity costs nor estimations for the future were considered.

For the GHG emissions, a Wheel-to-Wheel (WTW) analysis comparing three different vehicular models was made: two models that were used during the pilot and the van used for the lines 30 and 31. For the population’s perception, the data came from the evaluation available for users after the completion of each trip, where they could evaluate the displacement as “very satisfied”, “satisfied”, “reasonable”, “dissatisfied” and “very dissatisfied”.

4. Results

4.1 Distance and ridership

When comparing different systems, one of the most usual indicators is ridership. In addition, since this methodology incorporates other indicators that depends on the distances (such as operational cost and GHG emissions), the mileage travelled by the vehicles was also calculated, following the method presented in Section 3. A summary of both is proposed in Table 1:

Table 1: Mileage and ridership

	Fixed 30	Fixed 31	Fixed Total	DRT Mokumflex
Mileage (vehicular km/ day)	1085.9	166.8	1252.8	136.6
Demand (pass/ day)	64.7	13.4	78.1	15.9
Veh km/passenger	16.8	12.5	16.0	8.6

From this table, the low-demand character of the region is latent: the ridership of lines 30 and 31 combined was used for only 78 people. For Mokumflex this number was even lower, about 16 users daily, despite the fact that it was free of charge (this drop is possibly linked to the large time-frame of 15 minutes around the desired departure time, that required customers to organize their schedules for a 30-minutes basis). On the other hand, Mokumflex was more efficient in terms of vehicular mileage per passenger, as the distance reduced more than 46%, passing from 16 km/ passenger to 8,6 km/ passenger.

4.2 Operational costs

The second most traditional indicator is the cost and it relies on mainly four aspects of a transit system: the time-frame of the operation, the number of cars used, the vehicle model and the mileage. The number of vehicles and the mileages were already discussed but in regards to the models while the previous lines operated with Mercedes-Benz Sprinter City (Traminfo, 2019), Mokumflex used a set of different cars to operate Mokumflex. A CNG Combi, however, was used to provide more than 20% of the trips and was one of the models chosen for this evaluation. Moreover, an electric e-Crafter was introduced to check impacts of electrification. The cars studied in this comparison are shown in Figure 7



Figure 7: Car models used for the financial analysis (from the left to the right: Combi, e-Crafter and Sprinter)

Source: Autowereld (2018), Green car reports (2019) and Busphoto (2019)

A detailed explanation of each component of the operational costs can be found in Coutinho(2019) and the summary of the costs is proposed in Table 2 (the numbers are **per vehicle** and the information **per system** can be found in the conclusion).

Table 2: Operational cost analysis

	Fixed, 30 Sprinter	Fixed, 31 Sprinter	DRT Combi	DRT e-Crafter
Lifetime (years)	3.6	8.3	3.2	3.2
Lifetime (km)	504,000	360,000	288,000	288,000
Catalog price (€/ vehicle)	\$41,000	\$41,000	\$54,293	\$54,184
Total (€/ month)	\$15,360	\$13,567	\$4,775	\$4,951
Veh costs (%)	24%	14%	39%	41%
Workforce (%)	76%	86%	61%	59%
Total (€/ km)	\$1.30	\$3.74	\$1.15	\$1.19
Total (€/ pass)	\$21.63	\$50.06	\$6.42	\$6.65

Firstly, the lifetime of sprinters changed accordingly to the intense daily usage: the more a car travel in a daily basis, the larger will be the lifetime mileage (Laver et al., 2007).

The regular line was less cost-performing than the demand-responsive offer in all the “total” indicators, showing that despite the drop in demand, Mokumflex was more efficient. This happened for two reasons: the higher daily mileage (that caused more expenditure with fuels and other distance-dependent indicators, such as maintenance) but also due to the larger number of working hours per week (while the previous system operated 90h/ week with 3 cars thus 270 hours of direct and indirect staff, the demand-responsive ran an average of 192 minutes per day requiring, then, 44,8h per week).

When it comes to the comparison of the energy disbursements between the CNG Combi and the e-Crafter, the e-Crafter was more expensive, as the depreciation of the battery pack accounted for about 62% of the total expenses with energy, and pushed the number upwards. A cost composition is proposed in Figure 8.

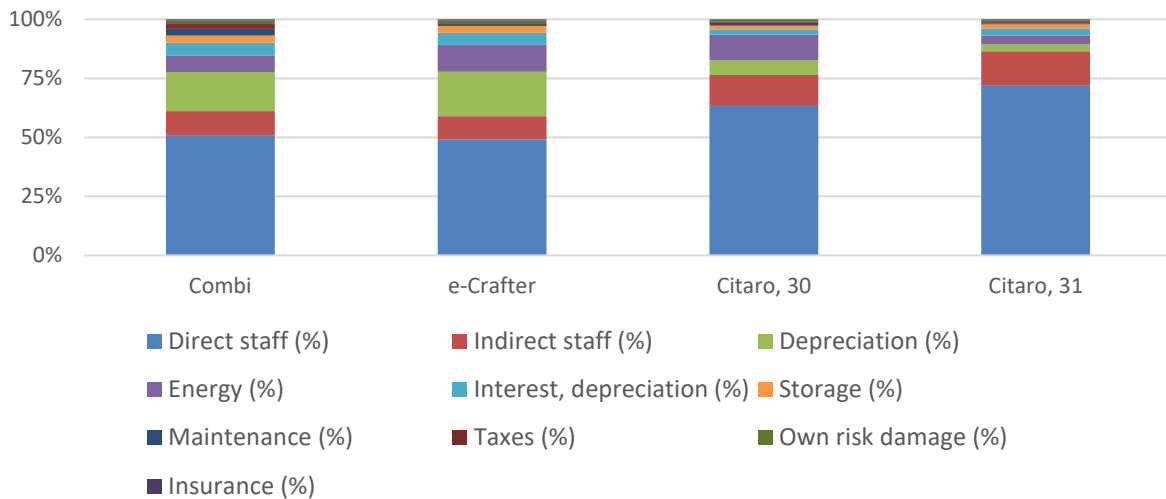


Figure 8: Cost composition

This cost composition demonstrates that workforce is indeed highly impacting for the previous lines but still accounts for the majority of the costs for Mokumflex, demonstrating the potential for automation. The absolute disbursements with depreciation were equivalent before and after but, given that after the transformation, the total monthly expenditure diminished, it grew in percentage.

4.3 GHG emissions

Since this work focused in the incorporation of a broader set of indicators that represented some of the ideals of sustainability, an analysis of GHG emission was mandatory. The choice for a WTW analysis evaluated more precisely the numbers and allowed the estimation of the impact of electric cars. It is important to say that for Tank-to-Wheel (TTW) emissions, the CO₂ emissions were considered numerically equivalent to the total CO₂eq emissions, as other GHG accounts for small fractions of the total (Nam et al., 2004, and Becker et al., 1999). The values were summarized in Table 3.

Table 3: Emissions per car model

	Fixed, 30+31 Sprinter	DRT Combi	DRT e-Crafter
Fuel	Diesel	CNG	Electricity
Conso (Lt, m ³ or kwh/ 100km)	39	7	22
WTT emissions (gCO ₂ eq/ km)	103.5	49.7	115.1
TTW emissions (gCO ₂ eq/ km)	233.0	195.4	0.0
Mileage (veh*km/day)	1252.8	136.6	136.6
Emissions (kgCO ₂ eq/ month)	9,275**	1,004*	472*
Emissions (kgCO ₂ eq/ pass)	5.4	2.1	1.0

* 30-days month

** 22-days month

Despite the similar emission per kilometre, the higher mileage drastically raises the total emissions, making the previous system much less performing than the demand-responsive one. Special attention should be given to the Well-to-Tank (WTT) emissions, that are a considerable part of the total: in the case of the e-Crafter, the carbon-intensity of the electrical Dutch matrix negatively impacted its performance being even more pollutant than the manufacturing of the diesel and demonstrating the necessity of decarbonizing this sector.

4.4 Population’s perception

The last indicator was the population’s perception, which was based in the evaluation available on the main dataset. As the punctuality was a major issue for Mokumflex, the following numbers were split in two sub-groups: “on-time” and “not on-time” trips. Trips were considered to be “on-time” if the pick-up time was contained the 15-minutes frame around the requested pick-up hour. In total, 3.892 completed trips were “on-time” and 329 were evaluated, while the “not on-time” accounted for 1,082 completed trips and 64 evaluations. In regards to the previous system, it was measured differently and GVB’s bus system had a satisfaction of 7,6 in 2016, in a 0-10 scale (GVB, 2018). The results for Mokumflex were summarized in Figure 9.

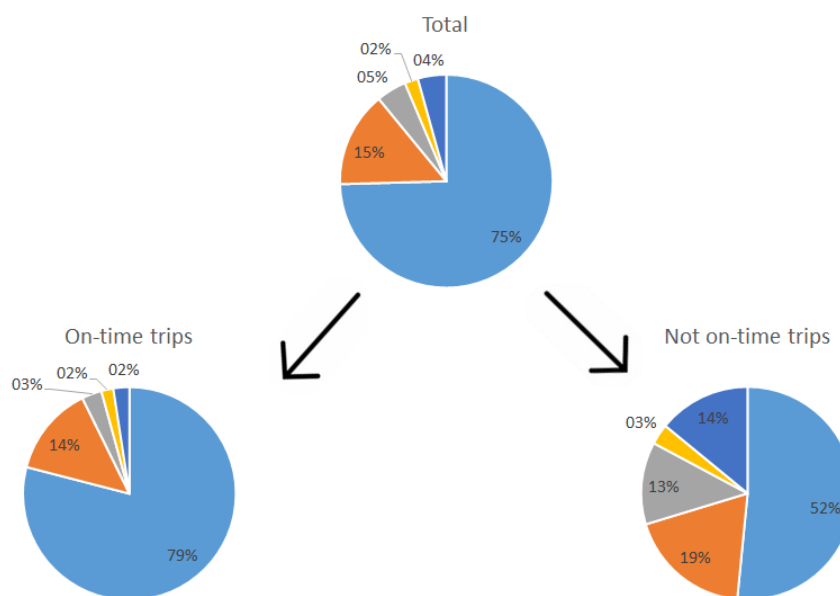


Figure 9: Population’s perception

As one can see, the system enjoyed a good perception, with almost 94% of the “on-time” trips being evaluated as “very satisfying” or “satisfying”. On the other hand, when it came to the judgement of the “Not on-time” trips, the sum of these numbers reduced to about 70%, mainly giving space to “very dissatisfied” and “reasonable” perceptions.

5. Conclusions

This article investigated the differences in terms of distances, ridership, costs, GHG emissions and population’s perception between a DRT system and a regular bus line based in a real case study in Amsterdam. The results showed that the reduced mileage and

operating time-frame contributed for a better performance of the on-demand system when compared to the previous, despite the drop in the ridership.

The nature of DRT is unstable and basic questions, such as the proper context for its implementation, are still lacking answers. However, the possibilities that the smartphone-based context is offering are bringing new and old actors to participate into the rediscovery of the concept.

In this perspective, the case study of a real DRT operation allowed interesting outcomes for the scientific community. It is acknowledged that a broader set of indicators could be internalised but this work wanted to propose the guidelines for a methodology to evaluate transport operations, helping decision-makers to substantiate their choices. For further comparisons, please refer to Coutinho (2019).

This study demonstrated that the transformation impacted considerably the ridership, which dropped to less than 28% of the previous. However, as the mileage reduced to less than 11% of the previous, the resources were rationalized: the comparisons of the indicators per passenger demonstrated considerable improvements, as the number of vehicular kilometres per passenger, operational costs per passenger and GHG emissions per passenger were smaller. Indeed, the regular system had larger mileages and operating time-frame, which caused negative impacts in these indicators.

Still, the WTT analysis showed the importance of evaluating the production of the fuel and electricity, as they may account for a considerable percentage of the total.

The system was also well seen by the users, with levels of satisfaction in almost 90% but punctuality was proven to be an important characteristic of a DRT system, having strong effect on the local community's evaluation. A summary of the indicators is proposed in Table 4.:

Table 4: Summary of the comparison

	Fixed, 30 + 31 Sprinter	DRT Combi	DRT e-Crafter
Mileage (vehicular km/ month)	27.561	4.098	4.098
Ridership (passengers/ month)	1.718	478	478
Vehicles	3	2	2
Operational costs (€/ month)	\$44.288	\$9.551	\$9.903
% vs Fixed line	100%	22%	22%
CO2 emissions (kgCO2Eq/ month)	9.275	1.004	472
Population's perception	7,6/10	89,1% "very satisfied" or "satisfied"	

* 30-days month

** 22-days month

Further considerations should be made about DRT. Since public transport requires large mileages to serve displacements in low-demand contexts (Coutinho, 2019), cars are usually more performing and they should be used for comparison in the moment of the decision-making process for these situations.

Secondly, smartphone-based services require a level of digital literacy that usually population do not dispose of and this can be a real barrier for users, especially for the elders, which are a vulnerable group in terms of mobility and tend to live in rural areas (Ellis and McCollom, 2009). Thirdly, ensuring a good user experience is fundamental: whether by teaching people how to use the application (that should be simple and provide real-time information) as well as by signaling properly stops and cars.

Finally, the lack of indicators to develop analysis about social impacts is clear: the study of mode change, socio-demographics of users and impacts on accessibility could offer interesting outcomes. Also, clarify questions such as the impact of increased ridership in the performance of the system is important. A methodology that incorporates all these indicators of sustainability is not an easy task but could give urban planners great outcomes.

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